STEP_®

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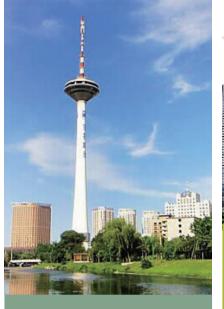


VER 1.0



Shanghai Yixin International Trade Co,Ltd. was found in April 2011, which is a wholly-owned subsidiary of Shanghai STEP Electric Corporation.

Yixin International is a comprehensive international trading company with multilanguage support of business, including English, Russian, Spanish, German, Japanese and so on. As an elevator part integrated supplier, we provide professional lift solutions.We cooperate with partners from more than 50 different countries such as Germany, Malaysia, Vietnam, Indonesia, Russia, Singapore,Australia, India, Turkey and so on.



Our company creates a global advantage by means of good service.

We have established overseas wholly owned subsidiaries, namely STEP Sigriner Elektronik GmbH in Germany and Hong Kong International STEP Holdings Co., Ltd. as well as two subsidiary joint-venture companies STEP-Sigriner DO BRASIL in Brazil and Sigriner Automation (MFG) SDN. BHD.in Malaysia. The Middle East and Southeast



Asia region have also been in the selection process,planning to set up offices in the coming year.Yixin will continue to expand the business scope all over the world.

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STEP Spirit: Strive for global competitiveness, pursue the best practice and always stay ahead of the industry.

STEP Mission: Provide the best controllers, drives and energy-saving products for the sustainable benefits of the society and the employees.

STEP Vision: To be a worldwide leading high-tech enterprise in electrical industry.

High Voltage Inverter

Product application

Product introduction

AS800 high-voltage inverter, as Voltage source HV to HV frequency designed and manufactured by Shanghai Sigriner STEP Electric Co., Ltd. and integrating the cutting-edge international power electronic technology and vector control technology, greatly suppresses the input harmonic current on the grid side through phase-shifting rectifier transformer, achieves voltage superposition through cascade connection of multistage H-bridge power units and obtains almost perfect high pressure sine wave output. It can directly drive the high-voltage motor without any filter and its harmonic indicator meets the requirements for the power harmonics in IEC std 519-1992 (International Electrotechnical Commission) and GB/T 12668.4-2006 (national standard).

Product introduction



AS800-12000-T10-PAD high-voltage inverter/nuclear power station pump test bench application case

Power industry: primary fan, secondary fan, forced draught blower, induced draft fan, exhauster, booster fan, compressor, storage pump, condensate pump, boiler feed pump, circulating water pump and morta, etc.

chemical industries: oil extraction and water injection pump, oil-submerged pump, fuel delivery pump, electric submersible pump, brine pump, circulating water pump, pipeline delivery pump, boiler primary fan, secondary fan, induced draft fan, Roots blower, compressor and coal milling circulating fan, etc.

Municipal water affairs: sewage pump, clean water pump, lift pump, water supply pump, heat circulating pump, pressure pump, induced draft fan and forced draught blower, etc.

Rubber and plastic industry: internal mixer, extruder and air compressor, etc.

Steel and metallurgy industry: main exhaust fan, blast furnace blower, compressing blower, converter dedusting fan, induced draft fan, secondary dedusting fan, gas compressor, forced draught blower, high temperature fan, combustion fan, oxygen compressor, sulfur dioxide fan, water delivery pump, feed pump, lift pump, circulating water pump and slag flushing pump, etc.

Coal and mine: belt conveyor, counter-rotating fan, axial flow fan, dedusting fan, forced draught blower, compressor, slurry pump, clean water pump, charge pump, agitator pump, descaling pump, slush pump, medium pump and kiln drive, etc.

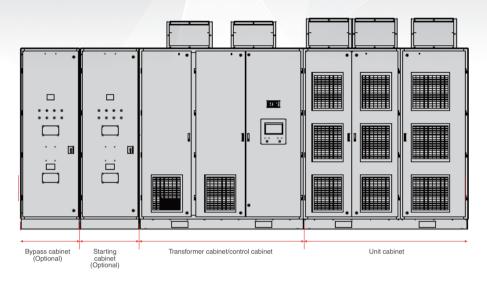
Cement and building materials: high temperature fan, circulating fan, kiln induced draft fan, kiln tail fan, kiln air supply fan, raw material wind mill, coal mill, separator fan, forced draft fan, cement mill exhaust fan and coal mill dedusting fan, etc.

Other industries: air conditioning compressor, various fan pump test stands and wind tunnel tester, etc.

High Voltage Inverter

Product structure

Product structure





Unit cabinet: a unit cabinet consists of several power units in series. A power unit consists of the elements such as three-phase diode-bridge rectifier, IGBT inverter bridge, capacitor bank and the drive, protection, monitoring and communication components; all power units are of intelligent design and have powerful fault self-diagnosis capacity; the power unit is of modular design for production and maintenance.

Control cabinet: the control cabinet is the control part of the whole frequency inverter and the core components of its main control system include A RM, DSP and FPGA. The multi-level PWM control algorithm is used to ensure optimized operation of the motor.

Transformer cabinet: the transformer is dry phase shifting transformer with H class insulation. The maximum system temperature is up to 180° C and $\pm 5\%$ tap at the primary side is adjustable. Function of phase shifting transformer: reducing harmonic interference and improving the power factor.

Bypass cabinet: function of the manual bypass cabinet system: manually switch the motor to the common frequency power grid after frequency inverter fault and decommissioning. Main function of automatic bypass system: directly switch the motor to the common frequency power grid in case of frequency inverter fault to guarantee production continuity. The automatic switching process has no impact on the grid and motor.

Starting cabinet: preventing large exciting current in the high-voltage transmission of the frequency inverter from causing quick-disconnect protection of the superior circuit breaker. Starting cabinet configuration standard: 3kV630kW, 6kV1250kW, 10kV2000kW and above standard configuration, other power sections optional.



Unit cabinet





Transformer cabinet

Control cabinet

07

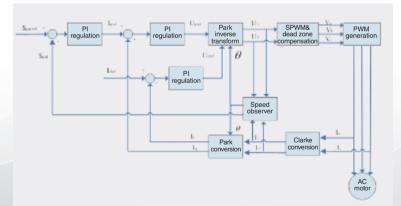
Technical features

• Flexible terminal expansion without the need for PLC

The flexible terminal configuration and expansion and the digital/analog input/output terminal functions may be flexibly expanded as required by the user without the need for PLC programming. Only corresponding parameter functions shall be set.

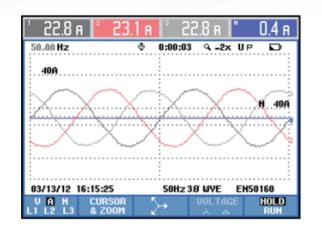
Vector control

- Calculate the motor speed and achieve the AC motor decoupling control according to the motor speed detected by the encoder and combined with the software vector control algorithm. The control performance may be comparable with DC speed regulation system.
- Support constant power operation and support operation above base frequency (flux weakening function).



• High quality drive of motor

- Multi-level PWM control mode and sinusoidal current output.
- Common mode voltage and du/dt, no special requirement for motor and cable, frequency conversion renovation of old equipment without the need for motor replacement



• Low harmonic content

- No additional output filtering device is required and the motor may not be subject to derating use due to harmonics.
- Harmonic content <5%.
- No pulsating torque caused by harmonics. Prolong the service life of the motor and mechanical equipment, reduce maintenance and save the maintenance cost.

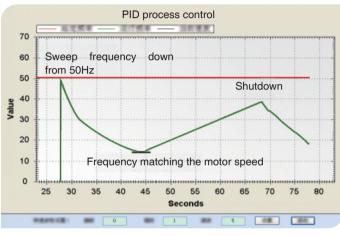
Harmoni	c form			
Amp	L1	© 0:00:58	L3	an a
THD%f H3%f H5%f H7%f	2.5 1.1 1.7 0.8	2.4 1.1 1.6 0.8	2.4 1.2 1.6 0.8	440.1 65.1 67.7 66.8
H9%f H11%f H13%f H15%f	0.1 0.9 0.2 0.1	0.1 0.9 0.2 0.1	0.1 0.9 0.2 0.1	72.8 62.5 64.9 71.4
03/13/12 V A W V&A	16:14:25	50Hz 3 Harmonic Graph	Ø WYE TREND	EN50160 HOLD BUN

High Voltage Inverter

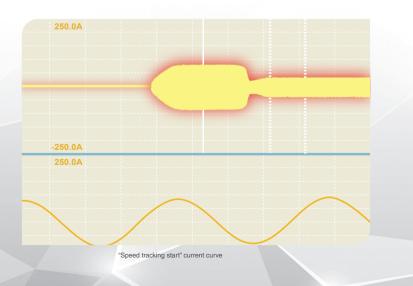
Product functions

Speed tracking start

Speed tracking start is also called "Fly a car start". The frequency inverter first sweeps frequency down from the maximum frequency. When tracking the frequency matching the motor speed, the frequency inverter quickly rises to the voltage-frequency curve by unique phase detection technology and achieves direct start on the basis of current motor speed.

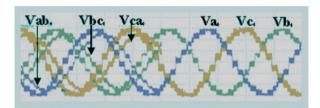


"Speed tracking start" frequency scanning curve



Mechanical unit bypass

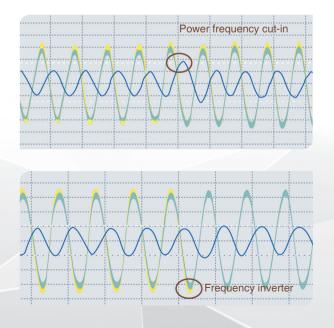
- Mechanical unit bypass: automatically bypass the fault unit in case of the unit fault in the high-voltage frequency inverter operation process to guarantee continuous operation of the equipment;
- The maximum bypass unit number is 2 in each phase;
- Independent design of the unit bypass control system to guarantee reliable equipment operation.





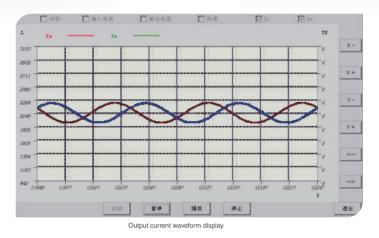
• Undisturbed switching between power frequency and variable frequency

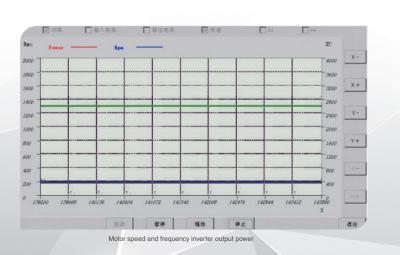
Control the high-voltage frequency inverter to output the same frequency and phase with the network voltage after detecting the voltage amplitude, frequency and phase to achieve undisturbed switching between the frequency inverter power supply and power frequency power supply.



• Curve display

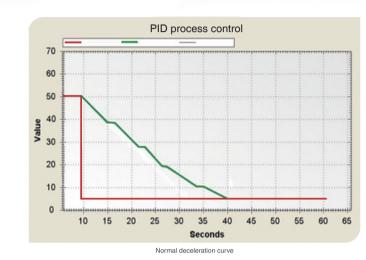
The operation interface of the frequency inverter touch screen can display the real-time output current waveform of the frequency inverter and choose to output the real-time curves of the motor speed and frequency inverter output power to observe equipment operation.

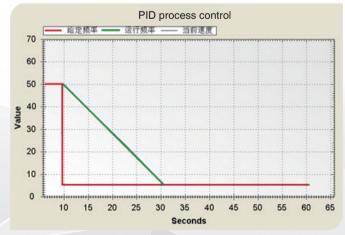




• Bus voltage self-equalization technology

Overvoltage of a unit in the deceleration process by means of the original S curve will result in deceleration process stagnation and extend the deceleration time; the bus voltage self-equalization technology solves deceleration stop of a single unit in the deceleration process, so that the deceleration time of the frequency inverter is shortened by about 66%, avoiding the unit overvoltage fault in the deceleration process.

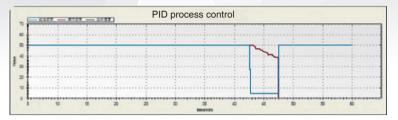




Self-equalization technology deceleration curve

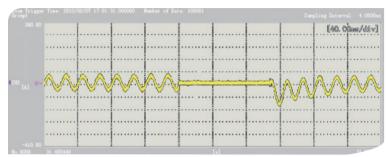
• Endurance after power failure

The high-voltage frequency inverter may constantly output 2s in case of high voltage instantaneous loss of power during operation. In case of high voltage recovery in this period, the frequency inverter may recover normal operation.



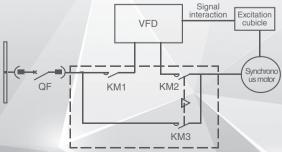
Cycle soft start

- Start multiple motors successively by 1 frequency inverter. It has accurate phase locking and frequency locking functions;
- The maximum starting current is twice the rated current of the motor and the switching time is within 1s.



Synchronous motor control

- · Support permanent magnet synchronous and separately excited synchronous motors;
- The absolute type encoder is chosen for the permanent magnet synchronous motor and can provide the absolute position signal of the motor angle;
- The excitation cubicle of the separately excited synchronous motor is controlled by the frequency inverter. The power frequency start and variable frequency synchronous start modes are supported.

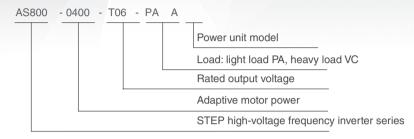


Technical indicators

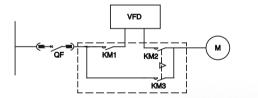
	Input line voltage	3.0/6.0/10.0kV (-10%~+10%)					
Incore	Input rated frequency	50Hz (-2% ~+2%)					
Input	Input power factor	Up to more than 0.95 when the load exceeds 20%					
	Control power supply	380V in three-phase four-wire system (configured according to the frequency inverter capacity)					
	Output line voltage	0~3.0/6.0/10.0 kV					
Output	Output frequency drift	± 0.5%					
	Output frequency resolution	0.01Hz					
	Frequency range	(0.5 $$ \sim 120) Hz (related to motor)					
	Overload capacity	120%, 60s (designed according to user requirements)					
	Control mode	VF control/Vector control					
	Control accuracy	± 0.5% of maximum frequency					
Control parameter	Speed-torque characteristic of load	Square torque load and constant torque load					
	Acceleration and deceleration time	(0 \sim 3200) s (related to load characteristic)					
	Signal input and output	4-channel analog input/output, 16-channel digital input and 8-channel digital output					
	Main protection functions	Overvoltage, undervoltage, overcurrent, short circuit, over-temperature and power unit fau					
	Communication functions	Standard: Modbus; optional: Profibus-DP					
Display	Operation interface	Touch screen					
Transformer	Insulation grade	н					
	Protection grade	IP30					
Construction	Cooling mode	Force air cooling					
	Maintenance	Front and rear maintenance					
	Operating ambient temperature	0°C~+40°C					
	Storage and transport temperature	-20°C~+70°C					
Environmental conditions	Humidity	< 95%, no condensation					
	Vibration	Below 0.5g					
	Usage occasion	Place without corrosive or explosive gas and dust and with the altitude less than 1000m					

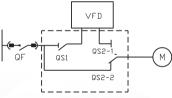
Model selection and application

• High-voltage frequency inverter model definition

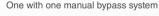


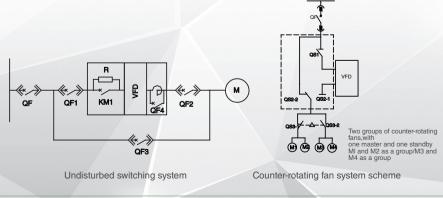
• System application scheme





One with one automatic bypass system





Note: Consult Shanghai Sigriner STEP Electric Company Ltd. for other system schemes

• frequency inverter system selection

· Square torque load

Load type: fan, water pump and oil pump. Select the frequency inverter according to the maximum current of the motor in operation at power frequency; if one frequency inverter drags multiple motors simultaneously, the frequency inverter s selected according to 1.25 times the rated current sum of the motor.

Constant power load

Load type: rolling mill and paper machine. The frequency inverter is selected according to 1.25 times the rated current of the motor.

· Constant torque load

Load type: frictional load such as conveyor belt, agitator and extruder; gravity load such as crane and elevator; air compressor, roots blower, ball mill and reciprocating injection pump. The frequency inverter is selected on the basis that the frequency inverter output current is greater than 1.25 times the maximum operating current of the motor (selected according to 1.25 times the motor current sum for one with two).

Special process load

Load type: cement plant high temperature fan. The frequency inverter is selected according to 1.25 times the rated current of the motor.

Bypass system selection

Automatic bypass system

It is recommended to select the automatic bypass system when the frequency inverter accidental shutdown may seriously affect production or result in major safety accident in some important load occasions, such as boiler fan, induced draft fan, air blower, mill exhauster, pressure pump and water delivery pump.

· Manual bypass system

The manual bypass cabinet is used in absence of high voltage power supply in case of safe maintenance, obvious cut-off point or timely standby motor operation after the frequency inverter accidental shutdown to achieve switching between the motor variable frequency status and power frequency status. The manual bypass system may be selected if the shutdown will not cause impact or accident to production.

Starting cabinet selection

Starting cabinet functions

The large exciting current and large DC bus capacitance loop charging current of the units at all levels at the moment of phase-shifting isolation transformer power-on when the frequency inverter is powered on at high voltage will cause quick-disconnect protection of the superior power cabinet. This situation may be avoided effectively by a starting abinet.

Application occasions

Old equipment project renovation and occasions that the setting value of the motor front-end high-voltage circuit-breaker cannot be changed according to the application requirements.

• 3kV product selection guide

Frequency inverter power (kW)	Transformer capacity (kVA)	Output current (A)	Product model	Overall blast capacity (m ³ /h)	Frequency inverter size(mm)	Total weight (T)
250	300	58	AS800-0250-T03-PAA	9000	2600x1500x2667	4.0
280	350	67	AS800-0280-T03-PAA	9000	2600x1500x2667	4.0
300	375	72	AS800-0300-T03-PAA	9000	2600x1500x2667	4.0
400	500	96	AS800-0400-T03-PAA	9000	2600x1500x2667	4.1
450	560	108	AS800-0450-T03-PAA	9000	2600x1500x2667	4.2
500	630	121	AS800-0500-T03-PAA	9000	2600x1500x2667	4.2
560	700	135	AS800-0560-T03-PAA	9000	2600x1500x2667	4.3
630	800	154	AS800-0630-T03-PAA	12000	3400x1500x2707 (including starting cabinet)	5.3
710	900	173	AS800-0710-T03-PAA	12000	3400x1500x2707 (including starting cabinet)	5.4
800	1000	192	AS800-0800-T03-PAB	12000	4300x1500x2895 (including starting cabinet)	5.6
900	1120	216	AS800-0900-T03-PAB	13000	4300x1500x2895 (including starting cabinet)	5.6
1000	1250	241	AS800-1000-T03-PAB	13000	4300x1500x2895 (including starting cabinet)	5.6
1120	1400	269	AS800-1120-T03-PAB	13000	4300x1500x2895 (including starting cabinet)	5.9
1250	1600	301	AS800-1250-T03-PAB	13500	4300x1500x2895 (including starting cabinet)	6.1
1400	1800	346	AS800-1400-T03-PAC	19500	5534x1500x2895 (including starting cabinet)	8.2
1500	1900	366	AS800-1500-T03-PAC	19500	5534x1500x2895 (including starting cabinet)	8.2
1600	2000	385	AS800-1600-T03-PAC	19500	5534x1500x2895 (including starting cabinet)	8.2
1800	2250	433	AS800-1800-T03-PAC	25500	5534x1500x2895 (including starting cabinet)	8.2
2000	2500	481	AS800-2000-T03-PAC	25500	5534x1500x2895 (including starting cabinet)	9.1
2240	2800	539	AS800-2240-T03-PAC	31500	5534x1500x2895 (including starting cabinet)	9.1
2500	3150	600	AS800-2500-T03-PAC	31500	5534x1500x2895 (including starting cabinet)	9.1

• 6kV product selection guide

Frequency inverter power (kW)	Transformer capacity (kVA)	Output current (A)	Product model	Overall blast capacity (m ³ /h)	Frequency inverter size (mm)	Total weight (T)	Hi
280	350	34	AS800-0280-T06-PAS	9000	3006x1500x2512	4.5	High Voltage Inverter
315	400	38	AS800-0315-T06-PAS	9000	3006x1500x2512	4.5	oltagi ter
355	450	43	AS800-0355-T06-PAS	9000	3006x1500x2512	4.5	Φ
400	500	48	AS800-0400-T06-PAS	9000	3006x1500x2512	4.5	5
450	560	54	AS800-0450-T06-PAA	9000	2900x1500x2667	4.7	Low Voltage Inverter
500	630	61	AS800-0500-T06-PAA	9000	2900x1500x2667	4.7	w Voltaç Inverter
560	700	67	AS800-0560-T06-PAA	9000	2900x1500x2667	4.7	ē
630	800	77	AS800-0630-T06-PAA	12000	2900x1500x2707	4.9	
710	900	87	AS800-0710-T06-PAA	12000	2900x1500x2707	5.3	Ped
800	1000	96	AS800-0800-T06-PAA	12000	2900x1500x2707	5.3	icate /pose
900	1120	108	AS800-0900-T06-PAA	12000	3300x1500x2707	5.7	r ♥ĕ
1000	1250	120	AS800-1000-T06-PAA	13000	3300x1500x2707	5.9	
1120	1400	135	AS800-1120-T06-PAA	13500	3300x1500x2667	6.4	An
1250	1600	154	AS800-1250-T06-PAA	19500	4100x1500x2707 (including starting cabinet)	8.3	Servo Drive And Motor
1400	1800	173	AS800-1400-T06-PAA	19500	4100x1500x2707 (including starting cabinet)	8.3	ptor
1500	1900	183	AS800-1500-T06-PAB	19500	5205x1500x2895 (including starting cabinet)	9.0	
1600	2000	192	AS800-1600-T06-PAB	19500	5205x1500x2895 (including starting cabinet)	9.0	
1800	2250	217	AS800-1800-T06-PAB	22500	5205x1500x2895 (including starting cabinet)	9.0	
2000	2500	241	AS800-2000-T06-PAB	25500	5205x1500x2895 (including starting cabinet)	9.0	
2240	2800	269	AS800-2240-T06-PAB	25500	5205x1500x2895 (including starting cabinet)	9.0	
2500	3150	303	AS800-2500-T06-PAB	31500	5205x1500x2895 (including starting cabinet)	9.0	
2600	3300	318	AS800-2600-T06-PAB	31500	5205x1500x2895 (including starting cabinet)	9.8	
2800	3500	337	AS800-2800-T06-PAC	34500	7434x1600x2895 (including starting cabinet)	11.3	
3150	4000	385	AS800-3150-T06-PAC	34500	7434x1600x2895 (including starting cabinet)	12.9	
3550	4500	433	AS800-3550-T06-PAC	42500	7434x1600x2895 (including starting cabinet)	14.0	
4000	5000	481	AS800-4000-T06-PAC	52500	7434x1600x2895 (including starting cabinet)	14.3	
4500	5800	558	AS800-4500-T06-PAC	52500	7834x1700x2895 (including starting cabinet)	15.5	
5000	6300	600	AS800-5000-T06-PAC	59500	7834x1700x2895 (including starting cabinet)	16.7	
5600	7000	673	AS800-5600-T06-PAD	68160	9270x1980x3438 (including starting cabinet)	20.7	
6300	8000	770	AS800-6300-T06-PAD	68160	9270x1980x3438 (including starting cabinet)	20.7	
7100	9000	870	AS800-7100-T06-PAD	96680	9470x1980x3438 (including starting cabinet)	22.2	
8000	10000	962	AS800-8000-T06-PAD	96680	9470x1980x3438 (including starting cabinet)	22.2	



• 10kV product selection guide

Frequency inverter power (kW)	Transformer capacity (kVA)	Output current (A)	Product model	Overall blast capacity (m³/h)	Frequency inverter size (mm)	Total weight (T)
280	350	20	AS800-0280-T10-PAS	13500	3608x1500x2512	5.8
315	400	23	AS800-0315-T10-PAS	13500	3608x1500x2512	5.9
355	450	26	AS800-0355-T10-PAS	13500	3608x1500x2512	5.9
400	500	29	AS800-0400-T10-PAS	13500	3608x1500x2512	5.9
450	560	32	AS800-0450-T10-PAS	13500	3608x1500x2512	5.9
500	630	36	AS800-0500-T10-PAS	13500	3608x1500x2512	5.9
560	700	40	AS800-0560-T10-PAS	13500	3608x1500x2512	5.9
630	800	46	AS800-0630-T10-PAS	13500	3608x1500x2512	6.5
710	900	52	AS800-0710-T10-PAA	13500	3800x1500x2667	6.5
800	1000	58	AS800-0800-T10-PAA	13500	4200x1500x2667	6.8
900	1120	65	AS800-0900-T10-PAA	13500	4200x1500x2667	6.8
1000	1250	72	AS800-1000-T10-PAA	13500	4200x1500x2667	7.4
1120	1400	81	AS800-1120-T10-PAA	13500	4200x1500x2667	7.4
1250	1600	92	AS800-1250-T10-PAA	19500	4200x1500x2707	7.9
1400	1800	104	AS800-1400-T10-PAA	19500	4200x1500x2707	7.9
1500	1900	110	AS800-1500-T10-PAA	19500	4200x1500x2707	7.9
1600	2000	115	AS800-1600-T10-PAA	22500	4400x1600x2707	9.0
1800	2250	130	AS800-1800-T10-PAA	25500	4400x1600x2707	9.0
2000	2500	144	AS800-2000-T10-PAA	25500	5200x1600x2707 (including starting cabinet)	9.8

Servo Driv

• 10kV product selection guide

Frequency inverter power (kW)	Transformer capacity (kVA)	Output current (A)	Product model	Overall blast capacity (m ³ /h)	Frequency inverter size(mm)	Total weight (T)
2240	2800	162	AS800-2240-T10-PAA	30000	5200x1600x2707 (including starting cabinet)	10.3
2500	3150	182	AS800-2500-T10-PAB	31500	6900x1600x2895 (including starting cabinet)	11.3
2650	3300	191	AS800-2650-T10-PAB	31500	7200x1600x2895 (including starting cabinet)	11.5
2800	3500	202	AS800-2800-T10-PAB	34500	7200x1600x2895 (including starting cabinet)	11.7
3150	4000	231	AS800-3150-T10-PAB	34500	7200x1600x2895 (including starting cabinet)	13.2
3400	4250	245	AS800-3400-T10-PAB	42000	7200x1600x2895 (including starting cabinet)	13.7
3550	4400	254	AS800-3550-T10-PAB	42000	7200x1600x2895 (including starting cabinet)	14.5
4000	5000	289	AS800-4000-T10-PAB	42000	7200x1600x2895 (including starting cabinet)	14.5
4500	5800	335	AS800-4350-T10-PAB	60000	7200x1600x2895 (including starting cabinet)	15.2
5000	6300	364	AS800-5000-T10-PAC	59500	11034x1700x2895 (including starting cabinet)	16.7
5600	7000	404	AS800-5600-T10-PAC	63000	11034x1700x2895 (including starting cabinet)	18.5
6300	8000	462	AS800-6300-T10-PAC	90000	11334x1700x2895 (including starting cabinet)	18.9
7100	9000	520	AS800-7100-T10-PAC	97500	11334x1700x2895 (including starting cabinet)	20.2
8000	10000	577	AS800-8000-T10-PAC	97500	11334x1700x2895 (including starting cabinet)	21.5
9000	11200	650	AS800-9000-T10-PAD	127800	16550x1980x3438 (including starting cabinet)	41
10000	12500	720	AS800-10000-T10-PAD	127800	16550x1980x3438 (including starting cabinet)	41
11200	14000	810	AS800-11200-T10-PAD	127800	16550x1980x3438 (including starting cabinet)	41.8
12500	16000	920	AS800-12500-T10-PAD	127800	16550x1980x3438 (including starting cabinet)	42.4

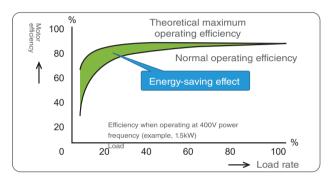
Note: Contact Shanghai Sigriner STEP Electric Co., Ltd. for the power sections not provided in the selection table.

Low Voltage Inverter

Universal AS series inverter performance characteristics & technical specifications

• High-efficient & energy-saving operation

With high-efficient & energy-saving operation and new PWM dead zone compensation technology, motor consumption can be effectively reduced, achieving maximum power saving rate.



• Fast dynamic response

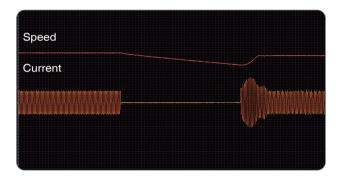
Speed Current

Torque

Advanced motor mode control can also quickly response to load change without PG card.

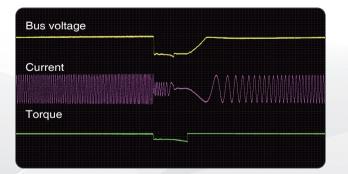
Smooth tracking start

At any time, smooth start can be perfectly achieved without impacting the rotating motor.



• Powerful grid adaptability

Automatic voltage adjustment function: when the grid voltage changes, the output voltage can be automatically kept constant. In the case of sudden loss of electricity, unique non-blackout function can keep inverter running.

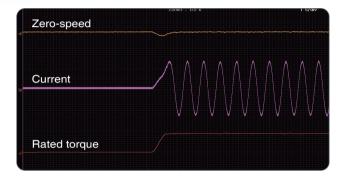


• Stable operation with low frequency and high torque

Dynamic calculation of IGBT internal temperature ensures that the IGBT module operates within the temperature limits, improving reliability of the module.

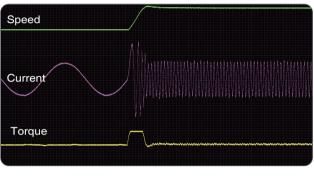
Rapid acceleration

0.1s full load acceleration with fast torque response and low speed overshoot.



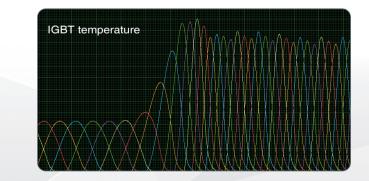
Positive-reverse switch

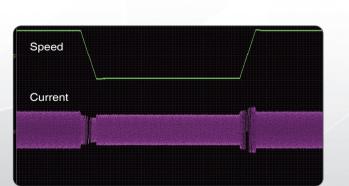
When positive-reverse motor switch to the zero-speed, the phase of current has no change or oscillation, and speed has no ripple.



• IGBT temperature protection curve

Dynamic calculation of IGBT internal temperature ensures that the IGBT module operates within the temperature limits, improving reliability of the module.



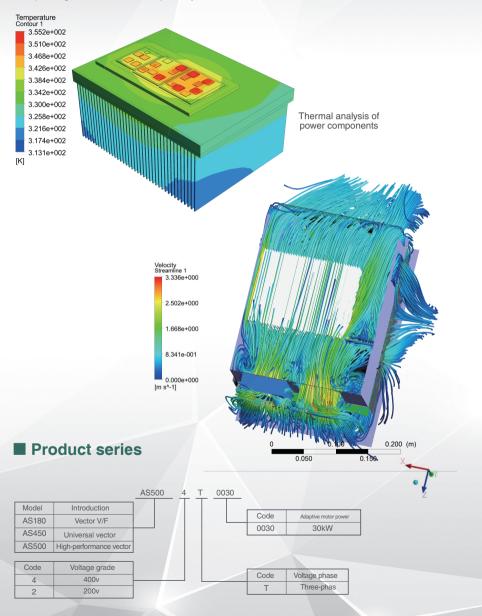


ligh Voltage

Low Voltage Inverter

• Reliable design for heat dissipation

The temperature distribution and wind direction of inverter have strict simulation calculation, improving environmental adaptability.





Comparison on technical performance of universal AS series inverter



Universal AS series inverter		S180 series nverter	Universal AS450 series vector inverter		AS 500 series	high-performar	ice vector inverte	er	and the second second	
Adaptive motor (kw)	2.2-7.5, 11-30,	37-400	1.1-5.5, 7.5-22, 30-35	5		200V grade 1.1- 3.7, 400V grade 1.1- 5.5, 7.5-22, 30-560				
Overload grade	120%,60s 150%,60s		150%,60s							
Output frequency	V/F control: 0.00	-300.00Hz	V/F control: 0.00- 300.0	00Hz vector control 0	.00- 120.00Hz	V/F control: 0.00	– –300.00Hz	vector control 0.0).00120.00Hz	
PG card electron spray			5V、12V, 300mA			5V、12V, 300m	A			
PG card signal			Set-open / push-pull / di	ifferential incremental t	ype, Resolver type	Set-open / push	–pull / differential	incremental type, S	SIN/COS incremental type,	Endat absolute value type,
PG card signal	Asynchronous m	notor	Asynchronous motor			ARseysnoclhver	or ntyope		SPM synchronous moto	or, IPM synchronous motor,
Control mode	V/F control	High-performance control	V/F control	Open-loop vector control	Closed-loop vector control	V/F control	Open-loop vector control	Closed-loop vector control	Open-loop vector control	Closed-loop vector control
Start torque	2.50Hz 120%	0.5Hz 120%	2.50Hz 150%	0.5Hz 150%	0.00Hz 150%	2.50Hz 150%	0.5Hz 150%	0.00Hz 150%	SPM: 5%speed, 150% IPM: 0.00Hz, 200%	0.00Hz, 200%
Speed range	1:50	1:200	1:50	1:200	1:1000	1:50	1:200	1:1000	1:100	1:1500
Steady-speed accuracy	± 2%	± 0.5%	± 2%	± 0.2%	± 0.02%	±2%	±0.2%	±0.02%	±0.2%	±0.02%
Torque accuracy			± 5% (closed-loop con	trol)		±5%(closed-loop control)				
Torque control			Torque / speed control car with a variety of torque se	n be switched through te tpoint.	erminal	Torque / speed of	control can be swi	tched through term	ninal with a variety of torque	setpoint.
Zero servo drives control			Achieve zero-speed po	sition locked		Achieve zero-speed position locked, accurate positioning, position control				
Build-in braking unit	30kW及以下		Below 22kW			Below 22kW				
Build-in direct current reactor	30kW以上		Above 22kW			Above 22kW				
Application fields	Iight industry standard load, 1.2 times overload fan Exhaust, blast Water pump: Constant pressure for water supply, water supply, and drainage HVAC: Heating, air conditioning termina Image Image <tr< td=""><td>Light industry heavy load Puffing machine: food ex Air compressor: screw co Construction material ma centrifugal industrial was Heavy medium pump, ro</td><td>truder ompressor; centrifugal achine: woodworking c hing machine</td><td></td><td>Metal processing Construction eng ball mill material s</td><td>machine comb: tu ineering machine storage/transfer tr</td><td>comb: concrete mix ansport: stereosco</td><td>overload nine, punch machine, forging ter, brick making machine; m pic warehouse, belt conveyo net synchronous application:</td><td>ining machinery: mine hoist, r, in/out brick machine</td></tr<>		Light industry heavy load Puffing machine: food ex Air compressor: screw co Construction material ma centrifugal industrial was Heavy medium pump, ro	truder ompressor; centrifugal achine: woodworking c hing machine		Metal processing Construction eng ball mill material s	machine comb: tu ineering machine storage/transfer tr	comb: concrete mix ansport: stereosco	overload nine, punch machine, forging ter, brick making machine; m pic warehouse, belt conveyo net synchronous application:	ining machinery: mine hoist, r, in/out brick machine

Universal AS series inverter technical specifications

	Input voltage	380-460V (-15%-+10%), three-phase power
Power input	Input Frequency	45-65Hz
-ower input	Accepting voltage change	Voltage unbalance<3%
	Voltage Dips	When three phase AC380-460V power, and input voltage <ac300v, 15ms.<="" after="" implemented="" low-voltage="" protection="" td="" was=""></ac300v,>
	Voltage	OVAC-input voltage
ower output	Overload grade	Stable running 45, overloading 120% 1min
ower output	Efficiency (full load)	≥0.94
	Output frequency accuracy	±0.01% digital command- 10 - +45°C); ±0.1%(analog command 25 10°C)
	Optical coupling isolation input	7 channels, 24V high and low level can be set, input function can be defined
Digital	Open collector output	2 channels, output function can be defined
nput/output	Relay output	2 channels, normally open contacts, contact capacity: inductive, 1.5A/250VAC, output function can be defined, 2 channels, dual normally open/closed contacts, contact capacity, resistive, 4.5A/250VAC or 4.5A/30VOC; inductive: 0.4A/250VAC or 0.4A/20VDC, output function can be defined.
Analog	Analog voltage input	2 channels, accuracy 0.1%; voltage- 10V - +10VDC or current 0-20mA optional signal
	Analog voltage input	2 channels, accuracy 0.1%; voltage- 10V - +10VDC or current: 0-20mA optical signal
	Carrier frequency	1.1-8kHz: carrier frequency can be adjusted automatically according to load characteristics
	Frequency setting resolution	0.01Hz (digital command) 0.06Hz/120Hz (analog command 11 bit + no signal
	Running command channel	Given operation panel, given control terminal, given communication
	Frequency-given channe	Given operation panel, given digital quantity/analog quantity, given communication, given performance function
ontrol naracteristics	Torque improved	Automatic torque improved, manual torque improved
	V/F curve	User-defined V/F curves, linear V/F curves, and three reduced torque characteristic curves
	Automatic voltage adjustment (AVR)	The duty ratio of output PWM signal is adjusted automatically based on the fluctuation of bus voltage, to reduce the influence of grid voltage fluctuation on output voltage fluctuation
	Electricity loss and keep-running process Direct current braking	In the case of instantaneous power-off, achieve uninterrupted operation through bus voltage control
	capability	Brake current: 0.0 - 120.0% motor rated current
	Parameters copy	The standard operation panel can upload and download parameters, and indicate copy progress
haracteristic Inction	Process PID	Used for closed-loop control of process quantities
	Common DC bus	All series can achieve the power supply of common DC bus for multiple inverter
	Rotor blocked, motor overlo	aded, speed limited
nverter rotection		ter overload, GBT I 't overloaded, undervoltage/overvoltage of input power, undervoltage/overvoltage of DC bus, GBT eating, power faulty, analog input signal loss (loss speed reference), communication abnormality, self-tuning faulty
	Operation place	Installed vertically in a well-ventilated electrical control cabinet. Horizontal or other installation is not allowed. Cooling medium is air. Installed in environment without direct sunlight, dust, corrosive gas, flammable gas, oil mist, steam, or water
	Environment temperature	-10 +40
	Used in diminished temperature	$>$ 40 $^\circ$ C, a rise of 1 $^\circ$ C, rated output current is reduced by 2%, the highest temperature is 50
	Altitude	<1000m
nvironment ondition	Used in diminished height	> 1000m, a rise of 100m, rated output current is reduced by 1%(up to 3000m)
	Environment humidity	5-95%, without condensation
	Vibration (transport)	2≤f 9Hz 3.5mm 9≤f 200Hz 10m/s² 200≤f 500Hz 15m/s²
	Vibration (install)	2≤f 9Hz 0.3mm 9≤f 200Hz 1m/s²
	Storage temperature	-40 +70
	Protection grade	IP20
	Туре	Movable
	Length	1m 3m
	Connect	RJ45
	LCD text display	4 row
	LED display	5 bit
	Visible LED indicator	4 pcs
	Key	9 pcs
	Cooling approach	Force-air cooling
	Installation mode	Installed in cabinet with wall-mounted
	Certificate	CE



Universal AS180 series V/F inverter



AS180 series inverter is an universal inverter designed for Chinese market . The product was adopted with German technology, made in China, and combined with the characteristics of domestic application, further strengthening the product reliability, environmental adaptability and design for customer and the industry, with excellent performance of V/F control to perfectly satisfy a variety of light load-driven application requirements.

Intimate application function

- · PID control Dedicated menu to set PID parameters, calculate inside the inverter, without independent external regulator option.
- · DC braking before operation: when the rotating direction of motor during free sliding isuncertain, DC braking automatically stop the motor before starting.
- For the square torque load of fan and water pump, high-performance excitation control can make the motor run at the optimal efficiency point and achieve optimal energy saving effect.

AS180 series inverter technical parameters & dimensions

	Stable i	unning 40 °C, over				
Inverter model AS180	Rated input current (A)	Rated output current (A)	Adaptive motor (kW)	Overloaded 120% (1min) output current (A)	Dimensions	
4T02P2	5.3	5	2.2	6		
4T03P7	7.5	7	3.7	8.4	A1	
4T05P5	11.5	11	5.5	13.2	AI	
4T07P5	16	15	7.5	18		
4T0011	21	20	11	24	A2	
4T0015	30.5	29	15	34.8	- AZ	
4T18P5	38	36	18.5	43.2		
4T0022	46	44	22	52.8	A3	
4T0030	59	56	30	67.2]	
4T0037	75	72	37	86.4	Α4	
4T0045	94	90	45	108	A4	
4T0055	115	110	55	132		
4T0075	154	148	75	177.6	A5	
4T0090	183	176	90	211.2	A6	
4T0110	216	208	110	249.6		
4T0132	261	252	132	302.4	A7	
4T0160	306	296	160	355.2		
4T0185	367	356	185	427.2		
4T0200	402	390	200	468	A8	
4T0220	427	415	220	498		
4T0250	481	468	250	561.6		
4T0280	533	520	280	624		
4T0315	614	600	315	720	A9	
4T0355	664	650	355	780	N.0	
4T0400	755	740	400	888		

Universal AS450 series vector inverter



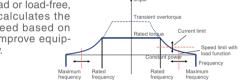
AS450 series inverter is an universal vector inverter. The product was adopted with typical V/F control technology, zero-speed sensor vector control technology, closed-loop vector control and torque control technology, combined with the characteristics of domestic application, further strengthening the product reliability, environmental adaptability and design for customer and the industry, perfectly satisfying a variety of heavy load-driven application requirements.

Intimate application function

Multi-segment speed operation · Based on the combination of signals, run with the frequency of internal memory (up to 16 segment speed instructions). Easy to be continuously controlled and determined the position by limit switch.

Rapid promotion

Under light load or load-free, the inverter calculates the maximum speed based on the load, to improve equipment efficiency.



AS450 series inverter technical parameters & dimensions

			ıg		 Master-sla 		
	Inverter model AS450	Rated input current A	Rated output current (A)	Adaptive motor (kW)	Overloaded 150% (1min) output current (A)		Flexible connection
	4T01P1	3.7	3.5	1.1	5.3		 Master drive is the control, and slave of control.
	4T02P2	6.6	6.2	2.2	9.3		speed control. Sma differences are allo
	4T03P7	9.5	9	3.7	13.5	A1	between slave driv master drive.
	4T05P5	12.7	12	5.5	18		 Slave drive receivir speed signal from the second signal from the second signal from the second seco
	4T07P5	18	17	7.5	25.5		drive is implemente Droop.
	4T0011	26	25	11	36.5	A2	Dioop.
	4T0015	35	33	15	47.5		
	4T18P5	43	41	18.5	59.5	A3	
	4T0022	47	45	22	67.5		Rigid connection
	4T0030	63	60	30	90		 Master drive is the control, and slave of
	4T0037	73	70	37	105	A4	speed control. Spe is not allowed betw
	4T0045	95	91	45	136.5		drive and master d
	4T0055	117	112	55	168	A5	 The torque signal of drive is transmitted
	4T0075	156	150	75	225	A6	drive inverter with and accuracy in the
	4T0090	187	180	90	270	A7	ways:
	4T0110	224	216	110	324	A7	1) profibus-DP cor
	4T0132	269	260	132	390		connection realize master-slave cont
	4T0160	312	302	160	451		(applicable to high master-slave cont
\setminus	4T0185	383	370	185	555	A8	2) analog input an outlet (master mag
	4T0200	401	390	200	585		slave machine-A0
	4T0220	438	426	220	639		ter-slave control (a
	4T0250	492	480	250	720		master-slave control low-speed and low
	4T0280	532	520	280	780	49	accuracy)
-	4T0315	613	600	315	900	1.5	
	4T0355	663	650	355	975		

Master-slave control

Flexible connection Master drive is the speed control, and slave drive is the speed control. Small speed differences are allowed between slave drive and master drive. Slave drive receiving the speed signal from the master drive is implemented with Droop.



Master drive is the speed control, and slave drive is the speed control. Speed difference is not allowed between slave Master drive Slave drive torgu drive and master drive. The torque signal of the master drive is transmitted to the slave drive inverter with high speed and accuracy in the following A0/A

ways: 1) profibus-DP communication connection realizes master-slave control (applicable to high-accuracy master-slave control)



2) analog input and output outlet (master machine-M0 /M1, slave machine-A0/A1) connection realizesmas ter-slave control (applicable to master-slave control with low-speed and low control accuracy)

Low Voltage Inverter

AS 500 series high-performance vector inverter



AS500 series high-performance inverter was adopted with typical V/F control technology, zero-speed sensor vector control technology, closed-loop vector control and torque control technology, as well as synchronous open-loop vector control technology, and synchronous closed-loop vector control technology, combined with the characteristics of domestic application, further strengthening the product reliability, environmental adaptability and design for customer and the industry. Products are widely used in heavy industry and engineering machinery load, suitable for asynchronous motor and synchronous motor.

Suitable for multiple motor

AS 500 series high-performance vector inverter model & technical parameters

sions	ıg	overloadin	unning 40 °C, (Stable ru	
	Overloaded 150% (1min) output current (A)	Adaptive motor (kW)	Rated output current (A)	Rated input current A	Inverter model AS500
	9	1.1	6	7	2T01P1
A1	18	2.2	12	13	2T02P2
	27	3.7	18	19	2T03P7
	5.3	1.1	3.5	3.7	4T01P1
A1	9.3	2.2	6.2	6.6	4T02P2
AI	13.5	3.7	9	9.5	4T03P7
	19.5	5.5	13	13.7	4T05P5
A2	28.5	7.5	19	20	4T07P5
1 12	40.5	11	27	29	4T0011
A3	51	15	34	35	4T0015
A3	61.5	18.5	41	43	4T18P5
	72	22	48	50	4T0022
A4	97.5	30	65	66	4T0030
74	120	37	80	82	4T0037
A5	144	45	96	106	4T0045
AS	192	55	128	138	4T0055
A6	240	75	160	170	4T0075
A7	292.5	90	195	205	4T0090
~ ~ ~	360	110	240	250	4T0110
	405	132	270	280	4T0132
A8	453	160	302	312	4T0160
10	555	185	370	380	4T0185
	585	200	390	400	4T0200
	639	220	426	436	4T0220
	720	250	480	490	4T0250
A9	780	280	520	530	4T0280
	900	315	600	610	4T0315
	975	355	650	660	4T0355



1PM motor (Super energy-saving motor)

Small and light

efficiency

sensor

· Energy-saving, high

High-start torque

without sensor Positioning without Model for A1

Inverter installation

figure for A1

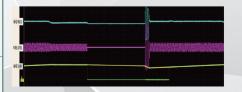
Inverter installation

figure for A2-A3

Inductive motor Synchronou SPM motor

> Super small, super light Energy-saving, high

- efficiency Full-enclosed and fan-free construction (no impact on air condition)
- For rotating synchronous motor, achieve speed tracking within 10ms and start up perfectly



Universal AS series inverter dimension specification

						Installation				Torque	
Specification						aperture Φ(mm)				fastener (Nm)	
A1	100	288.5	300	160	162	5.0	4M4	4M4	4Φ4	1.1	4.5
A2	166.5	357	379	222	182	7.0	4M6	4M6	4Φ6	3.5	8
A3	165.5	392	414	232	182	7.0	4M6	4M6	4Φ6	3.5	10.3
A4	200	512	530	330	288	9.0	4M8	4M8	4Φ8	9	29.5
A5	200	585	610	330	310	9.0	4M8	4M8	4Φ8	9	38
A6	320	718	750	430	350	13.0	4M12	4M12	4012	29	79.5
A7	320	768	800	430	350	13.0	4M12	4M12	4012	29	81
A8	374	844	880	500	350	14.0	4M12	4M12	4012	29	112.5
A9	500	997	1030	630	370	14.0	4M12	4M12	4012	29	170
A10	600	1157	11895	852	4312	140	4M12	4M12	4012	29	280
A11	600	1326	1359	852	4312	140	4M12	4M12	4Φ12	29	310

Servo Drive



Inverter installation

figure for A4-A9

0000

Inverter installation

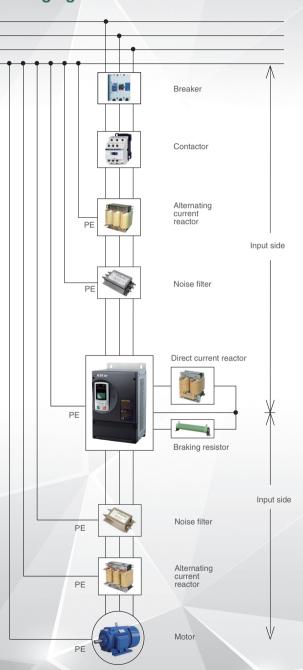
figure for A10-A11

Peripheral wiring figure

R

S

PE



AS700 series engineering inverter

• Brief introduction of AS700 engineering inverter

AS700 engineering inverter, as the latest medium and low voltage and high power inverter of Shanghai Sigriner STEP Electric Company Ltd. and characterized by modularity, high reliability and flexible expansion, may provide the complete set of motor drive system solutions, provide the module form and meet the user, OEM and system integration requirements. AS700 engineering inverter is designed according to rated current and may be applied in the occasions with high overload capacity, such as hoisting industry. The product is also suitable for industrial process control fields, such as pulp and paper making, metal, mining, cement, electric power, chemical, petroleum and natural gas industries.



- Basic characteristics: single unit drive and multi-unit drive; two-quadrant and four-quadrant
- Voltage class: 400V 690V
- Power range: 250KW—1600KW
- Control motor: AC asynchronous motor and permanent magnet synchronous motor
- Control mode: V/F control, open-loop vector control and closed-loop vector control

-

Air conditioning

• Application fields of AS700 engineering inverter



Hoisting equipment



Low Voltage Inverter



Petroleum drilling machine

Marine equipment



Mining machinery



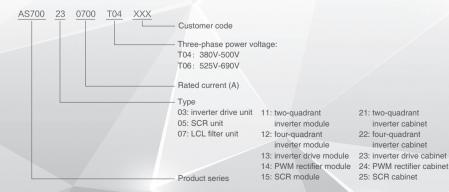
Test stand



Metallurgy

Variable frequency power supply

Model description of AS700 engineering inverter



Performance characteristics

Strong system integration capability

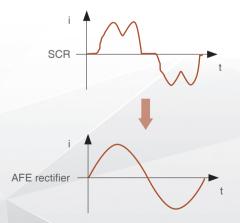
AS700 engineering inverter has SCR and AFE active rectifier modes for choice. SCR mode is mainly applied in the occasions without requirement for the grid harmonics and without the need for energy regeneration, such as centrifugal machine and pump; while AFE active rectifier mode is mainly applied in the occasions requiring low grid harmonics or requiring energy regeneration, such as hoisting machinery.

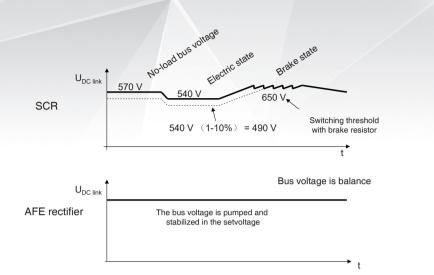


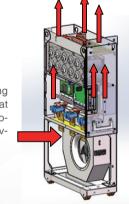
• AFE active rectifier technology

- · IGBT rectifier technology is used to achieve energy regeneration;
- Active rectifier control technology under non-ideal grid improves the system suitability and reduces interference with the grid;
- The grid current waveform tends to be sinusoidal, the current harmonics THDi is below 4% and the power factor is close to 1;
- The DC bus is more stable, reducing the impact of the grid fluctuation on the equipment.









• Dual duct design to improve the product reliability

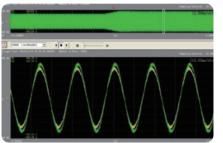
The dual duct design of AS700 engineering inverter power unit can quickly dissipate the heat of IGBT module, capacitor and other components, prolonging the component life and improving the product reliability.

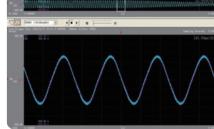
Reasonable structural design for easy maintenance

The drawer type design thought is used for the power unit, with the pulley at the bottom, for easy unit installation and disassembly.

Current sharing technology

The advanced current-sharing control algorithm for real-time adjustment of the current of each unit and for current sharing distribution of the load unit among the units.



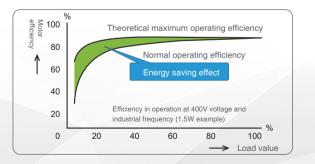


Waveform before current-sharing control (current unbalance)

Waveform after current-sharing control (current balance)

Efficient and energy-saving operation mode

The advanced current-sharing control algorithm for real-time adjustment of the current of each unit and for current sharing distribution of the load unit among the units.



AStar

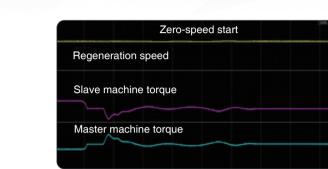
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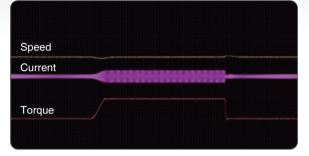
• Fast dynamic response

The advanced motor control mode can quickly respond to the sudden change in the load even if no PG card is applied.

• Torque memory function

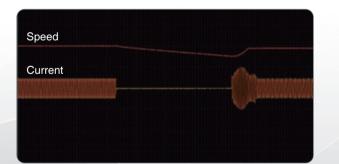
Record the output torque of the motor every time when the brake is closed. When the brake is open next time, output the memory torque of last time to ensure that the heavy object does not slip from the hook. (Support closed-loop control only)





Smooth speed tracking start

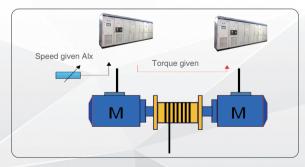
The advanced motor control mode can quickly respond to the sudden change in the load even if no PG card is applied.



Master-slave control technology

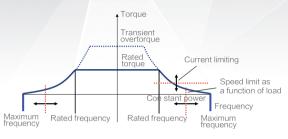
Rigid coupling

- The master drive unit is controlled by speed and the slave drive unit is controlled by torque.
- torque analog of the master drive unit is output to the slave drive unit as the torque given signal.



• Weakened flux and constant power function

The inverter independently calculates the maximum speed (above base frequency) under the rated power to improve the equipment working efficiency.



Motor parameter and operation curve switching function

control only)

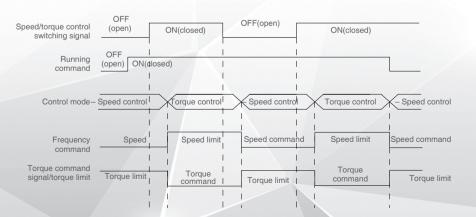
• Speed and torque switching function

Achieve static and dynamic speed/torque switching

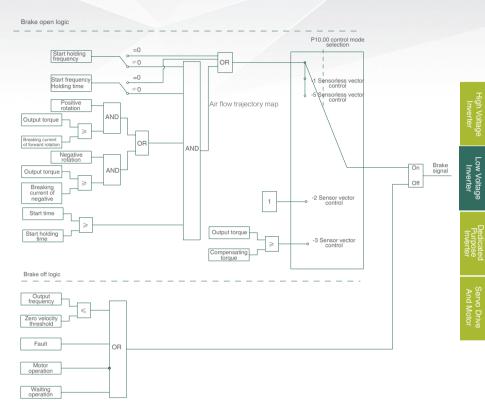
Record the output torque of the motor every time when the

brake is closed. When the brake is open next time, output

the memory torque last time to ensure that the heavy object does not slip from the hook. (Support closed-loop



• Brake logic: perfect, safe and reliable



Optical fiber communication technology

- The optical fiber communication is adopted between the control unit and the power drive unit to ensure the signal transmission speed and to improve the signal transmission accuracy;
- The optical fiber communication technology avoids electromagnetic interference and improves the anti-interference ability of the whole machine.

PCB thickened protective coating

All PCB boards including control board and I/O board are provided with the thickened protective coating to improve the environmental erosion resistance of the inverter and to extend the service life of the inverter.

Fault diagnosis function

In case of inverter fault, the software can quickly locate the fault point and display the fault code and specific fault unit through the manipulator for easy fault diagnosis and equipment maintenance.

Technical specifications

• Technical indicators and specifications of inverter module

	U4N: DC power supply: 450 ~ 800VDC U6N: DC power supply: 740- 1200VDC							
Output voltage	0VAC ~ Un							
Output frequency	V/F control: 0.00 -300.00Hz Vector control: 0.00 ~ 120.00Hz							
Overload capacity	Stable operation at 40°C, heavy load 150%, 1 min; light load 120%, 1 min							
Efficiency (full load) >97%								
Control mode	V/F control	Open-loop vector control	Closed - poppovector					
Starting torque	2.50Hz 150%	0.5Hz 200%	0.5Hz 200%					
Speed adjustable range	1:50	1:200						
Steady speed precision	± 2%	± 2%	± 0.02%					
Torque precision	\pm 5% (Closed-loop control)							
Carrier frequency	2~5kHz							
Frequency setting Resolution	0.01Hz (digital command) \pm 0.06Hz/120Hz (analog command 11bit+unsigned)							
Running command channel	Operation panel , control terminal and communication							
Frequency channel	Operation panel , digital quantity/analog quantity, communication given and function							
Torque compensation	Automatic torque compensation and manual torque compensation							
V/F curve	User-defined V/F curve, linear V/F curve and 3 reduced torque characteristic curves							
Automatic voltage regulation	Automatically adjust the duty cycle of PWM signal according to the bus voltage fluctuation, so as to reduce the impact of the network voltage fluctuation on the output voltage fluctuation							
DC braking capacity	Braking current: 0.0~120.0 %	rated current						
Parameter copy								
Process PID	Used for closed-loop control or	f process quantities						
Torque control function	Torque/speed control switching	g through terminals, many torque mod	les					
Zero servo and position control function	Achieve zero speed position lock, accurate positioning and position control							
	Output frequency Overload capacity Efficiency (full load) Control mode Starting torque Speed adjustable range Steady speed precision Torque precision Carrier frequency Frequency setting Resolution Running command channel Frequency channel Torque compensation V/F curve Automatic voltage regulation DC braking capacity Parameter copy Process PID Torque control function Zero servo and position	Output frequency V/F control: 0.00 ~300.00Hz Output frequency V/F control: 0.00 ~ 120.00H Overload capacity Stable operation at 40 Efficiency (full load) >97% Control mode V/F control Stating torque 2.50Hz Stating torque 2.50Hz Stating torque 2.50Hz Steady speed precision ± 2% Torque precision ± 5% (Closed-loop control) Carrier frequency 2-5kHz Frequency setting 0.01Hz (digital command) Running command Operation panel , control term channel Operation panel , digital quan Torque compensation Automatic torque compensatio V/F curve User-defined V/F curve, linear Automatic voltage So as to reduce the impact of th DC braking capacity Braking current: 0.0-120.0 % I Parameter copy The standard operation panel and dom/bada and indicate the Process PID Used for closed-loop control o Torque control function Torque/speed control switching	Output frequency V/F control: 0.00 -300.00Hz Vector control: 0.00~120.00Hz Overload capacity Stable operation at 40°C, heavy load 150%, 1 min; light load Efficiency (full load) >97% Control mode V/F control Open-loop vector control Stating torque 2.50Hz 150% 0.5Hz 200% Speed adjustable range 1:50 1:200 Stady speed precision ± 2% ± 2% 1 Torque precision ± 5% (Closed-loop control) Carrier frequency 2-5kHz Frequency setting 0.01Hz (digital command) 2 5keslution 0.06Hz/120Hz (analog command 11bit+ unsigned) Normanication 0 Running command channel Operation panel , control terminal and communication Greque compensation 4.000000000000000000000000000000000000					

• Technical indicators and specifications of PWM rectifier module

Power input	Voltage and power range	3-Phase U4N: 380-500VAC[-10%+10%] 3-phase U6N: 520-690VAC[-10%+10%]				
	Input frequency	45~65Hz				
	Control mode	Vector control				
	THDi (rated current)	<4% (harmonics meet IEEEE519 requirements)				
Control characteristics	Power factor	Above 0.95 (rated current)				
Characteristics	Overload capacity	150% 1 min				
	Carrier frequency	2~ 4k (Hz)				
	Efficiency (rated power)	>97%				

• Operating environment and standard requirements

	Usage occasion	It is installed vertically in a well-ventilated electrical control cabinet; horizontal or other installation mode is not allowed. Keep out of direct sunlight, dust, corrosive gases, combustible gases, oil mist, water vapor or dropping water The cooling medium is the air.			
	Operating ambient temperature	-10°C[no condensing]+40°C			
	Temperature derating use	>40°C; when the temperature rises by 1°C, the rated output current is reduced by 2% (up to 50°C)			
	Storage temperature	-40°C+70°C			
	Transport temperature	-40°C+70°C			
	Relative humidity	5~95%RH, no condensation, corrosion or dropping water			
Environmental conditions	Storage	IEC60721 -3-1 Class 1C2 (chemical gas) Class 1S2 (solid particle)			
	Transportation	IEC60721 -3-2 Class 2C2 (chemical gas) Class 2S2 (solid particle)			
	Operation	IEC60721 -3-3 Class 3C1/3C2* (chemical gas) Class 3S2 (solid particle) C= chemical active substance, S= mechanical active substance, * coated circuit board			
	Altitude	1000m			
	Height derating use	>1000M; when the height rises by 100m, the rated output current is reduced by 1% (up to 3000			
	Earthquake-proof characteristics	3.5m/s2, 2~9Hz; 10m/s2,9~120Hz;			
	Protection grade	IP 20			
Others	Cooling mode	Forced air cooling			
	Installation mode	In-cabinet installation			
Product standards	Mechanical clauses 98/37/EC				
	Follow EN61800-3 standard				

High Voltage

Introduction of inverter unit

AS700-03 inverter drive unit

Hardware characteristics:

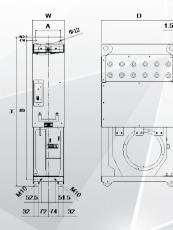
- · Bidirectional DC power supply inverter is used for motor power supply and drive;
- More convenient modular design and diversified installation:
- Cooling fan and capacitor with ultra-long life;
- Thickened coated circuit board design;
- Drive and control optical fiber communication and improve the anti-interference ability of the system
- Support parallel connection of multiple units

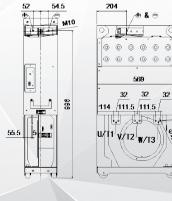
AS700 inverter drive unit specification

						L*W*Hmm	
Product model				PhdkW			
Un=400V (range 380~500V)							
AS700 03 0490 T04	490	250	382	200	D08	232*549.5*1080	
AS700 03 0600 T04	600	315	468	250	D08	232*549.5*1080	
AS700 03 0700 T04	700	355	545	280	D08	232*549.5*1080	
	Un=6	90V (range 525-6	690V)				
AS700 03 0322 T06	322	315	251	220	D08	232*549.5*1080	
AS700 03 0367 T06	367	355	286	280	D08	232*549.5*1080	
AS700 03 0429 T06	429	400	334	315	D08	232*549.5*1080	

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Main circuit terminal size of inverter drive unit



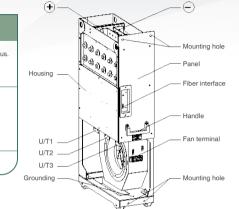


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Terminal label	Terminal function description
	DC bus positive and negative terminals, common DC bus.
	 DC bus output when used as rectifier unit; DC bus input when used as inverter unit
	① Three-phase AC input when used as rectifier unit
	 Three-phase AC output when used as inverter unit
Ð	Ground terminal, connecting the protection ground



Outline and installation dimensions of inverter drive unit

A	В	н	w	D	Mounting hole		Installation		Fastening	Mass		
(mm)							diameter Φ (mm)	Bolt	Flat washer	Spring washer	torque (Nm)	(kg)
182	1007.5	1080	232	549.5	12	4M10	40 Φ 10	40 Φ 10	14	84		

AS700-05 SCR unit

Hardware characteristics:

- Unidirectional (electric direction) rectifier device in the common DC bus system;
- The dedicated reactor at the input side supports parallel connection of units;
- Support 12,18 or 24-pulse rectification;
- External charging circuit is not required for SCR unit;
- SCR unit may charge the DC bus and is suitable for the occasions without higher requirement for the harmonic quantity or without the need for energy regeneration.



Low Voltage Inverter

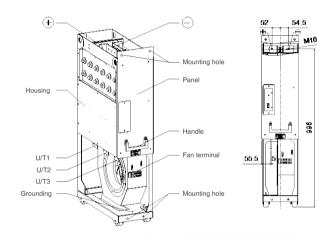
SCR unit specification

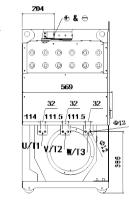
Product model		Pn kW	Ihd A	Phd kW	Framework		
Un=400V (range 380 ~ 500V)							
AS700 05 0730 T04	730	432	546	321	D08		
Un=690V (range 525-690V)							
AS700 05 0450 T06	450	450	351	351	D08		

Outline and installation dimensions of SCR unit

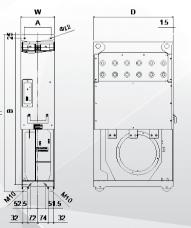
A						Mounting hole				Fastening	
(mr					diameter Ф (mm)		Flat washer	Spring washer	torque (Nm)	(kg)	
182	2	1007.5	1080	232	549.5	12	4M10	40 Φ 10	40 Φ 10	14	84

• AS700-07 LCL filter unit





Terminal label	
÷	DC bus positive and negative terminals, common DC
θ	bus, DC bus output;
U/T1	
V/T2	Three-phase AC input
W/T3	
Ð	Ground terminal, connecting the protection ground



т

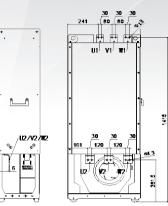


Outline and installation dimensions of SCR unit

Product model	In A		
Un=400V (rang	e 380~500V)		
AS700 07 0407 T04	407	L01	
AS700 07 0647 T04	647	L01	
AS700 07 0968 T04	968	L01	
Un=690V (rang	e 525-690V)		
AS700 07 0301 T06	301	L01	
AS700 07 0462 T06	462	L01	
AS700 07 0592 T06	592	L01	

Main circuit terminal size of LCL filter unit

Terminal label	Terminal function description
	Three-phase AC input
	Three-phase AC input
Ð	Ground terminal, connecting the protection ground

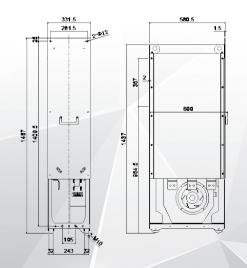


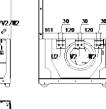


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Overall dimensions of LCL filter unit





Outline and installation dimensions of LCL filter unit

Current	A (mm)	B (mm)	H (mm)	W (mm)	D (mm)	Mounting hole diameter Φ (mm)				Fastening	
								Flat washer	Spring washer	torque (Nm)	(kg)
Un=400V (range 380-500V)											
407											
647	182	1007.5	1080	232	549.5	12	4M10	4 Φ 10	4 Φ 10	14	274
968											370
					Un=690V	(range 525~690	OV)				
301											316
462	182	1007.5	1080	232	549.5	12	4M10	4 Φ 10	4 Φ 10	14	352
592											380

AFE active rectifier

Hardware characteristics:

- Bidirectional (energy regeneration) rectifier device in the common DC bus system;
- · Consist of power drive unit and LCL filter;
- AFE shall be configured with a pre-charging circuit separately;
- AFE may be connected in parallel mutually without the need for a special connector;
- Apply to the application occasions requiring low grid harmonics or energy regeneration;
- Wide power capacity range:

Level 400V: 250kW-1400kW Level 690V: 315kW--1600kW



Control unit

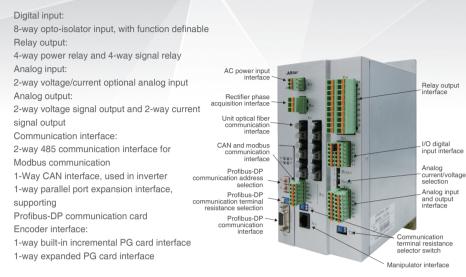
Hardware characteristics:

- Adopt STM32 control chip, internally installed with ARM Cortex-M3 kernel;
- High performance, low power consumption and strong operational capability;
- · Control and drive optical fiber isolation to improve the product anti-interference ability ;
- Built-in multiple interfaces, such as digital quantity, analog quantity, communication and encoder;
- Choose to burn the motor driver or AFE rectifier program;

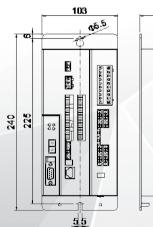
AS700.CN/A 01 rectifier control unit (code C01) AS700.CN/A 02 inverter control unit (code C02)



Peripheral interfaces:

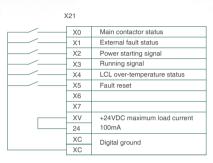


Control unit size:





Rectifier control circuit terminal function description



Main contactor

Soft start contactor control

Fan contactor control

control

Run

X20

1B

1A

2B

2A

3B

ЗA

4B

4A

5C

5B

5A

6C

6B

6A

7C

7B

7A

8C

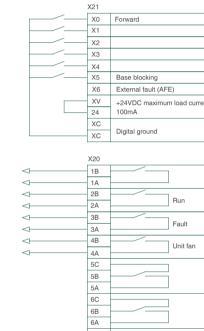
8B

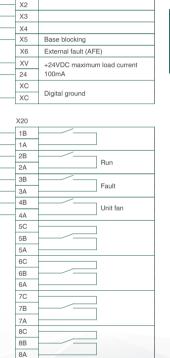
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Inverter drive control circuit terminal function description



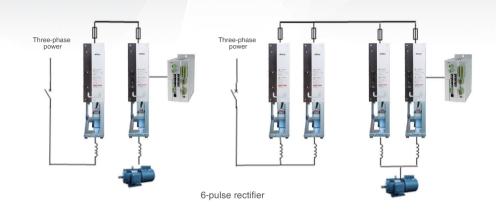


ligh Voltage

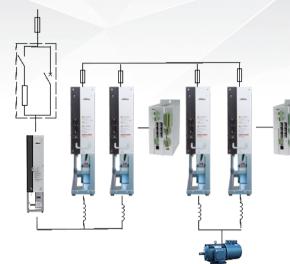
Low Voltage Inverter

System design scheme

• SCR scheme



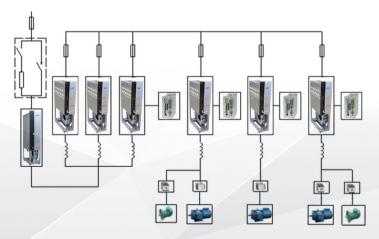




Note:

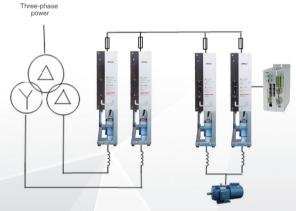
AFE full-feedback rectifier scheme may construct AFE drive system by means of the standard drive module configured as motor driver or AFE rectifier, so as to achieve energy regeneration and eliminate harmonics.

Multi-motor-drive system scheme





In multi-motor-drive configuration, the controller number is consistent with the motor number.



12-pulse rectifier

Note:

Separate drive scheme may achieve site standardization. Single-drive parallel drive scheme connects a number of AS700 03 in parallel to achieve higher output current.

Model selection by customer

Module specification

AS700 two-quadrant inverter module specification

Product model	Standard	application	Heavy load application		Framework
Floduct model	In A	Pn KW	lhd A	Pnd KW	
		Un=400V (rang	je 380~500V)		
AS700 11 0490 T04	490	250	382	200	D08*1+D08*1
AS700 11 0600 T04	600	315	468	250	D08*1+D08*1
AS700 11 0700 T04	700	355	545	280	D08*1+D08*1
AS700 11 0960 T04	960	500	750	400	D08*2+D08*2
AS700 11 1176 T04	1176	630	918	500	D08*2+D08*2
AS700 11 1372 T04	1372	710	1071	560	D08*2+D08*2
AS700 11 1746 T04	1746	900	1372	710	D08*3+D08*3
	2037	1120	1591	900	D08*3+D08*3
AS700 11 2688 T04	2688	1400	2100	1120	D08*4+D08*4
		Un=690V (rang	je 525~690V)		
	322	315	251	220	D08*1+D08*1
	367	355	286	280	D08*1+D08*1
AS700 11 0429 T06	429	400	334	315	D08*1+D08*1
AS700 11 0632 T06	632	630	493	450	D08*2+D08*2
AS700 11 0700 T06	700	710	545	500	D08*2+D08*2
AS700 11 0840 T06	840	800	655	630	D08*2+D08*2
AS700 11 1067 T06	1067	1120	831	800	D08*3+D08*3
AS700 11 1206 T06	1206	1200	940	900	D08*3+D08*3
AS700 11 1423 T06	1423	1400	1109	1000	D08*4+D08*4
AS700 11 1591 T06	1591	1600	1240	1200	D08*4+D08*4

AS700 four-quadrant inverter module specification

Product model	Standard	Standard application		application	Framework
	In A		Ihd A		
		Un=400V (rang	e 380~500V)		
AS700 12 0490 T04	490	250	382	200	D08*1+D08*1+L01
AS700 12 0600 T04	600	315	468	250	D08*1+D08*1+L01
AS700 12 0700 T04	700	355	545	280	D08*1+D08*1+L01
AS700 12 0960 T04	960	500	750	400	D08*2+D08*2+L01
AS700 12 1176 T04	1176	630	918	500	D08*2+D08*2+L01
AS700 12 1372 T04	1372	710	1071	560	D08*2+D08*2+L01
AS700 12 1746 T04	1746	900	1372	710	D08*3+D08*3+L01*2
	2037	1120	1591	900	D08*3+D08*3+L01*2
AS700 12 2688 T04	2688	1400	2100	1120	D08*4+D08*4+L01*2
		Un=690V (rang	e 525~690V)		
	322	315	251	220	D08*1+D08*1+L01
AS700 12 0367 T06	367	355	286	280	D08*1+D08*1+L01
AS700 12 0429 T06	429	400	334	315	D08*1+D08*1+L01
AS700 12 0632 T06	632	630	493	450	D08*2+D08*2+L01
AS700 12 0700 T06	700	710	545	500	D08*2+D08*2+L01
AS700 12 0840 T06	840	800	655	630	D08*2+D08*2+L01
AS700 12 1067 T06	1067	1120	831	800	D08*3+D08*3+L01*2
AS700 12 1206 T06	1206	1200	940	900	D08*3+D08*3+L01*2
AS700 12 1423 T06	1423	1400	1109	1000	D08*4+D08*4+L01*2
AS700 12 1591 T06	1591	1600	1240	1200	D08*4+D08*4+L01*2

AS700 inverter drive module specification

Product model	Standard application		Heavy load application		Framework
Floduct model	In A	Pn KW	Ihd A	Pnd KW	
		Un=400V (rang	ge 380~500V)		
AS700 13 0490 T04	490	250	382	200	D08*1
	600	315	468	250	D08*1
AS700 13 0700 T04	700	355	545	280	D08*1
AS700 13 0960 T04	960	500	750	400	D08*2
AS700 13 1176 T04	1176	630	918	500	D08*2
AS700 13 1372 T04	1372	710	1071	560	D08*2
AS700 13 1746 T04	1746	900	1372	710	D08*3
AS700 13 2037 T04	2037	1120	1591	900	D08*3
AS700 13 2688 T04	2688	1400	2100	1120	D08*4
		Un=690V (rang	ge 525~690V)		
AS700 13 0322 T06	322	315	251	220	D08*1
	367	355	286	280	D08*1
AS700 13 0429 T06	429	400	334	315	D08*1
AS700 13 0632 T06	632	630	493	450	D08*2
	700	710	545	500	D08*2
	840	800	655	630	D08*2
AS700 13 1067 T06	1067	1120	831	800	D08*3
AS700 13 1206 T06	1206	1200	940	900	D08*3
AS700 13 1423 T06	1423	1400	1109	1000	D08*4
AS700 13 1591 T06	1591	1600	1240	1200	D08*4

AS700 PWM rectifier module specification

Product model	Standard	Standard application		application	Framework
Floader	In A	Pn KW	Ihd A	Pnd KW	FIGHTEWOIK
		Un=400V (rang	e 380~500V)		
AS700 14 0384 T04	384	250	300	200	D08*1+L01
AS700 14 0473 T04	473	315	370	250	D08*1+L01
AS700 14 0573 T04	573	355	447	280	D08*1+L01
AS700 14 0752 T04	752	500	588	400	D08*2+L01
AS700 14 0927 T04	927	630	724	500	D08*2+L01
AS700 14 1123 T04	1123	710	880	560	D08*2+L01
AS700 14 1376 T04	1376	900	1075	710	D08*3+L01*2
AS700 14 1667 T04	1667	1120	1302	900	D08*3+L01*2
AS700 14 2200 T04	2200	1400	1718	1120	D08*4+L01*2
		Un=690V (rang	je 525~690V)		
AS700 14 0274 T06	274	315	214	220	D08*1+L01
AS700 14 0328 T06	328	355	256	280	D08*1+L01
	352	400	274	315	D08*1+L01
AS700 14 0538 T06	538	630	420	450	D08*2+L01
	642	710	500	500	D08*2+L01
AS700 14 0690 T06	690	800	538	630	D08*2+L01
AS700 14 0956 T06	956	1120	746	800	D08*3+L01*2
AS700 14 1024 T06	1024	1200	798	900	D08*3+L01*2
AS700 14 1272 T06	1272	1400	994	1000	D08*4+L01*2
AS700 14 1351 T06	1351	1600	1053	1200	D08*4+L01*2

Note:

D08*N, L01*N, in which, N is the unit number

D08 boundary dimensions W*H*D(width * height *depth): 232*1080*549.5(mm);

L01 boundary dimensions W*H*D(width * height *depth): 331.5*1481*580.5(mm);

Standard application (120% overload capacity) and heavy load application (150% overload capacity)

In— rated current of inverter Ihd—heavy load current of inverter Pn—rated power of inverter Phd—heavy load power of inverter

Remarks:

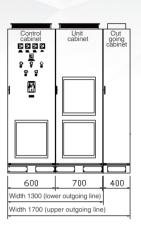
Contact the company for other powers and dimensions.

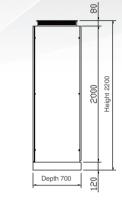
Low Voltage Inverter

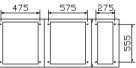
Four-quadrant inverter cabinet

	Standard application		Heavy load application		5
	In A	Pn KW	Ihd A	Pnd KW	
		Un=400V (rang	ge 380~500V)		
	490	250	382	200	B1
AS700 22 0600 T04	600	315	468	250	B1
AS700 22 0700 T04	700	355	545	280	B1
AS700 22 0960 T04	960	500	750	400	B2
AS700 22 1176 T04	1176	630	918	500	B2
AS700 22 1372 T04	1372	710	1071	560	B2
AS700 22 1746 T04	1746	900	1372	710	B3
AS700 22 2037 T04	2037	1120	1591	900	B3
AS700 22 2688 T04	2688	1400	2100	1120	B4
		Un=690V (rang	ge 525~690V)		
	322	315	251	220	B1
	367	355	286	280	B1
AS700 22 0429 T06	429	400	334	315	B1
	632	630	493	450	B2
AS700 22 0700 T06	700	710	545	500	B2
AS700 22 0840 T06	840	800	655	630	B2
	1067	1120	831	800	B3
AS700 22 1206 T06	1206	1200	940	900	B3
AS700 22 1423 T06	1423	1400	1109	1000	B4
AS700 22 1591 T06	1591	1600	1240	1200	B4

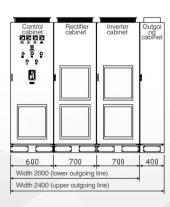
Cabinet frame size







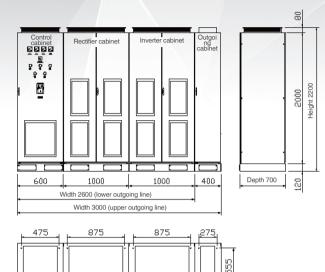
Frame A1 (the outgoing cabinet is the upper outgoing line option)







Frame A2 (the outgoing cabinet is the upper outgoing line option)



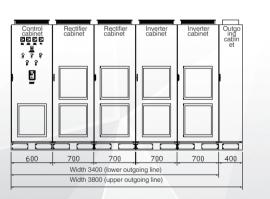
Frame A3 (the outgoing cabinet is the upper outgoing line option)

80

2000

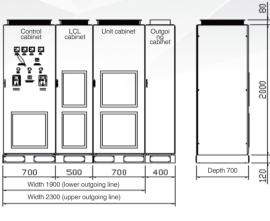
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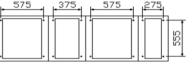
Depth 700



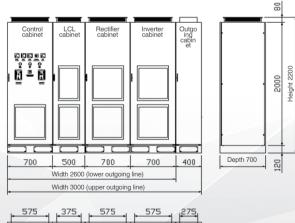


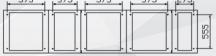
Frame A4 (the outgoing cabinet is the upper outgoing line option)





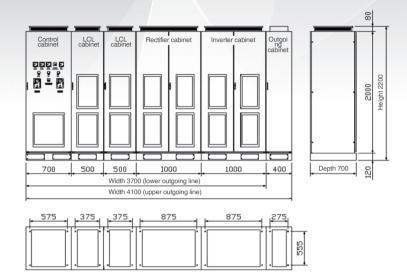
Frame B1 (the outgoing cabinet is the upper outgoing line option)



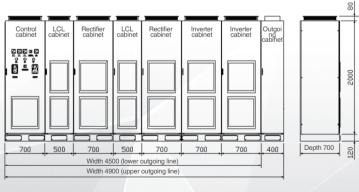


Frame B2 (the outgoing cabinet is the upper outgoing line option)

leight 2200



Frame B3 (the outgoing cabinet is the upper outgoing line option)





Frame B4 (the outgoing cabinet is the upper outgoing line option)

Dedicated Purpose Inverter

AS170 Series Motor-Integrated Inverter

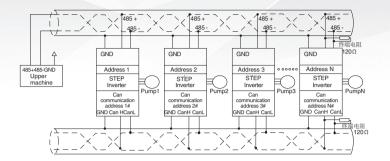


Product characteristics

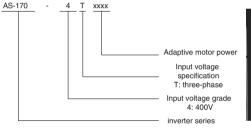
AS170 series inverter is a motor-driven integrated machine with high protection grade developed by Shanghai Sigriner Electric Co., Ltd., adopting unique appearance design and installation methods, with local and remote control mode, more convenient, reliable and safe to install and use.

- Advanced high-performance vector VF control mode improved the motor control accuracy, and reduced the motor consumption, achieving superior energy-saving effect
- Dedicated function of water pump: achieve full frequency conversion constant pressure water supply without PLC or control cabinet
- Periodic break control, balance working hours of water pump, and effectively prevent corrosion of water pump
- Flexible power off/on mode meets the requirements of minimal system pressure, avoiding water
 pump frequent starting and stopping
- Warning function of pipe network over /under voltage can early warn water pump idle or pipeline leakage
- In case of failure, pump automatically exiting from the system, quickly compensate for pipe network pressure drop
- Good environmental adaptability: whole series products have IP55 protection grade, 2g shock protection grade
- Automatic voltage regulation function (AVR), keep output voltage constant, ensure the characteristic curve of water pump not affected by grid fluctuation
- Automatically diminished frequency function for overcurrent, overvoltage/undervoltage, reduce the report of fault, and make the system running smoothly longer
- The external interface of the inverter adopts aviation fast plug, which is more convenient, timeand effort-saving

System topology



Model specification





Technical parameters and dimensions

		nning 45 °C, overloa			
Inverter model AS170	Rated input current (A)	Rated output current (A)	Adaptive motor (kw)	Overloaded 120%(1min) output current (A)	Dimensions
4T01P5	3.8	3.5	1.5	4.2	ALC: NOT
4T02P2	5.3	5	2.2	6	A1
4T03P0	6.5	6	3.0	7.2	AI
4T04P0	8.5	8	4.0	9.6	
4T05P5	11.5	11	5.5	13.2	40
4T07P5	16	15	7.5	18	A2
4T0011	21	20	11	24	40
4T0015	30.5	29	15	34.8	A3

gh Voltage Inverter

Pump

Technical specifications

	Input voltage	380-460V (-15% - +10%), three-phase power								
	Input Frequency	45-65Hz								
Power intput	Accepting voltage change	Voltage unbalance<3%								
	Instantaneous voltage drop	When three phase AC380-460V power, and input voltage <ac300v, lo<="" td=""><td>w-voltage protection was implemented after 15ms.</td></ac300v,>	w-voltage protection was implemented after 15ms.							
	Voltage	OVAC-input voltage								
	Overload grade	Stable running 45°C, overloading 120%, 1min								
	Efficiency	≥97%(full-load)								
	Output frequency accuracy	$\pm 0.01\%$ (digital command -10 - +45 $^\circ \rm C$); ±0.1% (analog comm	nand 25 ± 10℃)							
	Optical coupling isolation input	6 channels, 24V high and low level can be set, input function	n can be defined							
Digital	Open collector output	1 channel, output function can be defined								
	Relay output	2 channels, dual normally open/closed contacts, contact capa inductive: 0.4A/250VAC or 0.4A/30VDC; output function can l								
Analog	Analog voltage input	2 channels, accuracy 0.1%; voltage:0V - +10VDC or current:	0-20mA optional signal							
	Analog voltage output	1 channel, accuracy 0.1%; voltage :OV - +10VDC or current:	0-20mA optical signal							
	Control mode	V/F control	High-performance V/F (VFVC)							
	Start torque	2.50Hz, 120%	0.5Hz, 120%							
	Speed range	1:50	1:200							
	Steady-speed accuracy	± 2%	± 0.5%							
	Load frequency	1.1- 8kHz: carrier frequency can be regulated automatically according to load characteristics								
	Frequency setting resolution	0.01Hz (digital command), ±0.06Hz/120Hz (analog command 11 bit + no signal)								
Control	Running command channel	Given operation panel, given control terminal, given communication								
	Frequency-given channel	Given operation panel, given digital quantity/analog quantity, given communication, given performance function								
	Torque improved	Automatic torque improved, manual torque improved								
	V/F curve	User-defined V/F curves, linear V/F curves, and three reduced torque characteristic curves								
	Automatic voltage Regulation(AVR)	The duty ratio of output PWM signal is regulated automatically based on the fluctuation of busbar voltage fluctuation, to reduce the influence of grid voltage fluctuation on output voltage fluctuation								
	Electricity loss and keep-running process	In the case of instantaneous power-off, achieve uninterrupted operation through busbar voltage control								
	keep-running process Direct current braking capability	Brake current: 0.0 - 120.0% rated current								
	Parameters copy	The standard operation panel can upload and download para	ameters, and indicate copy progress							
	Process PIO	Used for closed-loop control of process quantities								
	Common DC busbar	All series can achieve the power supply of common DC busb	ar for multiple inverter							
	Reduce frequency function for overcurrent/overvoltage	When the current and voltage reach the setting value, inverte	r shall run with reduced frequency.							
	Reduce frequency function for overheating	When the temperature of cooling plate is higher than 95 $^\circ\!\mathrm{C},$ in	verter shall run with reduced frequency.							
	Build-in constant pressure water supply control (Full frequency)	Through CAN communication, the operation logic of multiple decrease the number of pump can be achieved.	full-frequency pumps to increase or							
	Rotor block									
Motor protection	Motor overload									
	Speed limit									
	Current limit									
	Inverter overload									
Inverter protection	IGBT I ² t overloaded									
protection	Input power undervolta	ge/overvoltage								
	DC Bus undervoltage/o	overvoltage								
	IGBT overheating									

	Heat sink overheat	ing							
	Power faulty								
nverter otection	Analog input signal loss (loss speed reference value)								
	communication abr	communication abnormality							
	self-tuning faulty								
	Operation place	Indoor use only, vertically or horizontally installed with motor fixed through the adapter plate, andcooling medium is air.							
	Environment temperature	-10~+55°C							
	Used in derating temperature	$>45^\circ\!\mathrm{C}$, a rise of 1 $^\circ\!\mathrm{C}$, rated output current is reduced by 2%, the highest temperature is 55 $^\circ\!\mathrm{C}$							
	Altitude	<3000m							
	Used in derating height	>2000 m, a rise of 100m, rated output current is reduced by 2% (up to 3000m)							
	Environment humidity	5-95%, without condensation							
	Vibration grade	2g							
	Storage temperature	-40~+70°C							
	Protection grade	IP55							
	Туре	Fixation							
	Connect	RJ45							
	LCD text display	4 row							
	Visible LED indicator	4 pcs							
	Key	9 pcs							
	Cooling approach	Force-air cooling							
thers	Installation mode	Install vertically or horizontally							

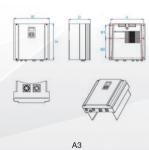
General AS series inverter dimensions and specifications

Specification	A (mm)	B (n	nm)	H (mm)	W (mm)	D (mm)
A1	230	23	30	272	260	196
A2	266	28	38	330	294	203
A3	340	135 200		373	369	222

A2



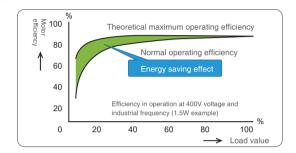




AS hoisting industry inverter performance characteristics

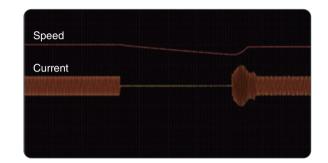
• Efficient and energy-saving operation mode

The high-efficiency driven energy-saving operation mode and new PWM dead zone compensation technique can effectively reduce the motor loss and maximize the power saving rate.



• Smooth tracking start

Perfectly achieve smooth start of the motor in rotation without impact at any time.



High Volt

• Fast dynamic response

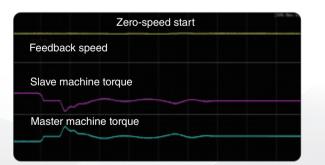
Spee Curre

Torqu

The advanced motor control mode can quickly respond to the sudden change in the load even if no PG card is available.

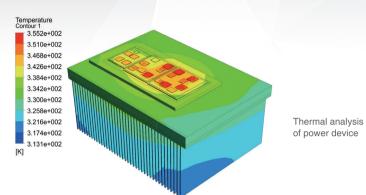
• Torque memory function

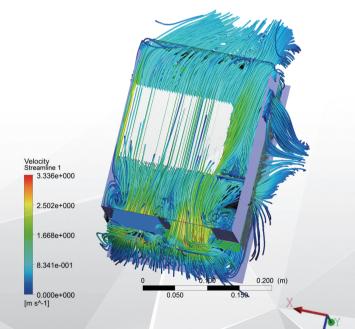
Record the output torque of the motor every time when the brake is closed. When the brake is open next time, output the memory torque last time to ensure that the heavy object does not slip from the hook. (Support closed-loop control only)



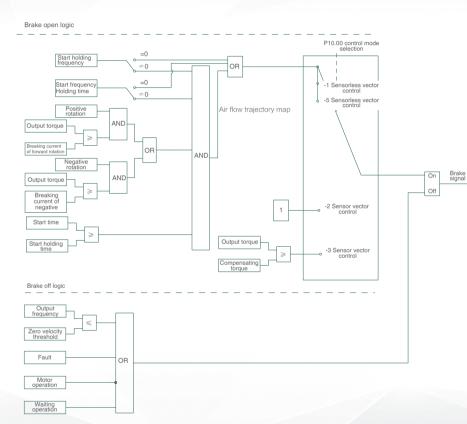
• Structure: reasonable and scientific

Unique air duct and compact thermal design, making the temperature rise far below the national standard





• Brake logic: perfect, safe and reliable



High Voltage Inverter

Low Voltage Inverter

Dedicated Purpose Inverter

Self-learning: rich and intelligent

To control the motor more accurately, the inverter may obtain relevant parameters of the motor by self-learning.

Self-learning: rich and intelligent

- · Static self-learning of editor
- · Static self-learning of motor
- Optimized self-learning of inverter
- Static advanced learning of motor
- · Dynamic self-learning of editor

Protection functions: perfect, safe and reliable

Motor protection

- Motor over-temperature protection (PTC)
- · Locked rotor protection
- Motor overload protection
- Motor open-phase protection
- Speed limit

Inverter protection

- Output current limiting
- Inverter over-temperature protection
- I2t protection
- Heatsink OT protection
- · Power supply fault
- IGST over-temperature protection
- Analog input signal loss (speed reference value loss)
- Communication exception

Weakened flux and constant power function

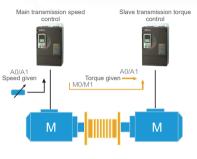
The inverter independently calculates the maximum speed (above base frequency) under the rated power to improve the equipment working efficiency.



Master-slave control functions

Rigid coupling

- The master drive unit is controlled by speed. The slave drive unit is controlled by torque.
- . The torque analog of the master drive unit is output to the slave drive unit as the torque given signal.



Motor parameter and operation curve switching function

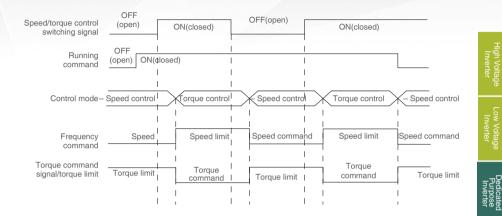
One inverter is used to control 2 mechanisms by output contactor switching to reduce equipment input. The inverter completes the motor parameter and operation curve parameter switching immediately upon receipt of the switching signal to ensure normal equipment operation.



Motor 2

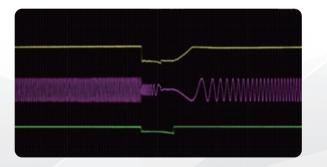
Static and dynamic speed and torgue switching function

Achieve static and dynamic speed/torgue switching



Strong grid adaptability

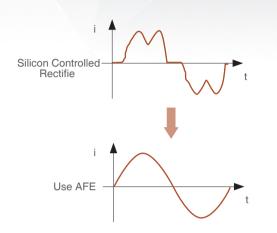
Automatic voltage regulation function: automatically keep the output voltage constant in case of change in the network voltage. The unique instant uninterrupted power function can keep the inverter running without shutdown in case of sudden power loss.



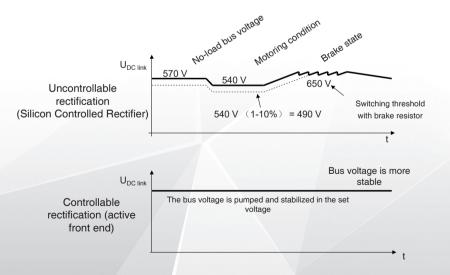
79

- Reduce reactive power and current harmonics
 - Cos φ = 1
 - THDi < 4%





• DC bus voltage is more stable





AS600 special inverter for cranes

• Product introduction

AS600 special inverter for crane is designed for the industrial cranes, such as guayside container bridge crane, container gantry crane, portal crane and beam crane. With the use of advanced vector control technology and torgue control technology, the product has the same excellent control performance with high-end international inverter and, combined with the application characteristics in the hoisting machinery industry, further strengthens the product output characteristics, reliability and environmental adaptation and can better meet various application requirements of the hoisting machinery.



• Technical features

High torque and high load capacity

- Support synchronous and asynchronous motors
- Perfect, safe and reliable brake logic
- Fast, preeminent and high adaptive dynamic response
- Smooth and shockless speed tracking start
- Support Profibus-DP and Modbus communication
- Perfect, safe and reliable motor inverter protection function
- Master and slave control func Weakened flux and constant power function
- Torque memory function
- · Parameter and operation curve switching function of 2 sets of motors
- · Static and dynamic speed and torque switching function
- · Non-stop at instantaneous stop

Application industries

- Harbor machinery: quayside container bridge crane, tyre crane and portal crane
- Standard lifting: bridge crane, portal crane, electric hoist, belt conveyor and winch
- Construction lifting: tower crane

Product model



Model and technical data

Inverter model AS400 4T-	02P2	03P7	, 05	P5	07P5	0011	0015	18P5	002	22	0030	0037	0045
Maximum power of adaptive motor (kW) (SHD))	1.1	2.2	3	.7	5.5	7.5	11	15	18.	5	22	30	37
Maximum power of adaptive motor (kW) (SHD)	2.2	3.7	5	.5	7.5	11	15	18.5	22	2	30	37	45
Rated output current (A) (SHD)	3.5	6.2	1	1	15	21	27	34	41		52	65	80
Rated output current (A) (SHD)	6.2	9	1	3	17	25	31	39	45	;	60	75	91
Carrier frequency (kHz)					2-8kł	Hz (modifie	d in param	eters)					
Inverter model AS600 4T-													0355
Maximum power of adaptive motor (kW) (SHD)	45	55	75	90	110	132	160	185	200	220	250	280	315
Maximum power of adaptive motor (kW) (SHD)	55	75	90	110	132	160	185	200	220	250	280	315	355
Rated output current (A) (SHD)	97	128	165	195	236	270	330	360	390	430	470	525	585
Rated output current (A) (SHD)	112	150	180	216	260	300	370	390	426 480		520	0 600	650
Carrier frequency (kHz)	2-8kHz (modified in parameters) 2-5kHz (modified in parameters)												
Supply voltage	AC 3-phase, 380-460V 50/60Hz												
Permissible power fluctuation		-15%-10% (interphase unbalance rate \leq 3%, add the DC reactor to improve the power factor)											
Permissible frequency fluctuation		-5% 5%											
Instantaneous low voltage tolerance	Co	Continue to run above 300V: continue to run 15ms when the rated voltage falls below 300V (test valye at 80% load)						oad)					

• Technical features

	Input voltage	(380-460) V (-15%-+10%), three-phase supply, voltage unbalance <3%
Power input	Input frequency	(45-65) Hz
r ower input	Instantaneous power drop	Undervoltage protection when the input voltage is less than AC300V in the power supply AC(380-460)V
	Voltage	OVAC - input voltage
Power output	Output frequency	V/F control: (0.00/300.00) Hz, vector control: (0.00-120.00) Hz
	Overload level	Heavy load: 150%, 60S; super-heavy load: 150%, 60S; 200%, 2S
Digital IO	Output frequency accuracy	\pm 0.01% (digital command- 10 - +45°C) ; \pm 0. 1% (analog command 25 \pm 10 °C)
	Opto-isolator input	7-channel, 24V active high and low settable and input functions definable
	Open collector output	2-channel, output functions definable
Analog input	Relay output	2-channel normally open, 2-channel normally open and normally closed contacts
and output	Analog voltage input	2-channel, voltage: (-10~+10) VDC or current: (0-20) mA optional signal
	Analog voltage output	2-channel, voltage: (-10~+10) VDC or current: (0-20) mA optional signal

	PG card power	5V, 12V,300mA							
	PG card signal	Open collector, push-pull, differential, SIN/COS incremental, Endat absolute value type, Resover type,orthogonal open collector output and division factor 2/4/8/16/32/64/128 settable (optional)							
	Control mode	V/F control	Open-loop vector control	Closed-loop control					
	Starting torque	2.50Hz,150%	0.5Hz,200%	0.00Hz,200%					
	Steady speed precision	± 2%	± 0.2%	± 0.02%					
	Torque precision	5% (Closed-loop control)							
	Torque compensation	Automatic torque compensation a	nd manual torque compensation						
	V/F curve	User-defined V/F curve, linear V/F	curve and 3 reduced torque cha	aracteristic curves					
Control characteristics	Automatic voltage regulation (AVR)	Automatically adjust the duty cycle	e of PWM signal according to the	e bus voltage fluctuation					
	Non-stop at instantaneous stop	Achieve continuous operation through bus voltage control in case of instantaneous power failure							
	Dynamic braking capacity	Built-in brake unit and external bra External brake unit (optional) for t		ver 22kW and below					
	DC braking capacity	Braking current: (0.0-120.0 % rate	ed current						
	Torque control function	Torque/speed control switching th	rough terminals, many torque gi	ven modes					
	Zero servo and position control function	Achieve zero speed position lock,	accurate positioning and positio	n control					
	Common DC bus	The whole series may achieve po	wer supply of many inverters by	common DC bus					
	Usage occasion	Keep out of direct sunlight, dust, cor	rosive gases, combustible gases, c	il mist, water vapor or dropping water					
	Environment temperature	(-10~+40)C							
Environmental conditions	Altitude	<1000m							
	Environment humidity	(5-95)%, no condensation allowed	l						
	Vibration (installation)	2≤f<9Hz,0.3mm; 9≤f<200Hz	, 1m/s2						
	Protection grade	IP20							
Others	Cooling mode	Forced air cooling							

Inverter size specification of A1 specification

0000

	Inverter model	А	в	н	w	D	Mounting hole diameter		Installation		Fastening torque	Mass
Specification	AS6000	(mm)	(mm)	(mm)	(mm)	(mm)	Φ (mm)	Bolt	Nut	Washer	(Nm)	(kg)
	4T02P2											
A1	4T03P7	100	288.5	300	160	162	5.0	4M4	4M4	4Φ4	1.1	4.5
	4T05P5											

High Voltage Inverter

Eow Voltage

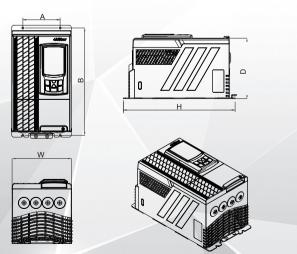
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Dedicated Purpose Inverter And t

Inverter size diagram of A4-A9 specification

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Inverter size diagram of A1 specification



Inverter size specification of A2-A9 specification

Inverter size diagram of A2-A3 specification

	Inverter model	А	В	н	W	D	Mounting hole diameter		Installation	ı	Fastening torque	Mass														
Specification							Φ (mm)				(Nm)															
10	4T07P5	165.5	057	070		400	7.0				0.5															
A2	4T0011	165.5	357	379	222	182	7.0	4M6	4M6	4Φ6	3.5	8														
	4T0015																									
A3	4T18P5	165.5	392	414	232	182	7.0	4M6	4M6	406	3.5	10.3														
	4T0022																									
A4	4T0030	200	512	530	330	288	9.0	4M8	4M8	4 Φ 8	9	29.5														
A4	4T0037	4T0037	512	530	330	200	9.0	41010	41110	440	9	29.0														
A5	4T0045	200	200	200	200	200	200	200	200	200	200	200	200	200	200	200	585	610	330	310	9.0	4M8	4M8	4 Φ 8	9	38
AS	4T0055		565	010	550	510	3.0		41110		-	30														
A6	4T0075	320	718	750	430	350	13.0	4M12	4M12	4Φ12	29	79.5														
A7	4T0090	320	320	320	320	320	320	768	800	430	350	13.0	4M12	4M12	4Φ12	29	81									
	4T0110	020	700	000	430	550	15.0	41112	-11/172	4412	20	01														
	4T0132																									
	4T0160	374	844	880	500	500 352	13.0	4M12	4M12	4Φ12	29	106.5														
A8	4T0185																									
	4T0200	374	844	880	500	52	13.0	4M12	4M12	4Φ12	29	112.5														
	4T0220	5/4	044	000	500	52	10.0	411172	410112	4412	20	112.5														
	4T0250											141														
A9	4T0280	500	997	1030	630	370	14.0	4M12	4M12	4 Φ 12	29	168														
	4T0315	0.00	007	1030			14.0	411172		4012	29	169														
	4T0355											170														

AS620 special inverter for construction lifts

Product introduction

AS620 inverter is the latest inverter designed for the lift market and is also used for the lift driving occasions. With the use of the motor control technique fully synchronous with the international advanced technique, the product has the same excellent control performance with high-end international inverter and, combined with the application characteristics of the Chinese lifts, further strengthens the product reliability, environmental adaptation and custom and professional design and can well meet the application requirements of the building hoists.



Model and technical data

Inverter model AS620	Rated capacity	Rated output current (A)	Adaptive motor (kW)
4T05P5	9	13	5.5
4T07P5	13	18	7.5
4T0011	19	27	11
4T0015	24	34	15
4T18P5	29	41	18.5
4T0022	34	48	22
4T0030	45	65	30
4T0037	55	80	37
4T0045	68	97	45
4T0055	89	128	55
4T0075	115	165	75
4T0090	125	180	90
4T0110	150	216	110
4T0132	190	260	132
4T0160	240	302	160

Technical features

- A variety of V/F curves, meeting various field usage requirements
- · Positive and negative torque start and fixed torque start for better comfort
- Safe and reliable AFR function
- · Brake control function to avoid absolute sliding
- Hopping frequency control function to effectively avoid the resonance point of mechanical load
- Automatic slip compensation to reduce the impact of load change on the motor speed
- New PWM dead zone compensation technology effectively reduces the motor loss

Application industries

Target application object: building hoist



Application industries

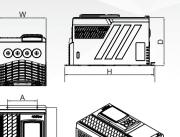
Target application object: building hoist

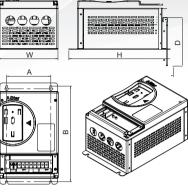


• New energy bus air conditioning

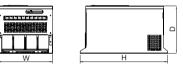
	Input voltage	380-460V (-15%-+10%), three-phase supply, voltage unbalance <3%
Power input	Input frequency	45-65Hz
Fower input	Instantaneous power drop	Undervoltage protection when the input voltage is less than AC300V in the three-phase power supply AC380-460V
	Motor output voltage	OVAC - input voltage, three-phase supply
	Output frequency	V/F control: 0.00/300.00Hz
Power output	Overload level	150%,60s
	Output frequency accuracy	0.01% (digital command- 10 - +45°C); 0.1% (analog command 25 10 °C)
	Opto-isolator input	8-channel, 24V active high and low settable and input functions definable
Digital IO	Open collector output	4-channel, output functions definable
	Relay output	2-channel normally open, 2-channel normally open and normally closed contacts
	Analog voltage input	2-channel, 10~+10VOC or 0-flOVDC precision 0.1%
	Potentiometer voltage	Provide +10VDC power supply (maximum 20mA) for the potentiometer set speed
	Control mode	VIF control
	Starting torque	2.50Hz 150%
Steady speed precisio		2%, obtain 0.5% precision in case of slip compensation
	Carrier frequency	2-8kHz; different default carrier frequency for different inverter power
	Frequency setting resolution	0.01Hz (digital command), 0.06Hz/120Hz (analog command 11bit unsigned)
Control	Torque compensation	Automatic torque compensation; manual torque compensation
	V/F curve	User-defined V/F curve, linear V/F curve and 5 reduced torque characteristic curves
	Automatic voltage regulation	Automatically adjust the duty cycle of PWM signal according to the bus voltage fluctuation
	Automatic frequency regulation	Automatically adjust the output frequency with the bus voltage fluctuation to maintain the torque constant
	Instantaneous stop processing	Achieve continuous operation through bus voltage control in case of instantaneous power failure
	Dynamic braking capacity	External brake resistor for the built-in brake unit at the power 75kW and below
	DC braking capacity	Braking current: 0.0-120.0% rated current
	Common DC bus	The whole series may achieve power supply of many inverters by common DC bus
	Usage occasion	Keep out of direct sunlight, dust, corrosive gases, combustible gases, oil mist, water vapor or dropping water
	Environment temperature	-10-+40 C
	Altitude	Less than 1000m
	Environment humidity	5-95%, no condensation allowed
	Vibration	$3.5 \text{ m/s}^2, \ 2{\sim}9\text{Hz}; \ 10 \text{ m/s}^2, \ 9{\sim}120\text{Hz}$
	Protection grade	IP20
Others	Cooling mode	Forced air cooling

Inverter size





Inverter size diagram of A2-A3 specification



Inverter size diagram of

A1 specification



Inverter size diagram of A4-A7 specification

	Inverter model			H W D Mounting								
Specification							Φ (mm)				torque (Nm)	
A1	4T05P5	100	288.5	300	160	162	5.0	4M4	4M4	4 Φ 4	2.5	4.5
A2	4T07P5	165.5	357	379	222	182	7.0	4M6	4M6	4 Φ 6	3	8
72	4T0011	105.5	337	3/9	222	102	7.0	41010	41010	400	3	0
	4T0015											
A3	4T18P5	165.5	392	414	232	182	7.0	4M6	4M6	4Φ6	3	10.3
	4T0022	1										
A4	4T0030	200	512	530	330	288	9.0	4M8	4M8	4 Φ 8	9	29.5
A4	4T0037	200	512	530	330	200	9.0	41110	41110	400	9	29.0
A5	4T0045	200	587	610	330	310	9.0	4M8	4M8	4 Φ 8	9	38
7.0	4T0055	200	567	010	330	310	9.0	41110	41110	400	9	30
	4T0075	320	718	750	430	350	13.0	4M12	4M12	4 Φ 12	18	79.5
A6	4T0090	320	768	800	430	350	13.0	4M12	4M12	4Φ12	29	81
	4T0110	320	/00	800	430	330	13.0	41112	41112	4012	29	01
A7	4T0132	374	844	880	500	352	13.0	4M12	4M12	4Φ12	29	106.5
7.0	4T0160	374	044	000	500	352	13.0	41112	4IVI 12	4012	29	100.5

Dedicated Purpose Inverter

AS510 AFE rectified feedback unit

Product introduction

AS610 AFE products, with the use of advanced controllable rectification technique and coupled with LCL filter, achieves the active rectification and provides constant DC power and energy feedback for the system. One or more inverter units may operate in the DC bus to form the multi-motor-drive system of four-quadrant operation, providing an ideal solution for the motor control application in various occasions.

Technical features

- Active rectification technique to reduce the reactive power, with the power factor close to 1
- Four-quadrant operation, with energy feedback function
- The DC bus is more stable
- Current harmonics less than 4% in full load
- Standard LCL filter and charging circuit
- · Perfect heat dissipation structure design

• Application industries

- · Harmonic suppression occasions: pump, wind turbine and compressor
- Energy feedback occasions: crane, winch, pipeline, hoist, test bench, turbine motor and other complex drive systems

• Product model



Model and technical data

Dimen sions	Inverter model AS510	Rated output power (kW)	Rated output current (A)	Rated input current (A)					
A1	4T0030	41	62	65					
A2	4T0055	80	122	128					
A3	4T0110	150	228	240					
A4	4T0185	220	334	352					
A4	4T0220	266	403	426					
٨٢	4T0280	325	492	520					
A5	4T0350	405	615	650					
A6	4T0450	511	775	820					
	Stable operation at 40 , heavy load								



• LCL filter and charge resistance configuration table

Product model AS510	Quantity			4T0110	4T0185	4T0220			
Line side L1(mH)	1	0.32	0.13	0.07	0.048	0.04	0.032	0.026	0.02
Machine side L2(mH)	1	1.28	0.52	0.28	0.192	0.16	0.128	0.105	0.08
Capacitance (uF)	3	50	100	150	250	250	300	300	250×2
		60W	60W	200W	200W	200W	300W	400W	500W
Charge resistance	3	10Ω	10Ω	2Ω	2Ω	2Ω	2Ω	2Ω	2Ω

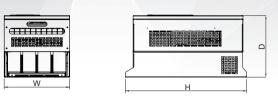
• Capacitance and charge resistance model

Product model AS510	4T0030	4T0055	4T0110	4T0185	4T0220	4T0280	4T0355	4T0450
Capacitance model SHA-500-	50	100	150	250	250	300	300	250×2
Charge resistance model RXLG	60W-10R	60W-10R	200W-2R	200W-2R	200W-2R	300W-2R	400W-2R	500W-2R

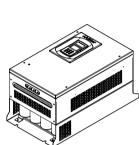
Technical features

Pr	oduct model AS510	4T0030	4T0055	4T0110	4T0185	4T0220	4T0280	4T0355	4T0450	
Ad		30	55	110	185	220	280	355	450	
Ra		38	76	142	209	253	308	358	487	
R. (w	ated output current rhen DC is 660V) A	58	115	215	316	383	467	584	737	
Rate	d input current (AC)A	65	128	240	352	426	520	650	820	
Contro		600~740V	/							
		380~460\	(±15%), T	Three-phase p	ower					
Power input		45~65Hz								
inpat		Undervolta power supp	Indervoltage protection when the input voltage is less than AC300V in the three-phase ower supply AC380-460V							
		Vector con	Vector control							
	Input power factor	Above 0.95 (under rated current)								
Control charac- teristics		Less than 4	Less than 4% (under rated current)							
		150%, 1m	150%, 1min							
		4-6kHz								
			f direct sunlig		sive gases, co	mbustible gas	es, oil mist,			
		-10~+40℃	2							
		1000m								
Environ- mental conditions		5~95%, ľ	5 \sim 95%, No condensation allowed							
		3.5 m/s², 2	3.5 m/s ² , 2 \sim 9Hz: 10 m/s ² , 9 \sim 120Hz:							
		-40~+70°C	2							
		IP20 for 4T	055 and belo	w, IP00 for 4T	110 and above	e				
Others		Forced air cooling								
Ouncro	Certification CE									

Inverter size







Inverter size diagram of A1-A6 specification

AS510 rectified feedback unit size specification

	Inverter model						Mounting			Fastening	
Specification	AS510						(mm) hole diameter			torque (Nm)	(kg)
A1	4T0030	200	512	530	330	290.5	9.0	4M8	4M8	9	29.5
A2	4T0055	200	587	610	330	312.5	9.0	4M8	4M8	9	38
A3	4T0110	320	768	800	430	351	13.0	4M10	4M10	11	81
A4	4T0185	374	844	880	500	353	13.0	4M10	4M10	11	106.5
A4	4T0220	374	844	880	500	353	13.0	4M10	4M10	11	112.5
45	4T0280	500	997	1030	630	372.5	14.0	4M12	4M12	18	168
A5	4T0355	500	997	1030	630	372.5	14.0	4M12	4M12	18	170
A6	4T0450	560	1309	1352	774	392	14.0	4M12	4M12	18	180

AS520 inverter drive unit

• Product introduction

AS520 product is an inverter drive unit developed for the common DC bus occasions. With the use of advanced vector control technology and torque control technology, the product has the same excellent control performance with high-end international inverter and, combined with the application characteristics in the hoisting machinery industry, further strengthens the product reliability, environmental adaptation and custom design and can better meet various drive application requirements.



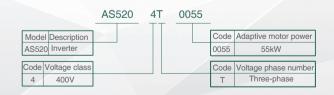
• Technical features

- Common DC bus supply
- Automatic voltage regulation to reduce voltage fluctuation
- A variety of V/F curves
- Non-stop at instantaneous stop of control bus
- Perfect, safe and reliable brake logic
- Fast, preeminent and high adaptive dynamic response
- Smooth and shockless speed tracking start
- Support Prol1bus-DP and MODBUS communication
- Perfect, safe and reliable motor inverter protection function

• Application industries

- Lifting occasions: quayside container bridge crane, container gantry crane, portal crane and beam crane
- Elevator occasions: high speed elevator

Product model



Model and technical parameters

Unit model (AS520 4T)	0030	0037	0045	0055	0075	0090	0110	0132	
Maximum power of adaptive motor (kW) (SHD)	22	30	37	45	55	75	90	110	
Maximum power of adaptive motor (kW) (HD)	30	37	45	55	75	90	110	132	
	52	65	80	97	128	165	195	236	
	60	75	91	112	150	180	216	260	
			2-8	kHz (modifie	d in paramete	rs)			
	0160	0185	0200	0220	0250	0280	0315	0355	
Maximum power of adaptive motor (kW) (SHD)	132	160	185	200	220	250	280	315	
Maximum power of adaptive motor (kW) (HD)	160	185	200	220	250	280	315	355	
	270	330	360	390	430	470	525	585	
	300	370	390	426	480	520	600	650	
	2-5kHz (modified in parameters)								
Supply voltage (V)	DC power supply 460-750VDC								

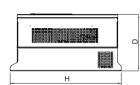
• Technical features

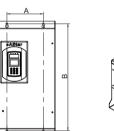
Power input	Input power	DC power supply 460-750VDC	DC power supply 460-750VDC							
		OVAC - input voltage/1.35, three-	phase supply							
		V/F control: 0.00/300.00Hz, vecto	or control: 0.00-120.00Hz							
Power output		leavy load: 150%, 60S; super-heavy load: 150% 60S 200% 2S								
		≥94%								
		0.01% (digital command- 10 - +45°C) ; 0.1% (analog command 25 10 °C)								
		V/F control	Open-loop vector control	Closed-loop control						
		2.50Hz 150%	0.5Hz 200%	0.00Hz 200%						
		1:50	1:200 1:1000							
Control characte		± 2% ± 0.2% ± 0.02%								
ristics		5% (Closed-loop control)								
		2-8kHz; automatically adjust the	carrier frequency according to load	l characteristics						
		0.01Hz (digital command), 0.06H	Hz/120Hz (analog command)							
		Automatic torque compensation a	and manual torque compensation							
		User-defined V/F curve, linear V/	F curve and 5 reduced torque char	racteristic curves						
		Automatically adjust the duty cycl	e of PWM signal according to the	bus voltage fluctuation						
	Non-stop at instantaneous stop	Achieve continuous operation through bus voltage control in case of instantaneous power failure								
		Braking current: 0.0-120.0% rated current								
		Torque/speed control switching through terminals, many torque given modes								
	Zero servo and position control function	Achieve zero speed position lock, accurate positioning and position control								
	Common DC bus	The whole series may achieve po	ower supply of many inverters by c	ommon DC bus						

	Usage occasion	Keep out of direct sunlight, dust, corrosive gases, combustible gases, oil mist, water vapor or dropping water
		-10~+40°C
Environmental		Less than 1000m
		5~95%, no condensation allowed
		3.5m/s ² , 2~9Hz; 10m/s ² , 9~120Hz;
		-40~+70°C
		IP00、IP20
Others		Forced air cooling

• Inverter size







Inverter size diagram of A4-A9 specification

Specifi	Inverter drive unit	А	В	Н	W	D	Mounting hole diameter		Installatio	า	Fastening	Mass
cation	model AS520						Φ (mm)				torque (Nm)	(kg)
A4	4T0030	200	512	530	330	288	9.0	4M8	4M8	4 Φ 8	9	29.5
7.4	4T0037	200	512	550	000	200	3.0	41010	41010	400	3	20.0
A5	4T0045	200	585	610	330	310	9.0	4M8	4M8	4 Φ 8	9	38
7.5	4T0055	200	505	010	000	510	3.0	41010	41010	400	3	50
A6	4T0075	320	718	750	430	350	13.0	4M12	4M12	4Φ12	29	79.5
A7	4T0090	320	768	800	430	350	13.0	4M12	4M12	4 Φ 12	29	81
A/	4T0110	320	700	800	430	330	13.0	411172	411112	4912	29	01
	4T0132											
	4T0160	374	844	880	500	352	13.0	4M12	4M12	4Φ12	29	106.5
A8	4T0185											
	4T0200	374	844	880	500	352	13.0	4M12	4M12	4Φ12	29	112.5
	4T0220	374	044	000	500	352	13.0	4IVI I Z	4IVI I Z	4012	29	112.5
	4T0250											141
	4T0280	500	0.07	1000		070						168
A9	4T0315	500	997	1030	630	370	14.0	4M12	4M12	4Φ12	29	169
	4T0355											170

Overview

STEP AS720 liquid-cooled inverter is an integrated product developed for HVAC industry based on STEP mature hardware platform. The inverter adopts the air conditioning refrigerant for cooling with high power density. The HVAC working environment, installation, volume, protection, heat dissipation, efficiency and harmonics requirements are fully considered in the design process to ensure safe and reliable operation of the product.



- Basic characteristics: small volume, high efficiency, high protection level and onboard design
- Voltage range: 380-460VAC

Application field

- Power range: 250kW—-1200kW
- · Control motor: AC asynchronous motor and permanent magnet synchronous motor
- Control mode: V/F control and open-loop vector control



Big power centrifugal machine



Small power centrifugal machine



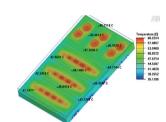
Water cooled screw machine

Air-cooled screw machine

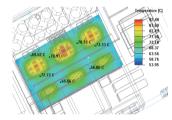
Functional characteristics

• Refrigerant cooling

The compressor refrigerant was used to dissipate the heat of the inverter cold plate and can achieve good heat dissipation effect and improve the module utilization rate. The inverter cold plate takes away 85% heat of the inverter, greatly reduce the inverter cabinet temperature rising and prolong the service life of the electrical components; the end user may not perform heat dissipation treatment for the air-conditioning control room, reducing the project cost and increasing the competitiveness of HVAC products.



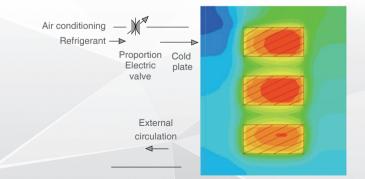
400kW liquid-cooled 490X305.5x18mm (length x width x height) Maximum temperature of radiator 60°C



400kW air-cooled 680x350x110mm (length x width x height) Maximum temperature of radiator s92°C

Anti-condensation function

Perform real-time monitoring of IGBT cold plate temperature and inverter cavity temperature. The inverter controls on-off of the electric proportional valve in the front of the cold plate through advanced algorithm to prevent condensation in the cold plate.



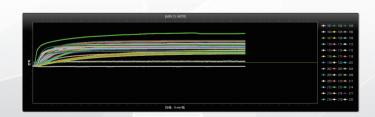
• Onboard installation mode

The elements (refrigerant copper tube connect with the compressor, cabinet height design no more than compressor height and support of a number of in and out line modes) for installation of the inverter products in the compressor bracket in onboard manner shall be fully considered in the structure design process for easy onboard installation and transportation. HVAC manufacturer has completed the inverter wiring and debugging before delivery to effectively reduce the debugging costs for end user.



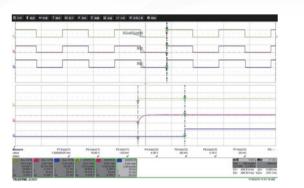
• High operating ambient temperature

The inverter can reach the maximum output capacity at the temperature up to 45° C and can still operate by derating capacity at the maximum ambient temperature of 55° C (type test and temperature rise test; conduct the temperature rise test for each heat device to ensure that it can work normally).



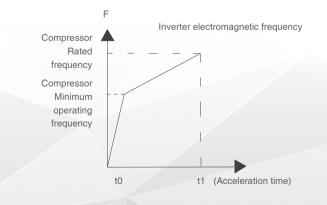
• Hardware shutdown function

The hardware shutdown function port can be controlled by the compressor high voltage protection switch or emergency stop switch. The hardware seals PWM wave and turns off the inverter output in emergency (guarantee effective shutdown of software out of control) to prevent the malfunction injury to the human and equipment.



• Segmented acceleration function

Design the segmented acceleration function and quickly pass through the minimum operating frequency of the compressor according to the compressor load characteristics to prevent the compressor system faults such as resonance and undervoltage and perform steady acceleration and deceleration in the normal operating frequency range.



High frequency output function

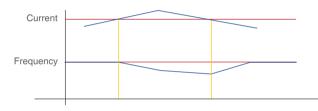
The output frequency range 0-600Hz which can meets the permanent magnet synchronous, direct drive and magnetic compressor drive requirements.

• Multiple protection grades for choice

With full consideration to the use conditions of the indoor and outdoor units of HVAC, the inverter cabinet protection grade is optional in IP20, IP22 and IP54.

• Current limit and frequency reduction function

Automatically reduce the frequency and limit the current if the running current over the set current to effectively protect the compressor.



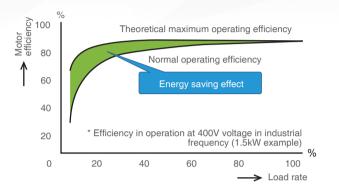
Low current harmonics

The long-term service life of the capacitor was achieved through optimal matching design of the filter capacitor and reactor. THDI of the standard inverter products is less than 35% and the low harmonic inverter scheme (passive filter configured in the front end) meets THDI<5%; the harmonic meets IEEEE519 requirements.

Normal Mode			Peak (ine ine Ine ine Instati	Scaling AVG	Line F Freq F			æt -::	YOKOGAWA
Voltage Current	Element 1. 600V 1V	Element2 600V 1V	Element3 600V 1V	.≍A(3V3A).	Element4 600V 1V	Element5.	Element6 800V	_===B(3V3A),	₩# ■ 1	CF:3 ΣA(3V3A)
Urms [V]	386.68	386.75	387.40	386.94	403.82	403.74	403.84	403.80	R	11 E 1V
Inns [A]	0.4841k	0.4814k	0.4811k	0.4822k	0.5991k	0.6024k	0.6030k	0.6015k	2	Sync Srct
P [M]	167.37k	154.68k	10.94k	322.05k	96.52k	216.99k	-119.85k	313.51k	3	U2 600V
	186.90k	185.93k	186.23k	322. <i>TI</i> k	217.71k	218.93k	219.12k	378.60k	Ř	12 E 1V
Q [var]	-83.16k	103.17k	-185.91k	21.50k	195.14k	29.11k	183.43k	212.25k		Sync Srct U1
	0.8955	0.8319	0.0587	0.9978	0.4434	0.9911	-0.5470	0.8281	H	10 600V
	333.58	33.70	273.37	3.82	63.68	7.64	123.16	34.10	5	13 E 1V
					49.892				6	Sync Srci UI
fl [Hz]	50.002					49.892	49.897		- R.	ΣB(3V3A)
										U4 600V
00000 (X)	1.390	1.426	1.265		3.195	2.914	2.814		8	14 E 1V
Ithd [X]	3.314	3.350	3.406		4.097	4.102	3.818		ి	Sync Src=
Pthd [X]	0.002	0.012	0.143		0.085	0.002	0.020		9	US 600V
Uthf [X]	1.362	1.421	1.305		3.467	3.129	3.148		R	15 E 1V
Ithf [X]	1.765	1.766	1.774		1.468	1.345	1.505		10	Sync Src=
Utif[]	0 F	0 F	0 F		0 F	0 F	0 F		- 11	UG 600V
	0.436	0.447	0.381		1.005	0.930	0.849		- 🔛	16 E 1V
hvf [2]] hef [2]]	1,199	1.245	1.225		1.695	1.715	1.589		12	Sync Src:
ner [X]	1,199	1.245	1.225		1.695	1.715	1.089			

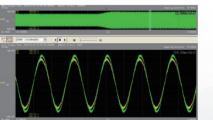
• Efficient and energy-saving operation mode

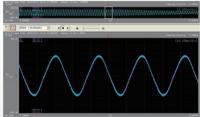
The high-efficiency drive & energy-saving operation mode and new PWM dead zone compensation technology can effectively reduce the motor loss and maximize the power saving rate.



• Current-sharing control technology

Strict hardware matching is not required among the units through current-sharing control and it is only required to increase algorithm in control to achieve good current-sharing effect among the units.





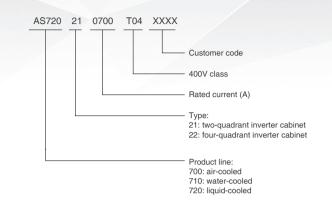
Before current-sharing control

After current-sharing control

Technical parameters

	Input voltage	380-460V (-15% ~ +10%), three-phase supply							
Power input	Input frequency	45-65Hz							
r ower input	Allowable voltage fluctuation	Voltage unbalance <3%							
	THDI	<35% (full load, standard inverter), <5% (full load, low harmonic inverter)							
	Voltage	0VAC - input voltage							
Power output	Output frequency	V/F control: 0.00-600.00Hz (depending on the power)							
	Overload level	120%, 1 min							
	Opto-isolator input	7-channels, 24V active high and low settable and input functions definable							
	Open collector output	2-channels, output functions definable							
Digital input and output	Relay output	2-channels, normally open contact, contact capacity: inductive, 1.5A/250VAC, output function definable 2-channels, normally open and closed double contact, contact capacity: resistive, 4.5A/250VAC or 4.5A/30VDC; Inductive: 0.4A/250VAC or 0.4A/30VDC; output functions definable							
Analog input and output	Analog input	2-channels, precision 0.1%; Voltage: -10V ~ + 10VDC or current: 0-20mA optional signal							
and output	Analog output	2-channels, precision 0.1%; Voltage: -10V ~ + 10VDC or current: 0-20mA optional signal							
Communication	Communication mode	Profibus_DP、Modbus							
mode and command channel	Running command channel	Operation panel given, control terminal given and communication given							
	Frequency given channel	Operation panel given, digital/analog given, communication given and function given							
		Rotor locked							
Motor protection		Motor overload							
		Motor over-temperature (PTC)							
		Speed limit							
		Output current limiting							
		inverter overload							
		I ² t protection							
		Input power undervoltage/overvoltage							
		DC bus undervoltage/overvoltage							
Inverter protection		IGBT overheating							
		Radiator overheating							
		Power source fault							
		Analog input signal loss (speed reference value loss)							
		Communication anormal							
		Self-setting fault The whole series may be subject to onboard installation and the installation							
	Usage occasion Operating ambient	environment shall reach the heat dissipation potential required by the inverter							
	temperature Temperature	-10°C[no frosting] ~ +45°C When the temperature is 1°C higher than the operating ambient temperature stipulated							
	derating use	for the product, the rated output current is reduced by 2%/1°C (up to 55°C)							
	Storage temperature	$-40^{\circ}\text{C} \sim +70^{\circ}\text{C}$							
conditions	Transport temperature	-40℃ ~ +70℃							
	Relative humidity	5~95%RH, no condensation, corrosion or dropping water							
	Altitude	1000m							
	Height derating use	>1000M; when the height rises by 100m, the rated output current is reduced by 1% (up to 3000m)							
	Vibration -proof characteristics	3.5m/s², 2-9Hz; 10m/s², 9-120Hz							
	-	in the second seco							
	Protection grade	IP22/IP54							

Technical parameters



• Inverter cabinet specification

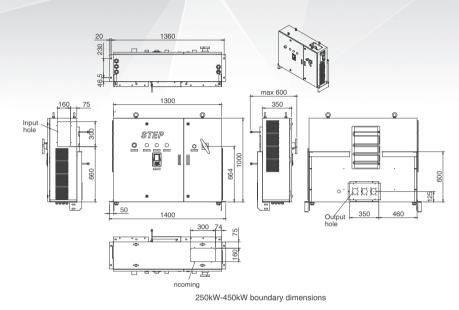
	T04:380-460V stable operation at 45°C							
No.	Inverter cabinet name	Rated power	Rated current	Cabinet size	W x H x D (mm)	Incoming and outgoing		
INU.		(kW)	(A)	IP21 / IP22	IP54	line mode		
1	AS720 21 0468 T04	250	468					
2	AS720 21 0520 T04	280	520					
3	AS720 21 0600 T04	315	600	1300×1000×350	1300×1000×350	Input line: bottom back Output: bottom		
4	AS720 21 0650 T04	355	650		1300×1000×350			
5	AS720 21 0740 T04	400	760					
6	AS720 21 0850 T04	450	850					
7	AS720 21 0960 T04	500	960					
8	AS720 21 1176 T04	630	1176					
9	AS720 21 1372 T04	710	1372	1800×1500×670	1800×1700×670	land the stars laft and		
10	AS720 21 1519 T04	800	1519			Input line: top left and side left		
11	AS720 21 1746 T04	900	1746			Output line: right		
12	AS720 21 1886 T04	1000	1886	3000×1500×670	3000×1700×670			
13	AS720 21 2037 T04	1200	2037					

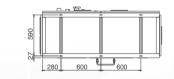
• Passive filter cabinet configuration

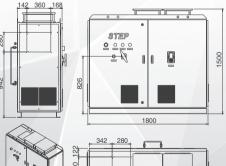
	Inverter cabinet name	Filter model	Filter quantity	Filter cabinet size (mm)	
1	AS720 21 0468 T04	FN3410-470-99-O	1		
2	AS720 21 0520 T04	FN3410-470-99-O	1		
3	AS720 21 0580 T04	FN3410-580-99-O	1	1500×1000×500	
4	AS720 21 0650 T04	FN3410-580-99-O	1		
5	AS720 21 0740 T04	FN3410-650-99-O	1		
6	AS720 21 0820 T04	FN3410-380-99-O	2		
7	AS720 21 0880 T04	FN3410-470-99-O	2	2000×1300×500	
8	AS720 21 1176 T04	FN3410-580-99-O	2	2000×1300×500	
9	AS720 21 1372 T04	FN3410-650-99-O	2		

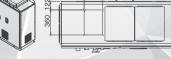
Dedicated Purpose Inverter

Boundary dimensions









500kW-710kW boundary dimensions

Cabinet layout

250kW-450kW inverter layout







(1) Input copper bar

Upper input and side input line two modes.

② Main power switch (circuit breaker)

Standard configuration of the inverter cabinet for easy installation and maintenance

③ Input AC reactor

External AC reactor effectively reduces the harmonic interference of the power supply, meets the international standard 61000 and effectively improves the grid adaptability. In case of network voltage change, the inverter can automatically keep constant output voltage. In case of sudden power loss of the grind, the inverter is kept on without shutdown.

(4) Control panel

The local control panel may be pulled or plugged in operation and the setup parameters can be copied from one inverter to another through the control panel; the given command and user can set password.

(5) Electrolytic capacitor

Select 105°C electrolytic capacitor to guarantee the product life and select the product with the withstand voltage 450V to guarantee reliable product operation under the grid voltage fluctuation.

(6) Output copper bar

Back output and lower output line two modes.

⑦ Transformer

Provide power for control system. The system control power supply is isolated from the network source to ensure stable system control.

8 Customer wiring terminal

The inverter connecting terminal is led to the customer's port for easy wiring.

④ Control line input and output holes

Select the product with IP54 protection grade to guarantee the inverter protection grade IP54.

10 Indicator light and emergency stop button

Indicator lights include power light, running indicator light and fault indicator light.

Dedicated Purpose Inverter

500kW-800kW inverter layout





(1) Input copper bar

Upper input and side input line two modes.

2 Main power switch (circuit breaker)

Standard configuration of the inverter cabinet for easy installation and maintenance

③ Input AC reactor

External AC reactor effectively reduces the harmonic interference of the power supply, meets the international standard 61000 and effectively improves the grid adaptability. In case of power voltage change, the inverter can automatically keep constant output voltage. In case of sudden power loss of the grind, the inverter is kept on without shutdown.

(4) Control box

Send PWM wave to the inverter unit through optical fiber.

5 Transformer

Provide power for control system. The system control power supply is isolated from the network power source to ensure stable system control.

6 Rectifier unit

Adopt the rectifier and inverter unit split design for easy installation and maintenance.

⑦ Inverter unit

Invert DC to the three-phase AC with controllable frequency

(8) DC fuse

Protect the effectively fusing of rectifier and inverter units

Output copper bar Support a number of output line modes.

Light Commercial VRF

Overview

AS570 dicated inverter for light commercial VRF drives the DC inverter compressor by space vector pulse width modulation (SVPWM). The inverter is suitable for VRF with its modularity. The whole set of product consists of drive board, capacitor boardplate, EMC filter board and DC reactor.

- · Basic features: space saving, flexible, high cost effectivenes and excellent heat dissipation
- Voltage class: 400V
- Power range: 11kW-30kW
- Control mode: sensorless SVPWM sine wave control









Dedicated Purpose Inverter

Drive board

Capacitor board

EMC filter board

DC reactor

Application field



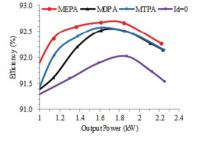
03/04

Applicable compressor

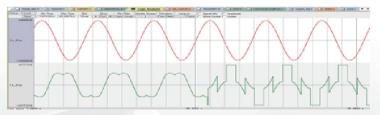
No.	Compressor model	Category	Brand
1	C-SDP330H02B	Three-phase	Panasonic
2	C-SDP205H01B	Three-phase	Panasonic
3	JPW066AC-4X9	Three-phase	Copeland
4	JPW053AC-4X9	Three-phase	Copeland
5	LNB65FTEMC	Three-phase	Mitsubishi
6	LNB53FTAMC	Three-phase	Mitsubishi
7	E655DHD-65D2G	Three-phase	Hitachi

Functional characteristics

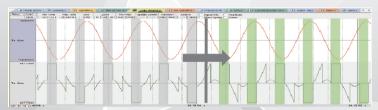
Efficient and energy-saving operation mode



2) New PWM modulation mode - control with minimum switching loss to reduce the inverter switching loss.



SVPWM \rightarrow DPWM, reduced by 1/3 on-off action



DPWM \rightarrow MSLPWM, the on-off action is not conducted in case of high current

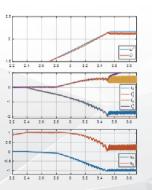
3) New motor control method - using sensorless vector control algorithm for the synchronous reluctance motor to improve the motor efficiency. The efficiency is tested as follows:

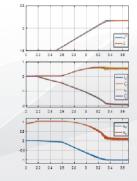
IE4 (>93.8	%)	IE3 (>92.	6%)	IE2 (>91	.2%)	IE1 (>8	39.3%)
		Moto	or Efficience	cy (Motoring	g)		
Load Freq(Hz)	20%	40%	50%	60%	80%	100%	120%
0.5	36.77%	38.80%	34.36%	33.46%	30.14%	26.21%	24.71%
5	83.56%	83.57%	82.83%	80.91%	79.70%	76.92%	73.90%
10	89.17%	89.32%	90.00%	88.44%	86.88%	85.37%	83.52%
15	90.39%	91.30%	92.37%	92.31%	90.67%	89.48%	88.57%
20	92.27%	93.75%	94.08%	92.15%	92.45%	91.78%	89.25%
25	92.02%	92.85%	94.44%	92.97%	92.66%	91.87%	89.51%

	Motor Efficiency (Motoring)							
Load Freq(Hz)	20%	40%	60%	80%	100%	120%		
0.5	-52.33%	-64.90%	-87.04%	-118.22%	-151.39%	-189.82%		
5	80.42%	81.60%	79.86%	76.40%	73.97%	69.39%		
10	86.58%	89.42%	89.50%	88.64%	86.91%	84.93%		
15	90.01%	92.92%	92.73%	92.31%	91.50%	90.47%		
20	92.32%	94.72%	94.14%	94.58%	94.07%	92.95%		
25	89.61%	93.70%	94.27%	94.51%	94.11%	93.48%		

• Ultra high speed operation mode is supported

The new flux weakening control strategy is used to drive the compressor to reach a higher speed. The current in the flux weakened area has no shock and the dynamic response is fast. Operation conditions of the motor under 2.17 times frequency and 0.83 times load.





Traditional flux weakening control mode

New flux weakening control mode

High reliability design

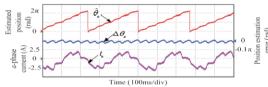
1) Automatic frequency reduction function - with the functions such as frequency reduction with limited current, frequency reduction with limited power and frequency reduction for overheating, the product can achieve automatic frequency reduction to guarantee reliable and stable operation of the compressor.

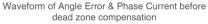
2) Super high temperature test - conduct temperature rise test at 42°C environment temperature to verify the hardware reliability.

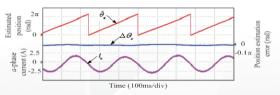
3) Fault protection - perfect fault protection system to minimize the inverter and compressor damage.

Ultralow noise operation design

Automatically identify the dead zone size and make compensation control by advanced software algorithm and reduce sixth harmonic components to reduce the noise.

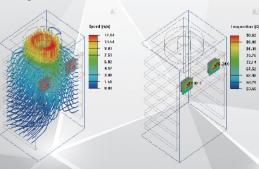






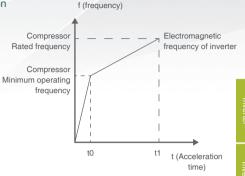
Waveform of Angle Error & Phase Current before dead zone compensation

Reliable thermal design



Compressor segmented acceleration function

Segmented acceleration function is designed according to the compressor load characteristics to quickly pass through the minimum operating frequency of the compressor and prevent the compressor system faults such as resonance and undervoltage, and perform steady acceleration and deceleration in the normal operating frequency range.



Technical parameters

	•	
	Input voltage	Three-phase 400V: 320-460V (±10%)
Power input	Input frequency	45-65HZ
	Allowable voltage fluctuation	Voltage imbalance <3%
	Voltage range	0VAC~ input voltage
	Output frequency	Vector control: 0.00~460.00Hz
Power output	Carrier frequency	4-8k adjustable, default 4k
	Efficiency (full load)	≥ 0.97
	Control mode	The sensorless SVPWM sine wave control effectively reduces the higher harmonic components, motor vibration, torque ripple and noise
Control	Control strategy	Speed loop + current loop double closed-loop motor control model; the speed loop (external loop) ensures stable output frequency and the current loop (internal loop) ensures torque accuracy
characteristics	Enabling torque	Enable zero-speed rated torque
	Enable differential pressure	10P410A system passes 20bar differential pressure enabling
	Manual operator connection	The manual operator connection port is reserved and meets the usage functions of LCD manual operator
	The drive board has nixie tube	4-digit red seven-segment nixie tube displays the running status and fault information
	Communication interface	RS485interface as standard; the protocol is changed according to the user requirements
	Fan control interface	N/A; the fan and power supply are provided externally for heat dissipation
Characteristic functions	I/O port	The reserved IO port can extend various IO boards; the expansion card is attached with instructions
	Process PID	Used for closed-loop control
	Module frequency reduction for overheating	When the radiator temperature is higher than the set temperature threshold, the inverter frequency is reduced automatically
	Frequency limit for input undervoltage	The output frequency may be limited automatically according to the bus voltage in case of low input
	Frequency reduction for overcurrent	The frequency may be reduced automatically when the set current is reached according to the compressor characteristics
	Flux weakening control	The limited voltage input improves the compressor operating frequency range
	Compressor overload	
	Compressor overcurrent	
Protection	Inverter overload	
functions	Inverter overcurrent	
	Radiator overheated	

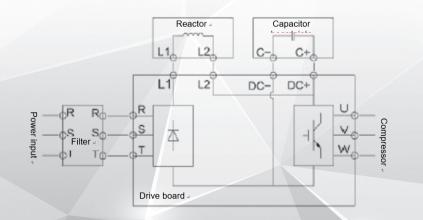
Dedicated Purpose Inverter

	Output phase-missing			
Protection	Input phase-missing			
functions	Input undervoltage/overvolta	ge		
	Communication protection			
	Usage occasion	VRF electric control cabinet application installation		
	Ambient temperature	-25 ~+70°C		
Environmental	Temperature derating use	Derating use at high temperature due to the impact of the ambient temperature and heat dissipat		
conditions	Storage temperature	-40 ~+85°C		
	Environment humidity	$5{\sim}95\%,$ no condensation allowed		
	Vibration (transportation)	2≤f<9Hz, 3.5mm; 9≤f<200Hz, 10m/s²; 200≤f<500Hz, 15m/s²		
	Vibration (installation)	2≤f<9Hz, 0.3mm; 9≤f<200Hz, 1m/s²		
	Protection grade	IP00		
Other	Installation mode	The drive board and radiator are embedded; other circuit boards are tiled in the cabinet		
	Cooling mode	The capacitor board, filter board and reactor are self-cooled in the cabinet; the drive board radiator is embedded in the air conditioning heat exchanger for heat dissipation		
	Certification	Inverter standard for civil use, supporting certain certification requested by the customer		

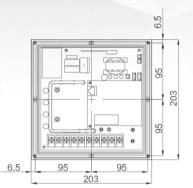
Product specification

Product specification	Rated power (kW)	Rated current (A)
AS570 4T 0011	11	17
AS570 4T 0015	15	27
AS570 4T18P5	18.5	37.5
AS570 4T 0022	22	44
AS570 4T 0030	30	61

Wiring example



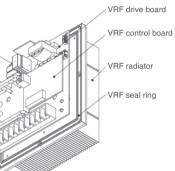
Dimensions

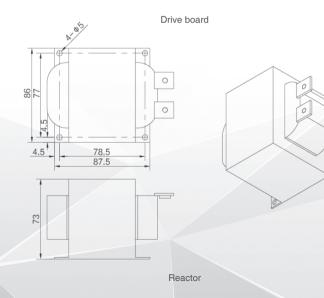


203 200

170.5

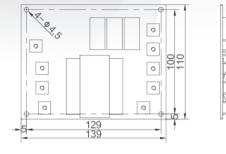


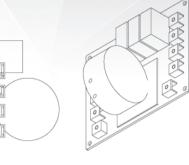




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3.5





Filter board

New Energy

Mobile air conditioning and refrigeration solution

• New energy bus air conditioning

New energy adopts battery power supply to replace the traditional engine, so a new solution is required for the air conditioning system.



STER



Low Voltag Inverter

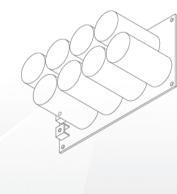
AS560 inverter

Vehicle DC

Product solution







Capacitor board

115

Refrigerator car

The electrification trend of the refrigerator car brings the electrification of the refrigeration unit

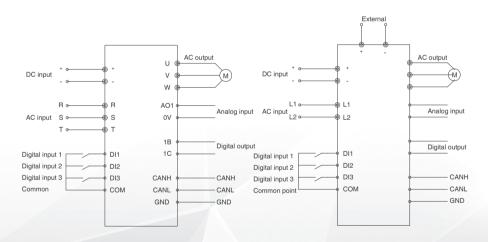




Cold chain transport vehicle

AS610 inverter

External capacitor



- Specification A: support DC and AC input, voltage range 250- 800 VDC after converted to DC, rated output current 8.5A
- Specification B: support DC and AC input, voltage range 200- 450 VDC after converted to DC, rated output current 8.5A
- With rectification function, can supply power for DC/DC in standby battery application.
- · With extremely small volume, suitable for cars

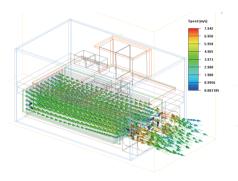
Vehicle air conditioning inverter characteristics

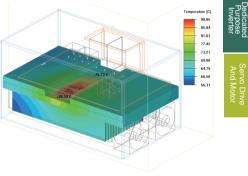
High reliability design

Automatic frequency reduction function

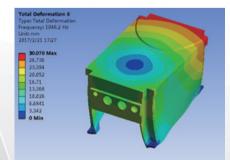
With the functions such as frequency reduction with limited current, frequency reduction with limited power and frequency reduction for overheating, the product can achieve automatic frequency reduction to guarantee reliable and stable operation of the compressor.

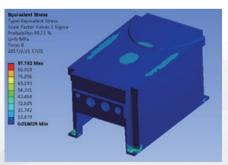
- Super high temperature test Conduct the temperature rise test at 55 C environment temperature to verify the hardware reliability.
- Fault protection Perfect fault protection system to minimize the damage of inverter and compressor.
- Reliable thermal design





• High anti-vibration performance



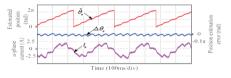


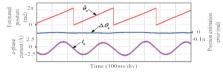
• High protection level

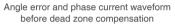
The product is designed and developed as IP67 high protection level to meet various working environment requirements in allweather

Ultralow noise operation

Automatically identify the dead zone size and make compensation control by advanced software algorithm and reduce sixth harmonic components to reduce the noise.



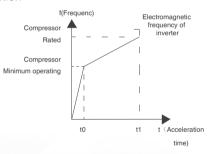




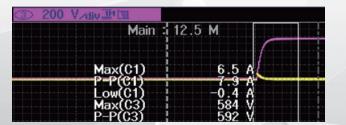
Angle error and phase current waveform after dead zone compensation

Compressor segmented acceleration function

Design the segmented acceleration function and quickly pass through the minimum operating frequency of the compressor according to the compressor load characteristics to prevent the compressor system faults such as resonance and undervoltage and perform steady acceleration and deceleration in the normal operating frequency range.

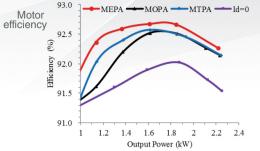


- Anti-reverse connection circuit design with DC input
- Advanced control logic to suppress current shock and prevent fuse from burning

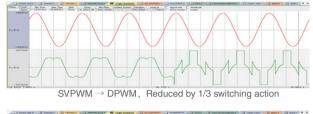


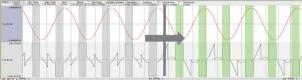
• Efficient and energy-saving operation mode

 Current control strategy Adopt advanced current control strategy for the permanent magnet synchronous motor to obtain the highest efficiency



New PWM modulation mode
 Adopt the least switching loss control to reduce the inverter switching loss.

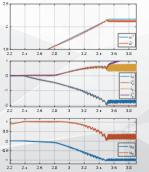


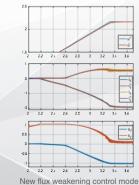


 $\text{DPWM} \rightarrow \text{MSLPWM}\,,~\text{The on-off}$ action is not conducted when it comes to the large current.

• Flux weakening control strategy

The new flux weakening control strategy is used to drive the compressor to reach the higher speed at low voltage input. The current in the flux weakened area has no shock and the dynamic response is fast. The operation conditions of the motor are under 2.17 times frequency and 0.83 times load , as shown in the figure





Traditional flux weakening control mode

0

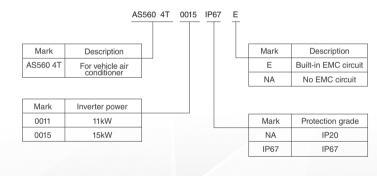
Dedicated Purpose Inverter

AS560 inverter

AS560 inverter, as a product customized for the on-board air conditioning application, may match AC inverter compressor and DC inverter compressor. The inverter is designed on basis of deep understanding of the industry characteristics to reduce some unnecessary functions, improve the product compactness, reduce the volume and greatly strengthen the product reliability, life and environmental adaptability. The series products may be optionally equipped with the built-in EMC filter and IP67 housing according to different customer requirements.



Model description



Product specifications

No.	Model AS560-4T	Ratedpower(kW)	Rated current(A)	Peak current(A)
1	0011	11	25	37.5
2	0015	15	32	48

Product technical specifications

Power input	Input voltage range	300-800V			
- ower input	Positive and negative reverse connection protection	In case of positive and negative reverse c not work but will not be damaged	In case of positive and negative reverse connection, the inverter does not work but will not be damaged		
	Output voltage	Three-phase AC output, highest 460V			
Power output	Output frequency	0-300Hz			
	Rated efficiency	>97.5%			
	Control mode	High-performance V/F	Open-loop vector		
Control	Starting torque	0.5Hz, 150%	0.25Hz, 150%		
	Steady speed precision	±0.5%	±0.2%		
	Automatic voltage regulation	Automatically adjust PWM duty cycle whe keep the output voltage constant	n input voltage fluctuation to		
	Digital input	6-channel, 24V high and low level are set definable	able and input functions are		
	Open collector output	1-channel, output functions are definable			
IO port	Relay output	1-channel, with normally open and normally closed function, output functions are definable			
	Analog input	1-channel, support 0- 10V or 4- 20mA			
	Communication	Optional CAN or Modbus function IO board			
Motor protection	Compressor locked-rotor				
	Compressor overload				
	Output current limit				
	inverter overload				
inverter protection	I ² tprotection				
	Input undervoltage/overvoltage				
	Heatsink overheat				
	Usage occasion	New energy bus air conditioner			
	Installation mode	Horizontal installation			
	Operating temperature	-20°C $\sim\!75^\circ\!\mathrm{C}$, $\leq\!50^\circ\!\mathrm{C}$ without derating			
Environment requirements	Storage temperature	-30℃~75℃			
	Vibration standard	Refer to 3.12 of QC/T 413- 2002 product	vibration resistance requirements		
	Humidity	5 \sim 95%, no condensation allowed			
	Altitude	3000m, derating use above 1000m and rat 1% for every rise of 100m	ted output current reduced by		
	Cooling mode	Forced air cooling			
Others	Protection grade	IP67, IP20			
	Certification	CE			

Dedicated Purpose Inverter

• Product size





AS560 4T0011(15)



STEP

160

4- φ 6×8 Waist round hole

165



AS610 inverter, as the air conditioning low-power inverter specially developed for low-power compressors and fans, has the greatest advantage of small volume and high performance and can be used to drive the asynchronous motor and synchronous motor.



High Voltage

• Product specifications

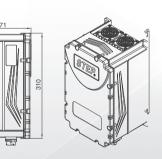
duct specification	IS		
	Stable operation		
	Power capacity (kVA)	Rated current (A)	Adaptive motor (kW)
AS610-4T0P75	1.5	2.3	0.75
AS610-4T01P5	3.0	4.1	1.5
AS610-4T02P2	4.0	5.5	2.2
AS610-4T03P7	7.2	8.5	3.7



4.00

AS560 4T0011(15) IP67 E





	Input voltage range	AC: 380-460V;-15% - +10%, three-phase supp	ply			
Input power	Input frequency	50/60Hz				
	Current harmonics	Current harmonics <40%(full load) (for reference)				
	Voltage unbalance	(The voltage unbalance is less than 2% in 95% time period and less than 4% in 5% time period) and the overall voltage unbalance is less than 3%				
	Output voltage	OVAC-input voltage				
	Starting torque	V/F control 2.5Hz/150%	Open-loop control 0.5Hz/200%			
	Speed adjustable range	1:50	1:200			
Basic characteristics	Steady speed precision	± 2%	± 0.2%			
	Overload capacity	150% rated current for 1min, 300S cycle. (Test mode) stable operation at 40 $^\circ\!\mathrm{C}$				
	Rated efficiency	≥0.93				
	Carrier frequency	2~10kHz				
	Automatic voltage regulation	Automatically adjust the duty cycle of PWM signal according to the busbar voltage fluctuation, so as to reduce the impact of the network voltage fluctuation on the output voltage fluctuation				

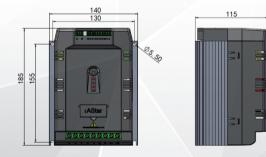
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General specifications

	Locked rotor							
Motor	Motor overload							
protection	Speed limit							
	Torque limit							
	Output current limit							
	inverter overload							
inverter	IGBT overheating							
protection	Input power undervoltage/ove	rvoltage						
	DC busbar undervoltage/over	voltage						
	Detailed attachment list							
Options	LCD handheld teach pendant	, Bluetooth and wireless module						
	Usage occasion	Keep out of direct sunlight, dust, corrosive gases, combustible gases, oil mist, water vapor, dropping water or salt						
	Installation mode	Wall mounting						
Working	Installation site	Roll backplate, moving with trolley						
environment	Cooling mode	Natural cooling and air cooling						
	Environment temperature	-10-+50'C (derating use at the environment temperature 40- 50'C)						
	Temperature derating use	>40'C; when the temperature rises by 1'C, the rated output current is reduced by 2%, up to 50'C						
	Protection grade	IP20						
Environment	Vibration standard	9.8m/s² at 5~150Hz						
requirements	Storage temperature	- 20°C~+ 70°C						
	Humidity	Less than 95%RH, without water condensation						
	Altitude	<1000m						
	Height derating use	<1000m; when the height rises by 100m, the rated output current is reduced by 1% (up to 3000m)						

• Product size

AS610 inverter, as the air conditioning low-power inverter specially developed for low-power compressors and fans, has the greatest advantage of small volume and high performance and can be used to drive the asynchronous motor and synchronous motor.



No.	Power (kW)	Dimensions H x W x D(mm)	Mounting hole size (mm)	Installation mode
1	0.75	150×140×120	5	
2	1.5	150×140×120	5	
3	2.2	105.110.115	5	Wall mounting
4	3.7	185×140×115	5	

Vehicle DC power supply

This product is the isolated switching power supply designed and produced for the electric bus industry fan drive and adopts the advanced digital and analog hybrid control technology. The input and output are fully electrically isolated, safe and reliable. The product is characterized by wide input voltage range, high output power, convenient installation, high conversion efficiency, stable output voltage, complete protection functions, high reliability and long service life.



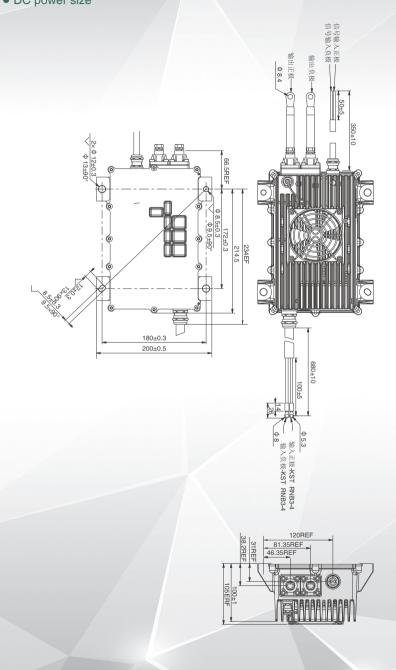
• Power supply specifications

Rated power (kW)	Rated output current (A)	Rated output voltage (VDC)		
3	110	27.5		
2	75	27.5		

Main technical parameters

	Input voltage	200-750V				
	Efficiency	≥97%				
	Maximum input voltage	11A				
	Static loss current	1mA				
Input protection	Input overvoltage	760 ±5VDC, the module output is off in car automatically at the recovery point	se of input overvoltage and recovers			
	Output overvoltage	190 ±5VDC, the module output is off in car recovers automatically at the recovery point				
Output	Rated output voltage	27.5V				
	Rated output current	3kW, 110A	2kW, 75A			
	Output overcurrent protection	Constant voltage and limited current, output current status exit	ut voltage recovery after limited			
Output protection	Output overvoltage protection	>31V DC ±1 V output off, recovered auton	natically when in normal conditions			
	Over-temperature protection	Over-temperature protection, recover automatically when the temperature falls to the safe temperature				
	Short-circuit protection	Shutdown protection, recover automatically until failure solution				
	Operating temperature	-40℃~55℃				
	Operating humidity	5%-90%, non-condensing				
Environment requirements	Storage place	Place with controlled temperature and hun	nidity			
requiremento	Storage temperature	-40℃~85℃				
	Storage humidity	10%~90%				
	Input-output	2500VDC, 60s, ≤10mA, without breakdow	n or flashover			
	Input-housing	2500VDC, 60s, ≤10mA without breakdow	n or flashover			
	Input-output	500VDC, \geq 20MΩ/min (standard pressure	and environment humidity)			
	Input - housing	500VDC, \geq 20MΩ/min (standard pressure and environment humidity)				
Protection grade		IP67 (except fan, IP65 including fan)				
		<55dB				

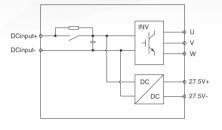
• DC power size



Two-in-one product

Two-in-one is integration and development of two platforms of AS560 inverter and DC power supply. It is characterized by high integration, compact volume and easy use

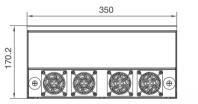


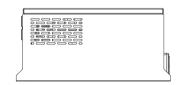


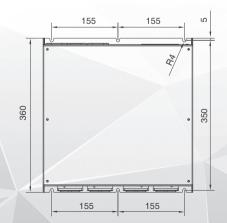
• Product technical specifications

	I0011/D0002	I0015/D0003
Rated power of inverter(kW)	11	15
Rated current of inverter(A)	25	32
peak current of inverter(A)	37.5	48
DC rated power(kW)	2	3
DC rated current(A)	75	110

Product size





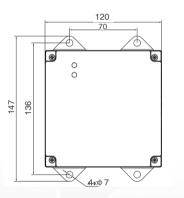


Vehicle air conditioner controller

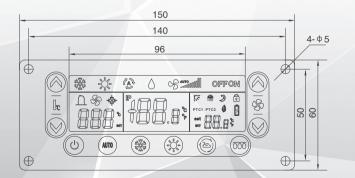
- The new energy vehicle air conditioner controllers characterized by reliable quality, complete functions and exquisite appearance. The system functions include refrigeration, heating, defrosting, internal and external wind circulation, wind speed (automatic/manual) regulation, failurewarning, voltage monitoring, corresponding indicator light and Nixie tube display interface.
- 8-Level wind speed, adjustable compressor speed, PTC auxiliary heating, air conditioning protection, forced defrosting and other protection functions.



Control box size



• Panel size



Servo Drive And Motor



High performance servo drive



Efficiency comes from reliability and focus drives the future. Simplified industrial design, modular design idea, standardized design criteria, and strong compatibility.

Faster response

Advanced control algorithm greatly improves system response. The current loop frequency response is at 2.5kHz and the speed loop frequency response is at 1.6kHz.

Higher precision

It supports many brands of encoders with a maximum precision up to 23bit, and the high resolution encoder meets the requirement of high precision positioning control and smooth operation. The E series is equipped with dual encoder interface to support full closed loop.

Smaller size

With a minimum thickness of only 42mm, the product is lighter and saves installation space.

Richer functionality

Real-time automatic gain control and adaptive filter greatly improve the use convenience, and the end jitter suppression, vibration suppression, inertia identification, instruction smooth, friction compensation, cogging torque compensation, self-tuning functions can greatly ease debugging together with various vibration damping filters as well as software analysis and monitoring functions.

Standard industrial Ethernet



Safer

It is consistent with international safety standards of STO/SBC/SS1/SS2, reliable and stable.

Complete product line

Servo driver power range: 50W ~ 7.5kW. Drivers fall into pulse type, analog voltage-type, and CANopen communication command type, MECHATROLINK-II communication command type, EtherCAT communication command type, and POWERLINK communication command type. Motor supports a variety of encoders, magnetic arrangers, rotary transformers, incremental dart/non-dart lines (2500 lines, 5000 lines), absolute value (17bit, 20bit, 23bit), rich models and motors of many specifications, easy to build the system the customer needs.



High-order pulse K5 series servo drive



Servo Drive And Motor

Technical indexes

① Power range: 50W ~ 3kW.

② Input voltage: single or three-phase 220VAC (-15~+10%), 50~60HZ control mode: position control.

③Encoder type: 2500-line incremental photoelectric encoder (dart/non-dart line), 17bit/20bit/23bit absolute value encoder.

(4) Communication mode: RS232, RS485

(5) I/O counts: IO is programmable and supports positive and negative logic settings and functional relocation; line 10 is for input and line 6 for output.

(6) Monitoring function: provide 16 monitoring states such as position, speed, current, voltage, input and output, etc.

Product advantages

① The advanced motor control algorithm is used to achieve a faster system response. The current loop frequency response is at 2.5khz, the speed loop frequency response is at 1.6khz, and the communication rate is 100Mbps.

② Adaptive filter, under the actual act conditions, infers resonance frequency according to the vibration in the motor speed component and automatically set the coefficient of the notching filter where the resonance components are removed, to reduce the vibration of the resonance point. ③ Real-time automatic gain adjustment is made to deduct the load characteristics of the machine and the result is then used to set the basic gain value and the friction compensation value of the corresponding rigidity.

④ End jitter suppression function is applied to calculate and compensate vibration frequency, to suppress low-frequency jitter.

(5) It supports PC software of the upper machine for parameter settings (upload, download, reset, import and export), waveform monitor (it supports automatic save of waves during the period before and after failure, if any, and can support historical waveform data call, playback, management analysis, linear transformation, FFT analysis);and it supports servo position, speed and torque control, start and stop, positive - reverse control, status monitoring, fault diagnosis and other operations.

(6) With security functions corresponding to international standards of STO/SS1/SS2/SBC, safe and reliable.

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High order bus E series servo drive



Efficiency comes from reliability and focus drives the future. Simplified industrial design, modular design idea, standardized design criteria, and strong compatibility.

Technical indexes

① Power range: 50W ~ 3kW.

Input voltage: single or three-phase
 220VAC (-15~+10%), 50~60HZ

③ Control modes: position control, speed control, torque control and bus control.

 ④ Encoder type: 2500-line incremental photoelectric encoder (dart/non-dart line), 17bit/20bit/23bit absolute value encoder.

5 Communication mode: EtherCAT.

 (6) I/O counts: IO is programmable and supports positive and negative logic settings and functional relocation; line 5 input supports 16 functional configurations, and line 3 output supports 12 functional configurations.

⑦ Monitoring function: provide 16 monitoring states such as position, speed, current, voltage, input and output, etc.

Product advantages

① The current loop frequency response is at 2.5kHz and the speed loop frequency response is at 1.6kHz. The communication rate is 100Mbps.

② End jitter suppression, friction compensation function and cogging torque compensation functions are arranged with the self tuning function and matched with various vibration damping filters. ③ It supports PC software of the upper machine for parameter settings (upload, download, reset, import and export), waveform monitor (it supports automatic save of waves during the period before and after failure, if any, and can support historical waveform data call, playback, management analysis, linear transformation, FFT analysis);and it supports servo position, speed and torque control, start and stop, positive - reverse control, status monitoring, fault diagnosis and other operations.

④ It is equipped with a hand-held operation panel for setting parameters and monitoring the state of servo and motor, allowing the system debugging to be more convenient.

(5) It supports the standard industrial Ethernet and achieves synchronous control of many servo drivers.



(6) With security functions corresponding to international standards of STO/SS1/SS2/SBC, safe and reliable.

⑦ A variety of instruction input methods greatly improve the use convenience, and can achieve position control, speed control and torque control by external terminals, hand-held operators, PC software of the upper machine and bus.

Universal bus iK3 series servo drive



Technical indexes

① Power range: 50W ~ 5kW.

Input voltage: single or three-phase
 220VAC (-15~10%), 50~60HZ

③ Control modes: position control, speed control, torque control and bus control.

 ④ Encoder type: 2500-line incremental photoelectric encoder (dart/non-dart line), 17bit/20bit/23bit absolute value encoder.

(5) Communication mode: EtherCAT, POWERLINK, CANopen.

 (6) I/O counts: IO is programmable and supports positive and negative logic settings and functional relocation; line 5 input supports 16 functional configurations, and line 3 output supports 12 functional configurations.

⑦ Monitoring function: provide 16 monitoring states such as position, speed, current, voltage, input and output, etc.



Product advantages

① The current loop frequency response is at 2.5kHz and the speed loop frequency response is at 1.6kHz; the communication rate is 100Mbps.

② It is equipped with a variety of subtraction filters to improve the control stability, support

speed curve planning, allow settings of acceleration and deceleration as well as acceleration and deceleration corner.

③ End jitter suppression, friction compensation function and cogging torque compensation functions.

4 It supports the weak magnetic control, and in the high speed operation under light load, can continue to raise the motor speed.

(5) It supports many auxiliary function parameter reset, self-learning, inching, fault history query and fault history clearance.

(6) It supports PC software of the upper machine for parameter settings (upload, download, reset, import and export), waveform monitor (it supports automatic save of waves during the period before and after failure, if any, and can support historical waveform data call, playback, management analysis, linear transformation, FFT analysis);and it supports servo position, speed and torque control, start and stop, positive - reverse control, status monitoring, fault diagnosis and other operations.

⑦ It supports communications with servo drivers with different addresses.

(8) With security functions corresponding to international standards of STO/SS1/SS2/SBC, safe and reliable.

(9) It can be optionally equipped with a hand-held operation panel for setting parameters and monitoring the state of servo and motor, allowing the system debugging to be more convenient. Servo Drive And Motor

Universal S series servo motor



1. The new electromagnetic design scheme can reduce the motor cogging torque, lower temperature rise and better performance; 2. The design of 5 pairs of motor poles is characterized by smooth start, low noise, high power density and high efficiency; 3. The optimization of magnetic steel and the new structural process design realize the small lightweight design;

4. The protection grade of IP65 greatly improves the environmental resistance; 5. The maximum speed of 5000RPM meets the need of high-speed application; 6.Equipped with encoders of various specifications, up to 23bit, it can achieve

high precision servo control.

Working voltage (VAC) Rated torque (Nm) Base (mm) Rated speed (rpm) Max Speed (rpm) Rated power (kW) 220 1000~3000 1500~5000 0.1~1.5 0.32~14.3 60 ~ 130 Environment temperature Environment humidity Installation mode Pole-pairs Protection grade Insulation grade Below 90% (non condensing 0~55°C F Flange plate 5 IP65

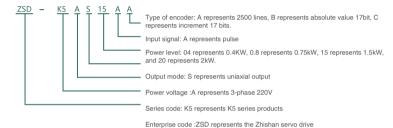
• Naming rules of general - purpose servo motor models:

	1: Flange size				X6: Rated voltage	X7: Input	
Code	Explanations:	Code	Explanations:	Code	Explanations:	Code	Explanations:
40	40mm side length square flange plate	S	Small inertia	10	1000r/min	D1	Tamagawa photoelectric increment 2500lines
60	60mm side length square flange plate	D	Medium inertia	15	1500r/min	D2	Tamagawa photoelectric dart line type 2500 lines
80	80mm side length square flange plate	н	Large inertia	20	2000r/min	D3	Tamagawa photoelectric increment 5000lines
90	90mm side length square flange plate	С	Super large inertia			D4	Tamagawa photoelectric multi-ring absolute value 17
100	100mm side length square flange plate					D6	Tamagawa photoelectric single-ring absolute value 17
110	110mm side length square flange plate					D10	Tamagawa multi-ring absolute value 23
130	130mm side length square flange plate			0.1	X5: Power	K1	Nikon single-ring absolute value 17
				Code	Explanations:	K2	Nikon multi-ring absolute value 17
				201	200W	K3	Nikon single-ring separated typ absolute value 24
				401	400W	K4	Nikon multi-ring separated typ absolute value 24
	2: Motor series	× Χι		751	750W		absolute value 24
Code	Explanations:	Code	Explanations:	102	1KW		
S	Zhishan S series	Α	220V	152	1.5KW	X	3: Special definitions
A	Zhishan A series	В	380V	202	2KW	Code	Explanations:
В	Zhishan B series	С	48V	302	ЗКW	Null	General motor
E	Zhishan E series					В	Electromagnetic contracting brake
						B2	permanent magnetic contracting brake

High-order pulse K5 series servo drive



K5 series naming way



		arameter							
	Series			High-order pulse	K5 series servo drive				
C	utput powe	r (kW)	0.4	0.75	1.5	2.2			
(Dutput curre	ent (A)	2.8	5.5	10	12			
	C	ontrol mode	IGBT PWM control sinu	usoidal current drive mode					
		ondormodo	220V: single or three-ph	ase full wave rectification					
	Enc	oder feedback	ABZ dart/ non dart line e	encoder					
Basic				oder, Tamagawa 17/23bit e					
specifications	l	Jse/storage emperature*1	0~45°C (Please derate than 80%)/40~70°C	when ambient temperatur	e above 45 °C, the avera	ige load rate no higher			
	Use l	Jse/storage humidity	90%RH below (non cond	densing).					
	condition	/ibration-resistance/im bact strength	4.9m/s2 / 19.6m/s2						
	7	Altitude	Below 1000m						
	Input		2-line input						
Pulse input		mput	Differential input: 4M ([Pulse/s]); optocoupler input: 500K ([Pulse/s]).						
r dibb input		Output	4-line output			And and a second second second			
			Differential output 3 lines, open-collector output 1 line encoder						
Analog signals	Analog speed Command input	Input voltage	0~10V	0~10V					
Analog signals	Analog torque Command input	e Input voltage	0~10V	0~10V					
	Figure	Signal distribution	Universal 10-line input						
Input/output	Input signal	can be changed	Selecting the function of universal input according to the parameters						
signal	Figure	Signal distribution	Universal 6-line output						
	Output signa	can be changed	Selecting the function of	universal output according	g to the parameters				
	Over travel (OT) prevention function		Stop immediately when	P-OT and N-OT act					
Built-in	Electronic gea	ar ratio	$0.1048576 \leqslant \text{B/A} \leqslant 419$	9430.4					
capabilities	Protection functions			e, voltage shortage, overlo peed, encoder anomaly, C					
	LED display fu	un et le u	lack of one phase, overspeed, encoder anomaly, CPU anomaly, parameter anomaly, etc 5-bit key, 6-bit LED display						

High order bus E series servo drive



E series naming way ZSD - E A S 08 E A

Type of encoder: A represents ABZ increment type, B represents absolute value Input signal: E represents EtherCAT, C represents CANopen, P represents POWERLINK.

Power level: 02 represents 0.2KW, 0.4 represents 0.4kW, 0.8 represents 0.75kW, 10 represents 1kW, and 15 represents 1.5kW. Output mode: S represents uniaxial output Power voltage : A represents 3-phase 220V

Series code: E represents the E series

Enterprise code :ZSD represents the Zhishan servo drive

	ecification p	arameter										
	Series			h o	rder bus E series se	rvo driv						
C	Output power	(kW)	0.2	0.4	0.75	1	1.5					
(Dutput currer	nt (A)	1.7	2.8	3.3	5	10					
	0	ontrol mode	IGBT PWM control	, sinusoidal current o	drive mode.							
		ontroi mode	220V: single or three	ee-phase full wave re	ectification.							
			17 bit incremental encoder									
Basic	Enc	oder feedback	ABZ fully closed loo	op / non dart line end	coder							
specifications	ecifications	Use/storage temperature*1	0~45°C (please us	se at a lower rate wh	en the ambient temp	perature is at or above	45 °C, and the					
	Use	Use/storage humidity	ty 90%RH below (non condensing).									
	condition	Vibration-resistance/ impact strength	4.9m/s2 / 19.6m/s2									
		Altitude Below 1000m										
		Communication protocol	EtherCAT protocol									
		Support services	CoE (PDO、SDO)									
		Synchronization mode	DC-distributed clock									
		Physical layer	100BASE-TX	00BASE-TX								
Basic EtherCA slave stati		Baud rate	100 Mbit/s (100Base-TX	()								
		Duplex mode	Full duplex									
		Topology structure	Ring and linear type									
		Transmission medium	A shielded Super 5 or b	etter network								
EtherCAT	properties	Transmission distance	It is less than 100M betw	ween the two nodes (good	d environment and excelle	ent cable).						
Slave station		Number of slave stations	The protocol supports up to 65535, but there are no more than 100 in use									
specifications		EtherCAT frame length	44~1498 bytes									
		Process data	The maximum size of a	single Ethernet frame is 1	1486 bytes							
		Synchronization jitter between two slave stations	< 1us									
		Refresh time	The input or output of 1000 switch oprations is about 30us									
		noncon uno	100 servo axes are abo	ut 100US								
		Communication error rate	10-10 Ethernet standard	st								
		FMMU unit	8 pcs									
	EtherCAT	Store synchronization management units	8 pcs									
	configuration	Process data RAM	8KB									
	unit	Clock distribution	64 bit									
		EEPROM capacity	32Kbit									
Analog signals	Analog speed Command input	Input voltage	-10V~ + 10V									
	Analog torque Command input	Input voltage	-10V~ + 10V									
			5-line DI			/						
Input/output	Figure Input signal	Signal distribution can be changed	DI function: servo enabl limit switch, negative lim	e, forward motion inhibit, it switch, zero return prov	reverse motion inhibit, for kimity switch, bus IO input	ward current limit, reverse t, probe 1, probe 2, fault res	current limit, positive et					
signal	Figure	Signal distribution	3-line DO									
	Output signal	can be changed	DO function: servo return zero completion, servo operation preparation completion, servo fault, position tracking over target location reach, STO enable sign, bus IO output, contracting brake output									
	Over travel (0	OT) prevention function	Stop immediately when	P-OT and N-OT act								
	Electi	ronic gear ratio	0.1048576 ≤ B/A ≤ 4194									
Built-in	Prote	ction functions	Over current, over volta encoder abnormality, Cl	ge, under voltage, overloa PU abnormality, paramete	ad, main circuit detection a er abnormality, others	abnormality, heat sink over	heating, overspeed,					
capabilities	LED o	display function	Main power supply CHA	BGE, 2-digit LED display								
	RS232	communication	State display, user para torque command signal	meter setting, monitor dis mapping, and other funct	play, alert tracking display	y, JOG operation and self-t	uning operation, spee					
		Others	Gain adjustment, alert lo									

Universal bus iK3 series servo drive



iK3 series naming way

ZSD - iK3 A S 15 E A Type of encoder: A represents ABZ increment type, B represents absolute

- Input signal: E represents EtherCAT, C represents CANopen, P represents POWERLINK.

Power level: 04 represents 0.4KW, 0.8 represents 0.75kW, 15 represents 1.5kW. Output mode: S represents uniaxial output

Power voltage: A represents 3-phase 220V, B represents 3-phase 380V - Series code: iK3 represents the iK3 series

-Enterprise code :ZSD represents the Zhishan servo drive

	Series				High order bus E	series servo driv							
AC 2	20V power le	evel (kW)	0.4	0.75	1.5	2.2	3	5					
(Dutput curren	t (A)	2.8	5.5	10	12	16	25					
AC 3	80V power le	evel (kW)	5	7.5			-	-					
	Output curre	ent	12	20			-	-					
	Co	ntrol mode			current drive mode.								
					wave rectification.								
Basic	Enco	der feedback	2500-line increi	mental standard	type								
specifications	LINGO		17 bit incremen										
		Use/storage temperature*1	0~45°C (pleas average load r	se use at a lowe ate shall not be	r rate when the amb higher than 80%.)/40	ient temperature 0~70°C	is at or above 4	5 °C, and the					
	Use	Use/storage humidity		(non condensin									
	condition	Vibration-resistance/ impact strength	4.9m/s2 / 19.6r	m/s2									
		Altitude	Below 1000m										
		Communication protocol	EtherCAT protocol										
		Support services	CoE (PDO、SDO)										
		Synchronization mode	DC-distributed close	ck									
		Physical layer	100BASE-TX										
		Baud rate	100 Mbit/s (100Ba	se-TX)									
	Desia	Duplex mode	Full duplex										
	Basic EtherCAT	Topology structure	Ring and linear typ	ie .									
	slave station EtherCAT properties ave station ecifications	Transmission medium	A shielded Super 5	shielded Super 5 or better network									
EtherCAT		Transmission distance	It is less than 100M	A between the two r	odes (good environment	and excellent cable).							
Slave station		Number of slave stations	The protocol supp	orts up to 65535, bu	t there are no more than	100 in use							
specifications		EtherCAT frame length	44~1498 bytes										
		Process data	The maximum size	of a single Etherne	et frame is 1486 bytes								
		Synchronization jitter between two slave stations	< 1us	< 1us									
			Befresh time	The input or output	t of 1000 switch opr	ations is about 30us							
		neiresnume	100 servo axes are	e about 100US									
		Communication error rate	10-10 Ethernet sta	ndards									
		FMMU unit	8 pcs										
	EtherCAT	Store synchronization management units	8 pcs	1.2.2.2.1.1.7									
	configuration	Process data RAM	8KB				and Alberton						
	unit	Clock distribution	64 bit										
		EEPROM capacity	32Kbit				Statistics and the						
Analog signals	Analog speed Command input	Input voltage	-10V~ + 10V										
analog signals	Analog torque Command input	Input voltage	-10V~ + 10V										
			5-line DI										
Input/output	Figure Input signal	Signal distribution can be changed			rd motion prohibition, reve tive limit switch, return ze								
signal			3-line DO	/									
	Figure Output signal	Signal distribution can be changed	DO function: servo location reach, ST	return zero comple O enable sign, bus l	tion, servo operation prep O output, contracting bra	paration completion, s ke output	ervo fault, position t	racking overlimit, target					
	Over travel (0	OT) prevention function	Stop immediately	when P-OT and N-O	DT act								
	Electr	ronic gear ratio	0.1048576 ≤ B/A :										
	Prote	ction functions	Over current, over	voltage, voltage sh	ortage, overload, exceptio	ons of main circuit, he	at sink overheat, lac	k of one phase,					
Built-in			Over current, overvoltage, voltage shortage, overload, exceptions of main circuit, heat sink overheat, lack of one phase, overspeed, encoder anomaly, CPU anomaly, parameter anomaly, etc.										
Built-in capabilities		display function	Main power CHAP	RGE, displayed by 5	bit LED	Main power CHARGE, displayed by 5 bit LED State display, user parameter setting, monitor display, alert tracking display, JOG operation and self-tuning operation,							
	LED o	display function	State display, use		monitor display, alert trad	king display, JOG op	peration and self-tuni	ing operation, speed,					

Universal bus iK2 series servo drive



iK2 series naming method

ZSD - iK2 A S 15 2 B Type of encoder: B represents absolute value 17bit Input signal: 2 represents M2 bus Power level: 04 represents 0.4kW, 08 represents 0.75kW, 15 represents 1.5kW

Output mode: S represents uniaxial output

Power voltage: A represents three-phase 220V, B represents three-phase 380V

Series code: ik2 represents ik2 series

Enterprise code :ZSD represents the Zhishan servo drive

Specifi	cation par	ameter									
	Seri	es									
Out	tput power	' (unit: kW)	0.4	0.75	1.5	2.2	3	5			
	Output current			5.5A	10A	12	16	25			
	Type of e	ncoder	17 bit absolute value encoder								
Reg	generation	resistance	Built-in or extern	al connection							
	C	Control mode	IGBT PWM cont	rol sinusoidal cu	rrent drive mode						
	Spe	eed control range	1:10000 (The low	er limit of the spe	ed control range is	stable operation v	without creep in ca	ase of rated load)			
	Fluctuatio	n Load fluctuation	0 to 100% load:	±0.01% max. (at	rated speed)						
Properties	ratio of	Voltage fluctuation	Rated voltage: ±	:10%:0% (at rate	d speed)						
	speed	Temperature fluctuation	25±25°C: ±0.1%	max. (at rated s	peed)						
	Torque con	trol accuracy (repeatability)	1%								
	Soft b	oot-time setting	0 ~ 10 seconds	(acceleration and	l deceleration can	be set separatel	ly)				
	BS-485	Communication protocol	Modbus								
Communication	on Communic	c 1; N communication	Up to N = 127 st	Jp to N = 127 stations							
	ation	Axis address setting	Set by paramete	er							
	Frequent output of	cy-dividing pulse encoder	A-phase, B-phase, and C-phase: linear drive output; number of divided pulses: can be set arbitrarily								
			7 channels								
Input/output signal	Sequenti	al control input signal	Functions: Origin return deceleration switch signal (/DEC), external latch signal (/EXT 1 to 2), forward rotation prohibition (P-OT), reverse rotation prohibition (N-OT), forward rotation torque limit (/P-CL), reverse rotation torque limit (N-CL). Changes in the positive/regative logic of the above signal can be performed.								
			5 channels								
	Sequenti	al control output signal	Functions: Servo alarm (ALM), positioning completion (/COIN), speed coincidence detection (/V-CMF brake (/BK), servo motor rotation detection (/TGON), servo ready (/S-RDY), torque limit detection encoder zero output (/PGC). Changes in the positive/negative logic of the above signal can be perform								
	Instruc	tion	CHARGE indica	itor							
Re	generatior	n handling	Built-in regenera	ative resistor or e	xternal regenerati	ve resistor (optio	inal)				
0	ver travel	handling	Dynamic brake (I	DB) stops, deceler	ation stops or free i	running stops duri	ng P-OT and N-O	T input operation			
P	rotection f	unctions	Over current, ov	ver voltage, unde	r voltage, overload	l, regeneration a	bnormality, etc.				
	Accessib	oility	Gain adjustment, alarm recording, jog operation, etc.								
		Display	7-segment 5-dig	jit red nixie tube							
Panel opera		Key	5 jog keys								
	0	Communication protocol	MECHATROLIN	IK-II							
	1	ransfer Rate	10 Mbps				and the second				
Communicat	ion 1	ransmission cycle	250 microsecon	ds, 0.5 to 4.0 mil	liseconds (multiple	es of 0.5 millisec	onds)				
	L	ink transfer words	Switch at 17 byt	es/station, 32 by	tes/station	/					
	5	Station address setting			f linked substation	ns: 30)					
		nstruction specification			nd torque control v						
Command m	ode (Command input		IK commands (su stment, and othe	uch as sequential r instructions)	control, moveme	ent, data setting/r	eference,			

Universal bus K1/K2 series servo drive

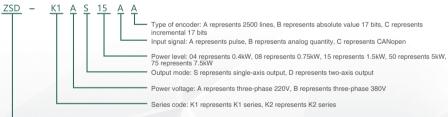




	Series			K1 K2										
AC 3	220V power		0.4	0.75	1.5	2.2	3	5	00.4	0.75	- 1.5	2.2		
	Output curre		2.8	5.5	1.5	12	5 16	25	2.8	5.5	1.5	12		
	380V power		2.0 5	7.5		12	10	23	2.0	5.5		12		
	Output curre	()	12	20			-	-						
	oupuround													
	Encoder t	уре		2500 line incremental encoder 17 bit absolute value encoder										
Reç	generation r				connection									
	Control m	ode	-			al current c								
	Spee	ed control range	1:10000 (The lower	limit of the	speed conti	ol range is	stable ope	ration with	out creep in	n case of ra	ted load)		
	Fluctuation ratio of speed	Load fluctuation	0 to 100%	6 load: ±0	.01% max.	(at rated s	peed)							
Properties		Voltage fluctuation	Rated vol	tage: ±10	%:0% (at r	ated speed	i)							
roportioo	speed	Temperature fluctuation	25±25°C:	±0.1% m	ax. (at rate	ed speed)								
	Torque contr	ol accuracy (repeatability)	1%											
	Soft I	poot-time set	0 ~ 10 se	conds (ad	celeration	and decele	ration car	n be set se	parately)					
	BS-485	Communication protocol	Modbus											
	Communic	1; N communication	Up to N =	Up to N = 127 stations										
Communication	ation	Axis address setting	Set by parameter											
Communication	CAN	Communication protocol	CAN Ope	n (DS30	1 + DS402)								
	communi	1; N communication	Up to N =	127 stati	ons									
	cation	Axis address setting	Set by parameter											
	Frequenc output of	y-dividing pulse encoder	A-phase, B-phase, and C-phase: linear drive output; number of divided pulses: can be set arbitrarily											
		Fixed input	Send											
	Sequential		Number of	of channe	s: K1 serie	s 4 channe	els, K2 sei	ries 8 char	nels					
Input/output signal	control input signal	Assignable input signal	Function: Servo enable (/S-ON), proportional control (/P-CON), forward rotation prohibition (P-OT), reverse rotation prohibition (N-OT), alarm reset (/ALM-RST), forward rotation torque limit (/P-CL), reverse rotation torque limit (/N-CL), position deviation zero clearing (/CLR), internally set speed switch. Changes in the positive/negative logic of the above signal can be performed.											
			Number of	of channe	ls: K1 serie	es 3 chann	els, K2 se	ries 6 char	nnels					
	Sequential control output signal	Assignable output signal	Function: Servo alarm (ALM), positioning completion (/COIN), speed coincidence detection (/V-CMP), br/ (/BK), servo motor rotation detection (/TGON), servo ready (/S- RDY), Torque Limit Detection (/CLT), Encoder Zero Output (PGC), which can be used to change the positive/negative logic of the above signal									LT),		
	Instructi	on	CHARGE indicator											
Re	egeneration	handling	Built-in regenerative resistor or external regenerative resistor (optional)											
C	over travel h	andling	Dynamic brake (DB) stops, deceleration stops or free running stops during P-OT and N-OT input operation											
F	Protection fu	nctions	Over current, over voltage, under voltage, overload, regeneration abnormality, etc.											
	Accessibility		Gain adjustment, alarm recording, jog operation, etc.											
		Display	7-segmer	nt 5-digit r	ed nixie tul	be			1					
Panel oper	ration	Key	5 jog keys		/									
	Input	Command voltage	Maximur	n input vo		(positive vo sponds to r								
Torque control	signal	Input resistance	About 20	KΩ										
rorque control														
		Electrical time constant	47 µs											

	Input	Command voltage	Maximum input voltage: ±10V (positive voltage corresponds to positive rotation) Factory setting: 150(r/min)/V (input gain can be set)
	signal	Input resistance	About 20KΩ
Speed control		Electrical time constant	47 µs
opeed control		Rotation direction selection	Switch direction via /P-CON
	speed control	Speed Select	Speed 1 to 3 is selected by forward rotation torque limit (/P-CL) and reverse rotation torque limit (/N-CL). When both signals are OFF, the servo motor stops or switches to another control method.
	Feed forward compensation		0 to 100%
	Positioni	ng completion width	0 to 5000 command units
		Command pulse form	Choose one of the following categories: Symbol + pulse sequence, CW + CCW pulse sequence 90° phase difference two-phase pulse (phase A and phase B)
Position control		Command pulse pattern	Support linear drive, open collector
Position control		Maximum input pulse frequency	Linear drive Symbol + pulse sequence, CW + CCW pulse sequence: 500K pps 90° phase difference two-phase pulse (phase A and phase B): Open collector Symbol + pulse sequence, CW + CCW pulse sequence: 200 Kpps 90° phase difference two-phase pulse (phase A and phase B): 200 Kpps
	Clear s	ignal	Clear position deviation, open collector

K1/K2 series namin g method



Enterprise code :ZSD represents the Zhishan servo drive

Multi-axis KAD/K1AD series servo drive



KAD/K1AD series naming method

<u>K1 A D 15 A</u> Type of encoder: A represents 2500 lines, B represents absolute value 17 bits, C represents incremental 17 bits

- - Information international and an analysis of the second structure of the

Output mode: S represents single-axis output, D represents two-axis output

Power voltage: A represents three-phase 220V, B represents three-phase 380V

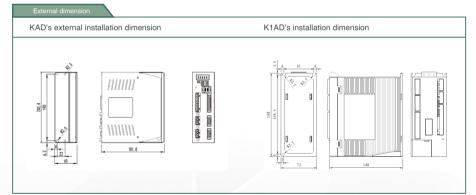
Series code: K1 represents K1 series, K2 represents K2 series

Enterprise code :ZSD represents the Zhishan servo drive

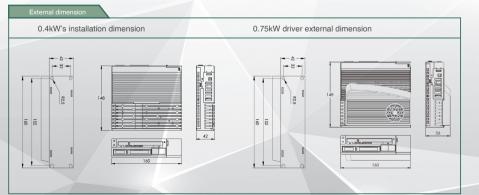
	Model		KAD15A						
	Output po	wer	1.5kW	2kW	0.75kW				
	Input pov	/er	Three-phase AC220V -15 ~ +10% 50 ~ 60Hz						
	Encoder t	уре	2500 line incremental encoder						
Continuous output			6A	6A 10A 5.5A					
Reg	generation re	esistance	Built-in or external connection						
Control mode			IGBT PWM control sinusoidal current drive mode						
	Spee	ed control range	1:10000 (The lower limit of the speed control range is stable operation without creep in case of rated load)						
	Fluctuation	Load fluctuation	0 to 100% load: ±0.01% max. (at	rated speed)					
	ratio of	Voltage fluctuation	Rated voltage: ±10%:0% (at rated	l speed)					
Properties	speed	Temperature fluctuation	25±25°C: ±0.1% max. (at rated speed)						
	Torque contro	ol accuracy (repeatability)	1%						
	Soft be	pot-time setting	0 ~ 10 seconds (acceleration and	deceleration can be set separatel	y)				
	RS-485	Communication protocol	Modbus	· · · ·					
	Communic	1; N communication	Up to N = 127 stations						
	ation	Axis address setting	Set by parameter						
Communication	CAN	Communication protocol	CANOpen (DS301 + DS402)						
	communi	1; N communication	N=127 max. available						
	cation	Axis address setting	Set by parameter						
	Frequent output of	cy-dividing pulse encoder	A-phase, B-phase, and C-phase: linear drive output; number of divided pulses: can be set arbitrarily						
		Fixed input	Send						
	Sequential		Number of channels: KAD – 8 channels, K1AD - 6 channels						
Input/output signal	control input signal	Assignable input signal	Function: Servo enable (/S-ON), proportional control (/P-CON), forward rotation prohibition (P-OT), reverse rotation prohibition (N-OT), alarm reset (/ALM-RST), forward rotation torque limit (/P-CL), internally set speed switch, which can which can be used to change the positive/negative logic of the above signals.						
			Number of channels: KAD – 6 channels, K1AD - 4 channels						
	Sequential control output signal	Assignable output signal	Functions: Servo alarm (ALM), positioning completion (/COIN), speed coincidence detection (/V-CMP), brake (/BK), servo motor rotation detection (/TGON), servo ready (/S- RDV), torque limit detection (/CLT), encoder zero output (PGC), which can which can be used to change the positive/negative logic of the above signals.						
	Instructio	on	CHARGE indicator						
Re	egeneration I	nandling	Built-in regenerative resistor or external regenerative resistor (optional)						
C	Over travel ha	andling	Dynamic brake (DB) stops, decelera	ation stops or free running stops duri	ing P-OT and N-OT input operation				
P	Protection fur	nctions	Over current, over voltage, under voltage, overload, regeneration abnormality, etc.						
	Accessibili	ty	Gain adjustment, alarm recording, jog operation, etc.						
Panel op		Display	7-segment 5-digit red nixie tube	us man					
Panel op	eration	Key	5 jog keys						
	Input	Command voltage		oositive voltage corresponds to po onds to rated torque (input gain ca					
Torque control	signal	Input resistance	About 20KΩ						
		Electrical time constant	47µS						
	Soft boot-t	ime setting	0 to 10 seconds (acceleration and deceleration can be set separately)						

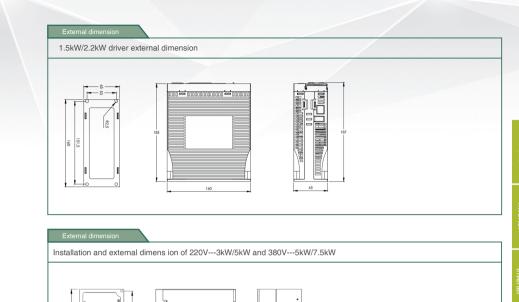
	Input	Command voltage	Maximum input voltage: ±10V (positive voltage corresponds to positive rotation) Factory setting: 150(r/min)/V (input gain can be set) About 20KΩ						
	signal	Input resistance							
Speed control	bl	Electrical time constant	47 µs						
	Internal speed	Rotation direction selection	Switch direction via /P-CON						
	control	Speed Select	Speed 1 to 3 is selected by forward rotation torque limit (/P-CL) and reverse rotation torque limit (/N-CL). When both signals are OFF, the servo motor stops or switches to another control method.						
	Feed fe	orward compensation	0 to 100%						
	Positio	ning completion width	0 to 5000 command units						
		Command pulse form	Choose one of the following categories: Symbol + pulse sequence, CW + CCW pulse sequence 90° phase difference two-phase pulse (phase A and phase B)						
		Command pulse pattern	Support linear drive, open collector						
Position control		Maximum input pulse frequency	Linear drive Symbol + pulse sequence, CW + CCW pulse sequence: 500K pps 90° phase difference two-phase pulse (phase A and phase B): Open collector Symbol + pulse sequence, CW + CCW pulse sequence: 200 Kpps 90° phase difference two-phase pulse (phase A and phase B): 200 Kpps						
	Clear si	nal	Clear position deviation, open collector						

KAD/K1AD series dimension chart



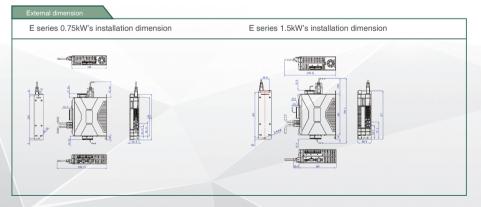
K1/K2/iK2/iK3/K5 series dimension chart





E series dimension chart

180



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High Voltage

Servo Drive And Motor

Universal S series servo motor

Specification parameter									
Motor model	40SD-A05130	40SD-A01130	60SS-A20130	60SS-A40130	80SS-A75130	30SH-A95115	130SD-A10210		
Rated power (kw)	0.05	0.1	0.2	0.4	0.75	0.95	1.0		
Pole-pairs	4	4	5	5	5	5	5		
Rated torque (N.m)	0.16	0.32	0.64	1.27	2.39	6.05	9.55		
Maximum torque (N.m)	0.48	0.95	1.92	3.8	7.2	14	21.5		
Rated input speed (rpm)	3000	3000	3000	3000	3000	1500	1000		
Maximum speed (rpm)	6000	6000	5000	5000	5000	2500	1500		
Rated current (A)	0.6	1.1	1.9	2.8	4.0	6	6.2		
Maximum current (A)	1.8	3.3	5.7	8.4	11.7	14.2	14.5		
Torque constant (N.m/A)	0.26	0.29	0.336	0.453	0.612	1.01	1.54		
Counter EMF (V/Krpm)	18.83	19.6	22.9	29.3	39.8	68.1	101		
Rotor inertia (Kg.m2)	0.02×10-4	0.04×10-4	0.16×10-4	0.28×10-4	1.0×10-4	13.9×10-4	6.7×10-4		
notor menta (rtg.mz)	0.02×10-4	0.04×10-4	0.18×10-4	0.3×10-4	1.1×10-4	15.9×10-4	8.6×10-4		
Line resistance (Ω)	32.28	13.97	4.5	3.3	1.4	1.444	1.92		
Line inductance (mH)	33.13	23.84	12.5	9.61	7.25	14.56	23.0		

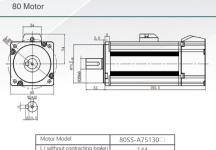
Specification parameter

Motor model	130SD-A10220 🗆	130SH-A13215 🗆	130SD-A15210	130SD-A15220	130SD-A20220 🗆	130SD-A30220
Rated power (KW)	1.0	1.35	1.5	1.5	2.0	3.0
Pole-pairs	5	5	5	5	5	5
Rated torque (N.m)	4.77	8.6	14.3	7.16	9.55	14.3
Maximum torque (N.m)	14.3	21.5	42.9	21.5	28.65	42.9
Rated input speed (rpm)	2000	1500	1000	2000	2000	2000
Maximum speed (rpm)	3000	2500	1500	3000	3000	3000
Rated current (A)	6	7.6	7.2	8.2	10.5	13.8
Maximum current (A)	18	22.8	21.6	24.6	31.5	41.4
Torque constant (N.m/A)	0.795	1.13	1.99	0.873	0.905	1.04
Counter EMF (V/Krpm)	51.2	75.4	127.5	55	61	65
Rotor inertia (Kg.m2)	4.6×10-4	20×10-4	15.1×10-4	6.7×10⁴	8.7×10-4	15.1×10-4
notor menta (rtg.mz)	6.5×10-4	22×10-4	17.1×10-4	8.6×10⁴	10.7×10-4	17.1×10-4
Line resistance (Ω)	0.955	1	1.31	0.70	0.54	0.3
Line inductance (mH)	7.96	11.4	14	6.1	5.91	3.17



External dimension

60 Motor

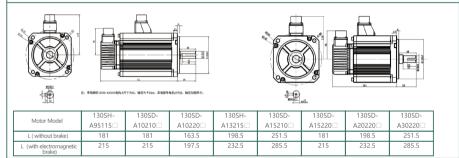




High Voltage Inverter



130 Motor



130SH-A95115



Schedule: 220V series servo drive adapter motor table

	Torque (N.m)	Speed (r/min)	Current (A)	Power (kW)	Servo rated power and rated output current					
Motor model					0.4kW	0.75kW	1.5kW	2.2kW	3kW	5kW
		(()	2.8A	5.5A	10A	12A	16A	25A
40ST M00130	0.16	3000	0.4	0.05	•	0	0	0	0	0
40ST – M00330	0.32	3000	0.6	0.1	•	0	0	0	0	0
60ST – M00630	0.637	3000	1.2	0.2	•	0	0	0	0	0
60ST – M01330	1.27	3000	2.8	0.4		0	0	0	0	0
60ST – M01930	1.91	3000	3.5	0.6		•	0	0	0	0
80ST – M01330	1.27	3000	2	0.4	•	0	0	0	0	0
80ST - M02430	2.39	3000	3	0.75		•	0	0	0	0
80ST – M03520	3.5	2000	3	0.73		•	0	0	0	0
80ST – M04025	4	2500	4.4	1.0		0	•	0	0	0
90ST – M02430	2.4	3000	3	0.75		•	0	0	0	0
90ST – M03520	3.5	2000	3	0.73		•	0	0	0	0
90ST – M04025	4	2500	4	1.0		0	٠	0	0	0
110ST – M02030	2	3000	2.5	0.6		•	0	0	0	0
110ST - M04020	4	2000	3.5	0.8		0	•	0	0	0
110ST - M04030	4	3000	5.0	1.2			٠	0	0	0
110ST - M06020	6	2000	4.5	1.2			•	0	0	0
110ST – M05030	5	3000	6.0	1.5			•	0	0	0
110ST - M06030	6	3000	6.0	1.8				•	0	0
130ST - M04025	4	2500	4.0	1.0		0	٠	0	0	0
130ST - M05025	5	2500	5.0	1.3			٠	0	0	0
130ST M06025	6	2500	6.0	1.5			٠	0	0	0
130ST – M07725	7.7	2500	7.5	2.0				•	0	0
130ST – M10010	10	1000	4.5	1.0		0	•	0	0	0
130ST – M10015	10	1500	6.0	1.5			•	0	0	0
130ST – M10025	10	2500	10	2.6		1		•	0	0
130ST – M15015	15	1500	9.5	2.3				•	0	0
130ST – M15025	15	2500	13.5	3.8					0	•
150ST – M15025	15	2500	17	3.8						•
150ST – M15020	15	2000	14	3.0					•	0
150ST – M18020	18	2000	17	3.6						•
180ST – M17215	17.2	1500	10.5	2.7				1	•	0
180ST – M19015	19	1500	12	3.0				1	•	0
180ST – M21520	21.5	2000	16	4.5				1		•
180ST – M27010	27	1000	12	2.9				1	•	0
180ST – M27015	27	1500	16	4.3				1		•
180ST – M35010	35	1000	16	3.7			1	1	•	•

Note:represents the recommended option, represents the option can be selected, the blank part represents that the option cannot be selected

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Special tailor

Standard M Series Motor Naming Method:

Explanations:

X-axis servo motor

Low voltage 48V serve

Rated st

High voltage 380V servo motor

Explanations: 1000r/min 1500¢min

2000r/min

Explanations: N production line Z production line H production line

motor

1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.		
>	(1: Flange size)	×
Code	Explanations:	Code
40	40mm side length square flange plate	ST
60	60mm side length square flange plate	HST
80	80mm side length square flange plate	LST
90	90mm side length square flange plate	
100	100mm side length square flange plate	
110	110 mm side length square flange plate	Code
130	130mm side length square flange plate	10
150	150mm side length square flange plate	15
180	180mm side length square flange plate	20
		-
		X7
		Code
		Null
		z

Explanations:
looromostal standard time
incremental standard type
Absolute value encoder
Magnetic Encoder
Resolving Encoder 05
Incremental 17-bit encoder 07
mal change specification definition
Explanations:
Standard Definition
Electromagnetic contracting brake
No. seam allowance

Schedule: 380V series servo drive adapter motor table

					rat	ed power and rat	ed output currer	nt	
Moto r model	Torque (N.m)	Speed (r/min)	Current (A)	Power (kW)	2kW	3.5kW	5kW	7.5kW	
	()	()	(*)	()	5A	8A	12A	20A	
110HST – M02030	2	3000	2.0	0.6	•	0	0	0	
110HST – M04020	4	2000	2.0	0.8	•	0	0	0	
110HST – M04030	4	3000	3.0	1.2	•	0	0	0	
110HST – M05030	5	3000	4.5	1.5	•	0	0	0	Ŧ
110HST - M06020	6	2000	3.0	1.2	•	0	0	0	High Voltage Inverter
110HST – M06030	6	3000	4.5	1.8	•	0	0	0	gh Volta Inverter
130HST – M04025	4	2500	2.6	1	•	0	0	0	age
130HST – M05025	5	2500	3	1.3	•	0	0	0	
130HST - M06025	6	2500	3.7	1.5	•	0	0	0	
130HST - M07725	7.7	2500	4.7	2	•	0	0	0	Low Voltage Inverter
130HST – M10010	10	1000	2.5	1	•	0	0	0	w Voltaç Inverter
130HST – M10015	10	1500	3.5	1.5	•	0	0	0	tag ler
130HST – M10020	10	2000	5.1	2	•	0	0	0	^O
130HST – M10025	10	2500	5.9	2.6	1	•	0	0	1
130HST – M15015	15	1500	5	2.3		•	0	0	
130HST – M15025	15	2500	7.4	3.8			•	0	Dedicated Purpose Inverter
150HST – M15020	15	2000	6.8	3.0		•	0	0	rter
150HST – M15025	15	2500	9.5	3.8	1		•	0	<u> </u>
150HST – M18020	18	2000	8.5	3.6			•	0	
150HST - M23020	23	2000	12	4.7			•	0	γv
150HST – M27015	27	1500	11	4.2	1		•	0	Servo Drive And Motor
150HST – M27020	27	2000	14.5	5.5	1			•	Š₽
150HST – M27025	27	2500	17	6.8				•	tor ive
180HST – M17215	17.2	1500	6.5	2.7		•	0	0	1
180HST – M19015	19	1500	7.5	3.0	1	•	0	0	1
180HST – M21520	21.5	2000	9.5	4.5			•	0	1
180HST – M27010	27	1000	7.5	2.9		•	0	0	1
180HST – M27015	27	1500	10	4.3			•	0	1
180HST – M35010	35	1000	10	3.7			•	0	1
180HST – M35015	35	1500	12	5.5			٠	0]

Note: represents the recommended option, represents the option can be selected, The blank part represents that the option cannot be selected

Other series products



Other servo drive products

G2 series: 0.4kW, 0.75kW, 1.5kW, 2.2kW, 3kW Cost-effective full-function servo driver

G_B series 0.4kW, 0.75kW, 1.0kW, 1.5kW, 2.0kW, 3kW Fanless full-function servo driver

K/iK series (220V and 380V) 2kW, 2.8kW, 3.5kW, 5kW High Performance Servo Driver, Pulse type, Analog type, CANopen,Mechatrolink II

iKF series two axes 50W \sim 1kW, two axes 0.4kW \sim 1.5k EtherCAT bus four-axis servo driver

A series power section: $0.05 \text{ kW} \sim 2.8 \text{kW}$ Frame No.: 40, 60, 80, 110, 130Design features: a new electromagnetic design, lower temperature rise, small motor inertia, high controllable precision.

51 series power section: 0.2 kW ~ 0.75kW Frame No.: 60, 80 Design features: low inertia small capacity motor, high power density, with efficiency meeting national first-class energy efficiency standard.

E series power section: 0.1 kW ~ 5kW Frame No.: 40、60、80、130 Design features: New process, compact structure, short body, small volume, improving system responsiveness.

B series power section: 0.85 kW ~ 1.3kW Frame No.: 130 Design features: 10-pole, 12-slot design reduces motor cogging torque, low cogging torque with better performance.

